

Variational Analysis of a Quasi-Static Thermo-Electro-Elastic Contact Problem with Normal Compliance

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Abstract

In this work we present the existence of weak solution for a quasi-static thermo-piezoelectric problem which describes frictional contact problem between a deformable body and a thermally-electrically conductive foundation. We model the material's behavior with a thermo-electro-elastic constitutive law and the contact with a normal compliance conditions and a version of Coulomb's law of dry friction including the electrical and thermal conductivity conditions in which the frictional heat generated in the process is taken into account. The model is in the form of a coupled system for displacements, electric potential, and temperature. The existence of solutions is obtained from an elliptic quasi-variational inequalities, time discretization and Banach fixed point argument.

Keywords: Thermopiezoelectric material, quasi-static process, Coulomb's friction law, frictional heat generation, Variational inequality.

1. INTRODUCTION

In this paper we consider the quasi-static frictional contact between a thermo-piezoelectric body and a conductive foundation. The body is assumed to satisfy the piezoelectric constitutive equations with added thermal effects. Our main interest lies

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in coupling between thermal effects and piezoelectrical properties and in electrical and thermal boundary conditions describing the contact. More precisely, it is supposed that the contact is modeled with normal compliance, a version of Coulomb's law of dry friction, a regularized electrical conductivity condition and a condition of thermal contact in which the frictional heat generated in the process is taken into account.

Recently piezoelectric frictional contact problems with or without conductivity of foundation have been investigated in a large number of papers, see e.g. [2, 10, 11, 12, 13] and the references therein. Contact problems involving thermo-piezoelectric materials with conductive foundation in the static case have been studied in [3, 4, 5]. This paper extends the results provided in [5] to the quasi-static case. We deal with a mathematical model for the quasi-static process of frictional contact between a thermo-piezoelectric body and a conductive foundation, under small deformations hypothesis, wherein the material's behavior is modeled by a linear thermo-electro-elastic constitutive law and the contact is described with the normal compliance, the quasi-static of nonlocal Coulomb friction law of dry friction, a regularized electrical conductivity condition and the condition of thermal contact.

The paper is structured as follows. In Section 3 we introduce the notation, we list the assumptions on problem's data, we derive the variational formulation of the problem and we present our main result stated in Theorem 3.1. The proof of this theorem is provided in sections 4-6. It is carried out in several steps and is based on arguments of compactness, time discretization and Banach fixed point theorem.

2. MATHEMATICAL MODEL AND ITS MECHANICAL FORMULATION

We consider a piezoelectric body occupies a bounded domain Ω in \mathbb{R}^d , $d = 2, 3$, with a Lipschitz continuous boundary Γ . We suppose that Γ is divided in three disjoint parts Γ_D , Γ_N and Γ_C on the one hand and that $\Gamma_D \cup \Gamma_N$ is partitioned into two open parts Γ_a and Γ_b on the other hand, such that Γ_D and Γ_a being on nonzero measure. The body is supposed to be stress free at a free temperature and the temperature variations, accompanying the deformations, produce changes in the material parameters which are considered as depending on temperature. Let $[0, T]$ be the time interval of interest, the body is clamped on $\Gamma_D \times (0, T)$, the displacement field vanishes there. In $\Omega \times (0, T)$, it is subjected to a volume force f_0 , a volume electric charge ϕ_0 and heat source q_0 . Surface tractions f_N are applied on $\Gamma_N \times (0, T)$, surface electric charges ϕ_b act on $\Gamma_b \times (0, T)$ and the body is subjected to heat source q_0 on $\Omega \times (0, T)$. Moreover, we suppose that is at null electric potential on $\Gamma_a \times (0, T)$ and null variation of temperature on $\Gamma_D \cup \Gamma_N \times (0, T)$. We assume that body is in frictional contact with an obstacle over the part Γ_C .

Here and below, to simplify the notation, we do not indicate the dependence of various functions on the spatial variable $x \in \bar{\Omega}$, the indices i, j, k, l take values between 1 and d , the summation convention over repeated indices is used and the index that follows a comma indicates a partial derivative with respect to the corresponding component of the spatial variable $u_{i,j} = \frac{\partial u_i}{\partial x_j}$. We also denote by $\text{Div } \sigma = (\sigma_{ij,j})$ and $\text{div } D = (D_{j,j})$ the divergence operator for tensor and vector valued functions, respectively.

Let \mathbb{S}^d be the space of second order symmetric tensors on \mathbb{R}^d . The canonical inner products and norms on \mathbb{R}^d and \mathbb{S}^d are given by

$$\begin{aligned} u \cdot v &= u_i \cdot v_i, & \|v\| &= (v \cdot v)^{\frac{1}{2}}, & \forall u, v \in \mathbb{R}^d, \\ \sigma \cdot \tau &= \sigma_{ij} \cdot \tau_{ij}, & \|\tau\| &= (\tau \cdot \tau)^{\frac{1}{2}}, & \forall \sigma, \tau = (\tau_{ij}) \in \mathbb{S}^d. \end{aligned}$$

Moreover, ν represents the unit exterior normal on Γ . Then the normal and the tangential components of the displacement vector v and the stress σ on the boundary are

$$v_\nu = v \cdot \nu, \quad v_\tau = v - v_\nu \nu \quad \text{and} \quad \sigma_\nu = \sigma \nu \cdot \nu, \quad \sigma_\tau = \sigma \nu - \sigma_\nu \nu.$$

The governing equations of thermo-electro-elasticity consist of the equilibrium equation, constitutive relations, strain-mechanical displacement, electric field-potential and thermal field-temperature change relations.

The elastic strain-displacement, electric field-potential and the thermal field-temperature change relations are given by

$$\begin{aligned} \varepsilon(u) &= \left(\frac{1}{2}(u_{i,j} + u_{j,i})\right) \quad \text{in } \Omega \times (0, T), \\ E(\varphi) &= -(\varphi_{,i}) \quad \text{in } \Omega \times (0, T), \\ q &= -\mathcal{K} \nabla \theta \quad \text{in } \Omega \times (0, T), \end{aligned}$$

where $\varepsilon(u) = (\varepsilon_{ij}(u))$, $E(\varphi) = (E_i(\varphi))$, $\mathcal{K} = (k_{ij})$, $u = (u_i)$, φ , θ are respectively, the linear strain tensor, quasi-static electric field vector, conductivity tensor, displacement vector field, electric potential and temperature change.

We suppose that the process is quasi-static. The equations of stress equilibrium, the equation of quasi-stationary electric field and the heat conduction equation are, respectively, given by

$$\text{Div } \sigma + f_0 = 0 \quad \text{in } \Omega \times (0, T), \quad (2.1)$$

$$\text{div } D = \phi_0 \quad \text{in } \Omega \times (0, T), \quad (2.2)$$

$$\dot{\theta} + \text{div } q = -\mathcal{M} \dot{\varepsilon}(u) - \mathcal{P} \dot{E}(\varphi) + q_0 \quad \text{in } \Omega \times (0, T), \quad (2.3)$$

where $\sigma = (\sigma_{ij})$, $D = (D_i)$ and $q = (q_i)$ represent the stress tensor, the electric displacement field and the heat flux vector, respectively.

The constitutive equations of a piezoelectric material including the effect thermal expansion can be written as

$$\sigma = \mathfrak{F} \varepsilon(u) - \mathcal{E}^* E(\varphi) - \mathcal{M} \theta \quad \text{in } \Omega \times (0, T), \quad (2.4)$$

$$D = \mathcal{E} \varepsilon(u) + \beta E(\varphi) + \mathcal{P} \theta \quad \text{in } \Omega \times (0, T), \quad (2.5)$$

where $\mathfrak{F} = (\mathfrak{F}_{ijkl})$, $\mathcal{E} = (e_{ijk})$, $\mathcal{M} = (m_{ij})$, $\beta = (\beta_{ij})$ and $\mathcal{P} = (p_i)$ are respectively, the linear elasticity operator, piezoelectric tensor, thermal expansion tensor, electric permittivity tensor, pyroelectric tensor and \mathcal{E}^* is the transpose of \mathcal{E} . We note that $\mathcal{E}^* = (e_{ijk})$.

Finally, to complete the mechanical model according to the description of the physical setting, we have

$$u = 0 \quad \text{on } \Gamma_D \times (0, T), \quad (2.6)$$

$$\sigma \nu = f_N \quad \text{on } \Gamma_N \times (0, T), \quad (2.7)$$

$$\varphi = 0 \quad \text{on } \Gamma_a \times (0, T), \quad (2.8)$$

$$D \cdot \nu = \phi_b \quad \text{on } \Gamma_b \times (0, T), \quad (2.9)$$

$$\theta = 0 \quad \text{on } \Gamma_D \cup \Gamma_N \times (0, T). \quad (2.10)$$

On the contact surface Γ_C , we consider

$$\sigma_\nu(u) = -p_\nu(u_\nu - g) \quad \text{on } \Gamma_C \times (0, T), \quad (2.11)$$

$$\left. \begin{aligned} \|\sigma_\tau\| &\leq p_\tau(u_\nu - g) \\ \|\sigma_\tau\| < p_\tau(u_\nu - g) &\implies \dot{u}_\tau = 0 \\ \|\sigma_\tau\| = p_\tau(u_\nu - g) &\implies (\exists \lambda \in \mathbb{R}^+), \dot{u}_\tau = -\lambda \sigma_\tau \end{aligned} \right\} \quad \text{on } \Gamma_C \times (0, T), \quad (2.12)$$

$$D \cdot \nu = \psi(u_\nu - g) \phi_L(\varphi - \varphi_F) \quad \text{on } \Gamma_C \times (0, T), \quad (2.13)$$

$$q \cdot \nu = -\mu p_\nu(u_\nu - g) S_c(\cdot, \|\dot{u}_\tau\|) + k_c(u_\nu - g) \phi_L(\theta - \theta_F) \quad \text{on } \Gamma_C \times (0, T), \quad (2.14)$$

$$u(\cdot, 0) = u_0, \theta(\cdot, 0) = \theta_0, \varphi(\cdot, 0) = \varphi_0 \quad \text{in } \Omega. \quad (2.15)$$

Then, the condition (2.11) represent the normal compliance contact condition where in which p_ν is prescribed function. Relations (2.12) are a version of coulomb's law of dry friction, p_τ is prescribed nonnegative function, the so-called friction bound. The condition (2.13) is the electric boundary condition. Relation (2.14) (as in [1]) is the

boundary condition for the temperature on Γ_C , we assume that there is heat exchange between the surface and the foundation, which is at temperature θ_F , Moreover, the flux of heat generated by the frictional contact forces is proportional to the tangential velocity \dot{u}_τ , The inclusion of such a term is required if the effects of the frictional heat generation are to be taken into account.

Finally, the initial conditions u_0, φ_0 and θ_0 in (2.15) are given and the functions ψ and ϕ_L used in (2.13) and (2.14) represent, respectively, the truncation function and a given positive function

$$\phi_L(s) = \begin{cases} -L & \text{if } s < -L \\ s & \text{if } -L \leq s \leq L \\ L & \text{if } s > L \end{cases}, \quad \psi(r) = \begin{cases} 0 & \text{if } r < 0 \\ k \delta r & \text{if } 0 \leq r \leq 1/\delta, \\ k & \text{if } r > 1/\delta \end{cases}$$

where $L > 0$ is a sufficiently large constant, $\delta > 0$ is a small given parameter and $k \geq 0$ is the electrical conductivity coefficient.

With these assumptions, the mechanical problem of frictional contact of the piezoelectric body under thermal environment, may be formulated as follows

Problem (P). Find a displacement field $u : \Omega \times [0, T] \rightarrow \mathbb{R}^d$, an electric potential $\varphi : \Omega \times [0, T] \rightarrow \mathbb{R}$ and temperature field $\theta : \Omega \times [0, T] \rightarrow \mathbb{R}$ such that (2.1)-(2.15) hold.

3. VARIATIONAL PROBLEM AND MAIN RESULT

First, Let us consider the following real Hilbert spaces

$$H = \{u = (u_i), u_i \in L^2(\Omega)\} = [L^2(\Omega)]^d, \quad \mathcal{H} = \{\sigma = (\sigma_{ij}), \sigma_{ij} = \sigma_{ji} \in L^2(\Omega)\},$$

$$H_1 = \{u \in H, \varepsilon(u) \in \mathcal{H}\} = [H^1(\Omega)]^d, \quad \mathcal{H}_1 = \{\sigma \in \mathcal{H}, \text{Div } \sigma \in H\},$$

endowed with their natural norms and inner products as follows

$$(u, v)_H = \int_{\Omega} u_i v_i dx, \quad (u, v)_{H_1} = (u, v)_H + (\varepsilon(u), \varepsilon(v))_{\mathcal{H}},$$

$$(\sigma, \tau)_{\mathcal{H}} = \int_{\Omega} \sigma_{ij} \tau_{ij} dx, \quad (\sigma, \tau)_{\mathcal{H}_1} = (\sigma, \tau)_{\mathcal{H}} + (\text{Div } \sigma, \text{Div } \tau)_H.$$

The notation $\langle \cdot, \cdot \rangle_{X', X}$ always denotes the duality pairing between a space X and its dual X' . We consider the trace map $\gamma : H_1 \rightarrow H_\Gamma = H^{1/2}(\Gamma)^d$, then for every $\sigma \in \mathcal{H}_1$, there exists $\sigma\nu \in H'_\Gamma = H^{-1/2}(\Gamma)^d$ satisfying the following Green formula

$$\langle \sigma\nu, \gamma v \rangle_{H'_\Gamma, H_\Gamma} = (\sigma, \varepsilon(v))_{\mathcal{H}} + (\text{Div } \sigma, v)_H, \quad \forall v \in H_1. \tag{3.1}$$

Moreover, if σ is continuously differentiable on $\bar{\Omega}$, then

$$\langle \sigma \nu, \gamma v \rangle_{H_\Gamma^1, H_\Gamma} = \int_\Gamma \sigma \nu \cdot \gamma v \, da, \quad \forall v \in H_1, \quad (3.2)$$

where da is the surface element. Let us also introduce the following subspace $H_{\Gamma_C}^{1/2}$ of $L^2(\Gamma_C)$ given by

$$H_{\Gamma_C}^{1/2} = \{ v_\nu \in L^2(\Gamma_C), \exists v \in H_1, v_\nu = \gamma v \cdot \nu \},$$

and called the space of normal traces on Γ_C . The spaces $H_{\Gamma_C}^{1/2}$ and its dual $H_{\Gamma_C}^{-1/2}$ endowed with the norms

$$\begin{aligned} \|v_\nu\|_{H_{\Gamma_C}^{1/2}} &= \inf_{v \in H_1} \{ \|v\|_{H_1}, v_\nu = \gamma v \cdot \nu \}, \quad \forall v_\nu \in H_{\Gamma_C}^{1/2}, \\ \|\sigma_\nu\|_{H_{\Gamma_C}^{-1/2}} &= \sup_{v_\nu \in H_{\Gamma_C}^{1/2}} \left\{ \frac{\langle \sigma_\nu, v_\nu \rangle_{\Gamma_C}}{\|v_\nu\|_{H_{\Gamma_C}^{1/2}}} \right\}, \quad \forall \sigma_\nu \in H_{\Gamma_C}^{-1/2}, \end{aligned}$$

where $\langle \cdot, \cdot \rangle_{\Gamma_C}$ denote the duality pairing between $H_{\Gamma_C}^{-\frac{1}{2}}$ and $H_{\Gamma_C}^{\frac{1}{2}}$.

In the sequel, for every $v \in H_1$, we denote the trace map γv of v on Γ , again by v to simplify notations. In order to prove existence results concerning our problem, we first give equivalent variational formulation and to this aim, we need to introduce the following closed subspace of H_1 defined by

$$V = \{ v \in H_1, v = 0 \text{ on } \Gamma_D \}.$$

Since $meas(\Gamma_D) > 0$, the following Korn's inequality holds

$$\|\varepsilon(v)\|_{\mathcal{H}} \geq c_k \|v\|_{H_1}, \quad \forall v \in V, \quad (3.3)$$

where $c_k > 0$ is a constant which depends only on Ω and Γ_D . Therefore the space V endowed with the inner product $(u, v)_V = (\varepsilon(u), \varepsilon(v))_{\mathcal{H}}$ is a real Hilbert space and its associated norm $\|v\|_V = \|\varepsilon(v)\|_{\mathcal{H}}$ is equivalent on V to the usual norm $\|\cdot\|_{H_1}$. Moreover, using the Sobolev's trace theorem, there exists a constant c_0 which depends only on Ω , Γ_C and Γ_D such that

$$\|v\|_{L^2(\Gamma_C)^d} \leq c_0 \|v\|_V, \quad \forall v \in V. \quad (3.4)$$

We also need to introduce the spaces

$$Q = \{ \eta \in H^1(\Omega), \eta = 0 \text{ on } \Gamma_D \cup \Gamma_N \}, \quad W = \{ \psi \in H^1(\Omega), \psi = 0 \text{ on } \Gamma_a \},$$

endowed with the following inner products and associated norms

$$(\theta, \eta)_Q = (\theta, \eta)_{H^1(\Omega)}, \quad \|\eta\|_Q = \|\eta\|_{H^1(\Omega)}, \quad \forall \theta, \eta \in Q,$$

$$(\varphi, \psi)_W = (\varphi, \psi)_{H^1(\Omega)}, \quad \|\psi\|_W = \|\psi\|_{H^1(\Omega)}, \quad \forall \varphi, \psi \in W.$$

Since Γ_D and Γ_a are on nonzero measure, it follows from the Friedrichs-Poincaré inequalities that the two spaces $(Q, \|\cdot\|_Q)$ and $(W, \|\cdot\|_W)$ are real Hilbert. Moreover, using the Sobolev trace theorem, there exist constants $c_1 > 0$ and $c_2 > 0$ such that

$$\|\eta\|_{L^2(\Gamma_C)} \leq c_1 \|\eta\|_Q, \quad \forall \eta \in Q, \quad (3.5)$$

$$\|\xi\|_{L^2(\Gamma_C)} \leq c_2 \|\xi\|_W, \quad \forall \xi \in W. \quad (3.6)$$

Recall that, for a regular vector fields $q, D \in \{\varpi \in H, \operatorname{div} \varpi \in L^2(\Omega)\}$, the below Green formulas hold

$$(q, \nabla \eta)_{L^2(\Omega)^d} + (\operatorname{div} q, \eta)_{L^2(\Omega)} = \int_{\Gamma} q \cdot \nu \eta \, da, \quad \forall \eta \in H^1(\Omega), \quad (3.7)$$

$$(D, \nabla \xi)_{L^2(\Omega)^d} + (\operatorname{div} D, \nabla \xi)_{L^2(\Omega)} = \int_{\Gamma} D \cdot n \xi \, da, \quad \forall \xi \in H^1(\Omega). \quad (3.8)$$

Let $(X, \|\cdot\|_X)$ be a real Banach space. For every $1 \leq p \leq \infty$, we will use the spaces $L^p(0, T; X)$ endowed with its standard norm and the sobolev space $W^{1,\infty}(0, T; X)$ equipped with the norm

$$\|x\|_{W^{1,\infty}(0,T;X)} = \|x\|_{L^\infty(0,T;X)} + \|\dot{x}\|_{L^\infty(0,T;X)}.$$

Finally, we will also use $C^1([0, T]; X)$ the spaces of continuous functions from $[0, T]$ to X endowed with

$$\|x\|_{C([0,T];X)} = \max_{t \in [0,T]} \|x(t)\|_X.$$

In ordre to study of the problem (P) , we need hypotheses on the data's problem. Hence, we assume

(H_1) : The elasticity tensor $\mathfrak{F} = (f_{ijkl}) : \Omega \times \mathbb{S}^d \rightarrow \mathbb{S}^d$ is symmetric, continuous and definite positive

$$f_{ijkl} = f_{jikl} = f_{klij} = f_{ijlk} \in L^\infty(\Omega),$$

$$f_{ijkl} \xi_{kl} \xi_{ij} \geq \alpha_0 \|\xi\|^2, \quad \forall \xi = (\xi_{ij}) \in \mathbb{S}^d.$$

(H_2) : The piezoelectric tensor $\mathcal{E} = (e_{ijk}) : \Omega \times \mathbb{S}^d \rightarrow \mathbb{R}^d$ is partial symmetric and continuous

$$e_{ijk} = e_{ikj} \in L^\infty(\Omega).$$

We recall here that the transposite tensor $\mathcal{E}^* = (e_{ijk}^*)$ is given by $e_{ijk}^* = e_{kij}$ and we have

$$\mathcal{E}\sigma \cdot v = \sigma \cdot \mathcal{E}^*v, \quad \forall \sigma \in \mathbb{S}^d, \forall v \in \mathbb{R}^d. \quad (3.9)$$

The thermal expansion tensor $\mathcal{M} = (m_{ij}) : \Omega \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ is symmetric and continuous

$$m_{ij} = m_{ji} \in L^\infty(\Omega).$$

The pyroelectric vector field $\mathcal{P} = (p_i) : \Omega \rightarrow \mathbb{R}^d$ is continuous

$$p_i \in L^\infty(\Omega).$$

Notice that the two conditions above, allows us to define $M_{\mathcal{M}} = \sup_{ij} \|m_{ij}\|_{L^\infty(\Omega)}$ and $M_{\mathcal{P}} = \sup_i \|p_i\|_{L^\infty(\Omega)}$.

(H₃) : The electric permittivity $\beta = (\beta_{ij}) : \Omega \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ is symmetric, continuous and definite positive

$$\beta_{ij} = \beta_{ji} \in L^\infty(\Omega), \quad \beta_{ij} b_i b_j \geq m_\beta \|b\|^2, \quad \forall b = (b_i) \in \mathbb{R}^d.$$

The thermal conductivity $\mathcal{K} = (k_{ij}) : \Omega \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ is symmetric, continuous and definite positive

$$k_{ij} = k_{ji} \in L^\infty(\Omega), \quad k_{ij} z_i z_j \geq m_{\mathcal{K}} \|z\|^2, \quad \forall z = (z_i) \in \mathbb{R}^d.$$

(H₄) : The coefficient of friction satisfies $\mu \geq 0 \in L^\infty(\Gamma_C)$ a.e on Γ_C . Then, we can pose

$$\bar{\mu} = \sup_{t \in [0, T]} \|\mu\|_{L^\infty(\Gamma_C)}.$$

(H₅) : The mapping $R : H'_{\Gamma_C} \rightarrow L^2(\Gamma_C)$ is linear compact and continuous with $c_R = \|R\|$.

(H₆) : The surface electrical conductivity and the coefficient of heat exchange satisfies for $\pi = \psi, k_c$

- (a) $(\exists L_\pi > 0), (\forall a, b \in \mathbb{R}^+), |\pi(\cdot, a) - \pi(\cdot, b)| < L_\pi |a - b|$ a.e. on Γ_C ,
- (b) For all $a \in \mathbb{R}^+$, the mapping $x \mapsto \pi(x, a)$ is measurable on Γ_C ,
- (c) For all $a \in \mathbb{R}^+$, the mapping $x \mapsto \pi(x, a)$ is M_π -bounded a.e. on Γ_C ,
- (d) $x \rightarrow \pi(x, u) = 0$ for $u \leq 0$, a.e. $x \in \Gamma_C$.

(H₇) : The normal compliance function $p_r : \Gamma_C \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$ satisfies for $r = \nu, \tau$

- (a) $(\exists L_r > 0), (\forall a, b \in \mathbb{R}^+), |p_r(\cdot, a) - p_r(\cdot, b)| < L_r |a - b|$ a.e. on Γ_C ,
- (b) For all $a \in \mathbb{R}^+$, the mapping $x \mapsto p_r(x, a)$ is measurable on Γ_C ,
- (c) For all $a \in \mathbb{R}^+$, the mapping $x \mapsto p_\nu(x, a)$ is L_{p_ν} -bounded a.e. on Γ_C ,
- (d) $x \rightarrow p_r(x, u) = 0$ for $u \leq 0$, a.e. $x \in \Gamma_C$.

(H₈) : The function $S_c : \Gamma_C \times \mathbb{R} \rightarrow \mathbb{R}^+$ satisfies

- (a) $(\exists L_{S_c} > 0), (\forall r_1, r_2 \in \mathbb{R}^+), |S_c(\cdot, r_1) - S_c(\cdot, r_2)| < L_{S_c} |r_1 - r_2|$ a.e. on Γ_C ,
- (b) The mapping $S_c : \Gamma_C \times \mathbb{R} \rightarrow \mathbb{R}^+$ is Borel measurable,
- (c) For all $r \in \mathbb{R}$, the mapping $x \mapsto S_c(x, r)$ is S^* -bounded a.e. on Γ_C .

(H₉) : The forces, tractions, charges, heat source densities and the foundation's temperature satisfy

$$f_0 \in W^{1,\infty}(0, T; L^2(\Omega)^d), \quad \phi_0, q_0 \in W^{1,\infty}(0, T; L^2(\Omega)),$$

$$f_N \in W^{1,\infty}(0, T; L^2(\Gamma_N)^d), \quad \phi_b \in W^{1,\infty}(0, T; L^2(\Gamma_b)), \quad \theta_F \in L^2(\Gamma_C).$$

Using Riesz's representation theorem, we define $f : [0, T] \rightarrow V$, $q_e : [0, T] \rightarrow W$, $\Theta : [0, T] \rightarrow Q$ by

$$(f, v)_V = \int_{\Omega} f_0 v \, dx + \int_{\Gamma_N} f_N v \, da, \quad \forall v \in V, \quad (3.10)$$

$$(q_e, \xi)_W = \int_{\Omega} \phi_0 \xi \, dx - \int_{\Gamma_b} \phi_b \xi \, da, \quad \forall \xi \in W, \quad (3.11)$$

$$(\Theta, \eta)_{L^2(\Omega)} = \int_{\Omega} q_0 \eta \, dx, \quad \forall \eta \in Q. \quad (3.12)$$

We consider $j : V \times V \rightarrow \mathbb{R}$, $\chi : V \times V \times Q \rightarrow \mathbb{R}$, $\omega : V \times Q \times Q \rightarrow \mathbb{R}$ and $l : V \times W \times W \rightarrow \mathbb{R}$ such that

$$j(u; v) = \int_{\Gamma_C} p_\nu(u_\nu - g)v_\nu \, da + \int_{\Gamma_C} p_\tau(u_\tau - g) \|v_\tau\| \, da, \quad (3.13)$$

$$\chi(u; v; \eta) = \int_{\Gamma_C} \mu p_\nu(u_\nu - g) S_c(\cdot, \|v_\tau\|) \eta \, da, \quad (3.14)$$

$$\omega((u, \theta); \eta) = \int_{\Gamma_C} k_c(u_\nu - g) \phi_L(\theta - \theta_F) \eta \, da, \quad \forall \theta \in Q, \forall \eta \in Q, \quad (3.15)$$

$$l((u, \varphi); \xi) = \int_{\Gamma_C} \psi(u_\nu - g) \phi_L(\varphi - \varphi_F) \xi \, da, \quad \forall \theta \in Q, \forall \eta \in Q, \quad (3.16)$$

for all $(u, \varphi, \theta) \in X$, $v \in V$, $\eta \in Q$. We consider some assumptions on the initial data

$$\left\{ \begin{array}{l} u_0 \in V \text{ and } \theta_0 \in Q \text{ such that for all } (v, \xi) \in V \times W, \text{ we have} \\ (\mathfrak{F} \varepsilon(u_0), \varepsilon(v))_{\mathcal{H}} + (\mathcal{E}^* \nabla \varphi_0, \varepsilon(v))_H - (\mathcal{M} \theta_0, \varepsilon(v))_H + j(u_0; v) \geq (f(0), v)_V, \\ (\beta \nabla \varphi_0, \nabla \xi)_H = (\mathcal{E} \varepsilon(u_0), \nabla \xi)_H + (\mathcal{P} \theta_0, \nabla \xi)_H + (q_e(0), \xi)_W - l((u_0, \varphi_0); \xi), \\ \text{and there exists } T_0 \in L^2(\Omega) \text{ such that} \\ (\mathcal{K} \nabla \theta_0, \nabla \eta)_H + \omega(u_0, \theta_0, \eta) - (\Theta(0), \eta)_{L^2(\Omega)} = (T_0, \eta)_{L^2(\Omega)}. \end{array} \right. \quad (3.17)$$

According to this notation and by a standard procedure based on Green's formulas, We can state the variational formulations of the problem P , in the terms of displacement, electric potential and temperature.

Problem (PV). Find a displacement field $u : [0, T] \rightarrow V$, an electric potential $\varphi : [0, T] \rightarrow W$ and a temperature field $\theta : [0, T] \rightarrow Q$ such that

$$(\mathfrak{F} \varepsilon(u), \varepsilon(v - \dot{u}))_{\mathcal{H}} + (\mathcal{E}^* \nabla \varphi, \varepsilon(v - \dot{u}))_H - (\mathcal{M} \theta, \varepsilon(v - \dot{u}))_H + j(u, v) - j(u, \dot{u}) \quad (3.18)$$

$$\geq (f, v - \dot{u})_V, \quad \forall v \in V.$$

$$(\beta \nabla \varphi, \nabla \xi)_H - (\mathcal{E} \varepsilon(u), \nabla \xi)_H - (\mathcal{P} \theta, \nabla \xi)_H + l((u, \varphi); \xi) = (q_e, \xi)_W, \quad \forall \xi \in W. \quad (3.19)$$

$$(\dot{\theta}, \eta)_{L^2(\Omega)} + (\mathcal{K} \nabla \theta, \nabla \eta)_H + (\mathcal{M} \dot{\varepsilon}(u), \eta)_{L^2(\Omega)} - (\mathcal{P} \nabla \dot{\varphi}, \eta)_{L^2(\Omega)} \quad (3.20)$$

$$- \chi(u; \dot{u}; \eta) + \omega(u, \theta; \eta) = (\Theta, \eta)_{L^2(\Omega)}, \quad \forall \eta \in Q.$$

$$u(\cdot, 0) = u_0, \quad \varphi(\cdot, 0) = \varphi_0, \quad \theta(\cdot, 0) = \theta_0 \quad \text{in } \Omega. \quad (3.21)$$

Our main existence result that we state now and prove in the next sections, is the following.

Theorem 3.1. Assume that (H_1) - (H_9) and (3.17) hold. If there exists a positive constant L^* such that $\bar{\mu} + L_\tau + L_\psi L + M_\psi + L_{k_c} L + M_{k_c} \leq L^*$, then the problem (PV) has at least a solution.

4. AN ABSTRACT RESULT

The existence of solutions of problems (PV) will be obtained by using the following abstract problem.

Let X be a real Hilbert space endowed with the inner product $(\cdot, \cdot)_X$ and the associated norm $\|\cdot\|_X$. We consider the problem of finding $x \in X$ such that

$$(Ax, y - x)_X + (Bx, y - x)_X + j(x, y) - j(x, x) \geq (f, y - x)_X, \quad \forall y \in X. \quad (4.1)$$

In the study the problem (4.1), we make the following assumptions :

1. The operator $A : X \rightarrow X$ is strongly monotone and Lipschitz continuous ,

$$(h_1) : \begin{cases} (a) \text{ There exists a constant } m > 0 \text{ such that for all } x, y \in X, \text{ one has} \\ \quad (Ax - Ay, x - y)_X \geq m \|x - y\|_X^2. \\ (b) \text{ There exists a constant } M > 0 \text{ such that for all } x, y \in X, \text{ one has} \\ \quad \|Ax - Ay\|_X \leq M \|x - y\|_X. \end{cases}$$

2. The operator $B : X \rightarrow X$ satisfies

$$(h_2) : \text{There exists } m > 0 \text{ such that } (Bx, x)_X \geq -m \|x\|_X^2, \quad \forall x \in X.$$

$$(h_3) : \begin{cases} \text{For every sequence } \{\eta_n\} \subset X \text{ such that } \eta_n \rightarrow \eta \in X, \text{ then there} \\ \text{exist a subsequence } \{\eta_{n'}\} \subset X \text{ such that } B\eta_{n'} \rightarrow B\eta \text{ strongly in } X. \end{cases}$$

$$(h_4) : (Bx - By, y - x)_X < (m - \alpha) \|x - y\|_X^2, \quad \forall x \neq y \in X.$$

$$(h_5) : \begin{cases} \text{There exists } 0 < \beta < (m - \alpha) \text{ such that} \\ (Bx - By, y - x)_X \leq \beta \|x - y\|_X^2, \quad \forall x, y \in X. \end{cases}$$

3. The functional $j : X \times X \rightarrow \mathbb{R}$ satisfies

$$(h_6) : j(\eta, \cdot) : X \rightarrow \mathbb{R} \text{ is a convex functional on } X, \quad \forall \eta \in X.$$

It is well known that there exists the directional derivative j'_2 given by

$$(h_7) : j'_2(\eta, x; y) = \lim_{\lambda \rightarrow 0} \frac{1}{\lambda} [j(\eta, x + \lambda y) - j(\eta, x)], \quad \forall \eta, x, y \in X.$$

4. The following assumptions are satisfied

$$(J_1) : \begin{cases} \text{For every sequence } \{x_n\} \subset X \text{ with } \|x_n\|_X \rightarrow \infty \\ \text{and for every sequence } \{t_n\} \subset [0, 1] \text{ one has} \\ \liminf_{n \rightarrow \infty} \left[\frac{1}{\|x_n\|_X^2} j'_2(t_n x_n, x_n; -x_n) \right] < m - C. \end{cases}$$

$$(J_2) : \begin{cases} \text{For every sequence } \{x_n\} \subset X \text{ with } \|x_n\|_X \rightarrow \infty \\ \text{and for every bounded sequence } \{\eta_n\} \subset X \text{ one has} \\ \liminf_{n \rightarrow \infty} \left[\frac{1}{\|x_n\|_X^2} j'_2(\eta_n, x_n; -x_n) \right] < m. \end{cases}$$

$$(J_3) : \begin{cases} \text{For every sequence } \{x_n\} \subset X \text{ and } \{\eta_n\} \subset X \text{ such that} \\ x_n \rightharpoonup x \in X, \eta_n \rightharpoonup \eta \in X \text{ and for every } y \in X \text{ one has} \\ \limsup_{n \rightarrow \infty} [j(\eta_n, y) - j(\eta_n, x_n)] < j(\eta, y) - j(\eta, x). \end{cases}$$

$$(J_4) : j(x, y) - j(x, x) + j(y, x) - j(y, y) \leq m \|x - y\|_X^2, \quad \forall x \neq y \in X.$$

$$(J_5) : \begin{cases} \text{There exists } \alpha < m \text{ such that for all } x, y \in X \text{ one has} \\ j(x, y) - j(x, x) + j(y, x) - j(y, y) \leq \alpha \|x - y\|_X^2. \end{cases}$$

Under all these assumptions, we have the following result.

Theorem 4.1. *Assume the conditions (h_1) - (h_3) and (h_6) hold, then :*

1. *Under the assumptions (J_1) - (J_3) and (J_5) , the problem (4.1) has at least one solution $x \in X$.*
2. *Under the assumptions (J_1) - (J_3) , (J_5) and (h_4) , the problem (4.1) has a unique solution.*
3. *Under the assumptions (J_1) - (J_3) , (J_5) and (h_5) , the problem (4.1) has a unique solution $x = x_f$ which depends Lipschitz continuously on f with the Lipschitz constant $(m - \alpha - \beta)^{-1}$.*

Theorem 4.1 has been obtained in [8] and therefore we do not provide here the details of the proof. We just specify that it was obtained in several step and it is based on topological degree theory as well as on convexity, monotonicity, compactness and fixed point arguments.

5. EXISTENCE OF THE DISCRETE SOLUTION

The problem (PV) can be integrated in time by an implicit scheme. We use a uniform subdivision $0 = t_0 < t_1 < \dots < t_n = T$ of the time interval $[0, T]$ where $t_i = i \Delta t$ for $i = 0, \dots, n$ and $\Delta t = \frac{T}{n}$. For any function ζ , we denote by ζ^i the approximation of the value $\zeta(t_i)$, by $\Delta \zeta^i$ the backward difference $\zeta^{i+1} - \zeta^i$ and if ζ is continuous, we use the notation $\zeta^i = \zeta(t_i)$. In each time step, we then obtain the following incremental problems (PV^i) defined for $u(\cdot, 0) = u_0$, $\varphi(\cdot, 0) = \varphi_0$ and $\theta(\cdot, 0) = \theta_0$ by

Problem (PV^i). Find a displacement $u^{i+1} \in V$, an electric potential $\varphi^{i+1} \in W$ and a temperature $\theta^{i+1} \in Q$ such that :

$$(\mathfrak{F} \varepsilon(u^{i+1}), \varepsilon(v - u^{i+1}))_{\mathcal{H}} + (\mathcal{E}^* \nabla \varphi^{i+1}, \varepsilon(v - u^{i+1}))_H - (\mathcal{M} \theta^{i+1}, \varepsilon(v - u^{i+1}))_H + j(u^{i+1}, v - u^i) - j(u^{i+1}, u^{i+1} - u^i) \geq (f^{i+1}, v - u^{i+1})_V, \quad \forall v \in V, \quad (5.1)$$

$$(\beta \nabla \varphi^{i+1}, \nabla \xi)_H - (\mathcal{E} \varepsilon(u^{i+1}), \nabla \xi)_H - (\mathcal{P} \theta^{i+1}, \nabla \xi)_H + l((u^{i+1}, \varphi^{i+1}); \xi) = (q_e^{i+1}, \xi)_W, \quad \forall \xi \in W, \quad (5.2)$$

$$(\theta^{i+1}, \eta)_{L^2(\Omega)} + \Delta t (\mathcal{K} \nabla \theta^{i+1}, \nabla \eta)_H + (\mathcal{M} \varepsilon(u^{i+1}), \eta)_{L^2(\Omega)} - (\mathcal{P} \nabla \varphi^{i+1}, \eta)_{L^2(\Omega)} - \Delta t \chi(u^{i+1}; \frac{u^{i+1} - u^i}{\Delta t}; \eta) + \Delta t \omega(u^{i+1}, \theta^{i+1}, \eta) = \Delta t (\Theta^{i+1}, \eta)_{L^2(\Omega)} + (\theta^i, \eta)_{L^2(\Omega)} + (\mathcal{M} \varepsilon(u^i), \eta)_{L^2(\Omega)} - (\mathcal{P} \nabla \varphi^i, \eta)_{L^2(\Omega)}, \quad \forall \eta \in Q. \quad (5.3)$$

For every $z_1 \in L^2(\Gamma_C)$, $z_2 \in L^2(\Gamma_C)$ and $z_3 \in L^2(\Gamma_C)$ we define the functions, $\forall \eta \in Q, \forall \xi \in W$

$$\chi_{z_1}(\eta) = \int_{\Gamma_C} z_1 \eta \, da, \quad \omega_{z_2}(\eta) = \int_{\Gamma_C} z_2 \eta \, da, \quad \ell_{z_3}(\xi) = \int_{\Gamma_C} z_3 \eta \, da. \quad (5.4)$$

and we construct the following intermediate problem in which $z = (z_1, z_2, z_3)$ is supposed to be known.

Problem (PV_z^i). Find a displacement $u_z^{i+1} \in V$, an electric potential $\varphi_z^{i+1} \in W$ and a temperature $\theta_z^{i+1} \in Q$ such that :

$$(\mathfrak{F} \varepsilon(u_z^{i+1}), \varepsilon(v - u_z^{i+1}))_{\mathcal{H}} + (\mathcal{E}^* \nabla \varphi_z^{i+1}, \varepsilon(v - u_z^{i+1}))_H - (\mathcal{M} \theta_z^{i+1}, \varepsilon(v - u_z^{i+1}))_H + j((u_z^{i+1}, \varphi_z^{i+1}, \theta_z^{i+1}), v - u^i) - j((u_z^{i+1}, \varphi_z^{i+1}, \theta_z^{i+1}), u_z^{i+1} - u^i) \geq (f^{i+1}, v - u_z^{i+1})_V, \quad \forall v \in V. \quad (5.5)$$

$$(\beta \nabla \varphi_z^{i+1}, \nabla \xi)_H - (\mathcal{E} \varepsilon(u_z^{i+1}), \nabla \xi)_H - (\mathcal{P} \theta_z^{i+1}, \nabla \xi)_H + \ell_{z_3}(\xi) = (q_e^{i+1}, \xi)_W, \quad \forall \xi \in W. \quad (5.6)$$

$$(\theta_z^{i+1}, \eta)_{L^2(\Omega)} + \Delta t (\mathcal{K} \nabla \theta_z^{i+1}, \nabla \eta)_H + (\mathcal{M} \varepsilon(u_z^{i+1}), \eta)_{L^2(\Omega)} - (\mathcal{P} \nabla \varphi_z^{i+1}, \eta)_{L^2(\Omega)} + \Delta t \omega_{z_2}(\eta) - \Delta t \chi_{z_1}(\eta) = \Delta t (\Theta^{i+1}, \eta)_{L^2(\Omega)} + (\theta^i, \eta)_{L^2(\Omega)} + (\mathcal{M} \varepsilon(u^i), \eta)_{L^2(\Omega)} - (\mathcal{P} \nabla \varphi^i, \eta)_{L^2(\Omega)}, \quad \forall \eta \in Q. \quad (5.7)$$

We consider an element Θ_z^{i+1} of Q defined for all $\eta \in Q$ by

$$\begin{aligned} (\Theta_z^{i+1}, \eta)_Q &= (\Delta t \Theta^{i+1}, \eta)_{L^2(\Omega)} + (\theta^i, \eta)_{L^2(\Omega)} + (\mathcal{M} \varepsilon(u^i), \eta)_{L^2(\Omega)} - (\mathcal{P} \nabla \varphi^i, \eta)_{L^2(\Omega)} \\ &\quad + \Delta t \chi_{z_1}(\eta) - \Delta t \omega_{z_2}(\eta). \end{aligned}$$

To solve the problem (PV_z^i) , we consider the spaces $X = V \times W \times Q$ and $Y = L^2(\Gamma_C)^d \times (L^2(\Gamma_C))^2$ endowed with the following inner product and the associated norm $\|\cdot\|_X$ and $\|\cdot\|_Y$ such that

$$(x, y)_X = (u, v)_V + (\varphi, \xi)_W + (\theta, \eta)_Q, \quad (5.8)$$

$$(z, z')_Y = (z_1, z'_1)_{L^2(\Gamma_C)^d} + (z_2, z'_2)_{L^2(\Gamma_C)} + (z_3, z'_3)_{L^2(\Gamma_C)}, \quad (5.9)$$

for all $x = (u, \varphi, \theta)$, $y = (v, \xi, \eta) \in X$ and $z = (z_1, z_2, z_3)$, $z' = (z'_1, z'_2, z'_3) \in Y$.

Next, we define the operators $A : X \rightarrow X$ and $B : X \rightarrow X$ given by

$$\begin{aligned} (Ax, y)_X &= (\mathfrak{F} \varepsilon(u), \varepsilon(v))_{\mathcal{H}} + (\Delta t \mathcal{K} \nabla \theta, \nabla \eta)_H + (\beta \nabla \varphi, \nabla \xi)_H \\ &\quad + (\mathcal{E}^* \nabla \varphi, \varepsilon(v))_H - (\mathcal{E} \varepsilon(u), \nabla \xi)_H, \end{aligned} \quad (5.10)$$

$$\begin{aligned} (Bx, y)_X &= -(\mathcal{P} \theta, \nabla \xi)_H - (\mathcal{P} \nabla \varphi, \eta)_{L^2(\Omega)} + (\theta, \eta)_{L^2(\Omega)} \\ &\quad - (\mathcal{M} \theta, \varepsilon(v))_H + (\mathcal{M} \varepsilon(u), \eta)_{L^2(\Omega)}, \quad \forall x = (u, \varphi, \theta), y = (v, \xi, \eta) \in X, \end{aligned} \quad (5.11)$$

the functionals $J : X \times X \rightarrow \mathbb{R}$ defined by

$$J(x, y) = j(u; v), \quad \forall x = (u, \varphi, \theta), y = (v, \xi, \eta) \in X. \quad (5.12)$$

and the element f_z^{i+1} of X given by

$$f_z^{i+1} = (f^{i+1}, q_e^{i+1} - \ell_{z_3}(\xi), \Theta_z^{i+1}). \quad (5.13)$$

We have the following lemma.

Lemma 5.1. The problem (PV_z^i) is equivalent to the following problem

$$\left\{ \begin{array}{l} \text{Find } x_z^{i+1} = (u_z^{i+1}, \varphi_z^{i+1}, \theta_z^{i+1}) \in X \text{ such that :} \\ (Ax_z^{i+1}, y - x_z^{i+1})_X + (Bx_z^{i+1}, y - x_z^{i+1})_X + J(x_z^{i+1}, y - x^i) \\ \quad - J(x_z^{i+1}, x_z^{i+1} - x^i) \geq (f_z^{i+1}, y - x_z^{i+1})_X, \quad (\forall y \in X). \end{array} \right. \quad (5.14)$$

Proof. Let $x_z^{i+1} = (u_z^{i+1}, \varphi_z^{i+1}, \theta_z^{i+1}) \in X$ be a solution to Problem (PV_z^i) and let $y = (v, \xi, \eta) \in X$. We use the test function $\xi - \varphi_z^{i+1}$ in (5.6) and $\eta - \theta_z^{i+1}$ in (5.7). We add the corresponding inequalities to (5.5) and we use (5.10)-(5.13) to obtain (5.14).

Conversely, let $x_z^{i+1} = (u_z^{i+1}, \varphi_z^{i+1}, \theta_z^{i+1}) \in X$ be a solution to the quasivariational inequality (5.14). If we take $y = (v, \varphi_z^{i+1}, \theta_z^{i+1})$ in (5.14) where v is an arbitrary element of V , we obtain (5.5) and if we take successively $y = (v, \varphi_z^{i+1} + \xi, \theta_z^{i+1})$ and $y = (v, \varphi_z^{i+1} - \xi, \theta_z^{i+1})$ in (5.14) where ξ is an arbitrary element of W , we deduce (5.6). In the same way, we take successively $y = (v, \varphi_z^{i+1}, \theta_z^{i+1} + \eta)$ and $y = (v, \varphi_z^{i+1}, \theta_z^{i+1} - \eta)$ in (5.14) where η is an arbitrary element of Q to get (5.7). Thus, the lemma is proved. \square

Using the previous lemma, we obtain the following existence and uniqueness result of (PV_z^i) .

Lemma 5.2. *For every z of $(L^2(\Gamma_C))^3$, the problem (PV_z^i) has a unique solution*

$$x_z^{i+1} = (u_z^{i+1}, \varphi_z^{i+1}, \theta_z^{i+1}) \in V \times W \times Q.$$

In order to proving this lemma, we use theorem 4.1 by taking to the account the mathematical inequality $c_0^2(L_\nu + L_\tau) + 2M_p \leq m$. We start by investigating the proprieties of the operators A , B and the functionals J given in (5.12)-(3.13). Thus, we have the following lemmas.

Lemma 5.3. *The operator $A : X \rightarrow X$ is strongly monotone and Lipschitz continuous.*

Proof. We consider two elements $x_1 = (u_1, \varphi_1, \theta_1)$ and $x_2 = (u_2, \varphi_2, \theta_2)$ of X . Using (4.1) we can get

$$\begin{aligned} (Ax_1 - Ax_2, x_1 - x_2)_X &= (\mathfrak{F} \varepsilon(u_1) - \mathfrak{F} \varepsilon(u_2), \varepsilon(u_1) - \varepsilon(u_2))_{\mathcal{H}} \\ &\quad + (\beta \nabla \varphi_1 - \beta \nabla \varphi_2, \nabla \varphi_1 - \nabla \varphi_2)_H + (\Delta t \mathcal{K} \nabla \theta_1 - \Delta t \mathcal{K} \nabla \theta_2, \nabla \theta_1 - \nabla \theta_2)_H \\ &\quad + (\mathcal{E}^* \nabla \varphi_1 - \mathcal{E}^* \nabla \varphi_2, \varepsilon(u_1) - \varepsilon(u_2))_H - (\mathcal{E} \varepsilon(u_1) - \mathcal{E} \varepsilon(u_2), \nabla \varphi_1 - \nabla \varphi_2)_H. \end{aligned}$$

Taking to the account that $(\mathcal{E}^* \nabla \varphi, \varepsilon(u))_H = (\mathcal{E} \varepsilon(u), \nabla \varphi)_H$, we find

$$\begin{aligned} (Ax_1 - Ax_2, x_1 - x_2)_X &= (\mathfrak{F} \varepsilon(u_1) - \mathfrak{F} \varepsilon(u_2), \varepsilon(u_1) - \varepsilon(u_2))_{\mathcal{H}} \\ &\quad + (\beta \nabla \varphi_1 - \beta \nabla \varphi_2, \nabla \varphi_1 - \nabla \varphi_2)_H + (\Delta t \mathcal{K} \nabla \theta_1 - \Delta t \mathcal{K} \nabla \theta_2, \nabla \theta_1 - \nabla \theta_2)_H. \end{aligned}$$

Combining with (H_1) and (H_3) , there exists $m > 0$ depending on \mathfrak{F} , β , \mathcal{K} , Ω , Γ_D , Γ_N , Γ_a such that

$$(Ax_1 - Ax_2, x_1 - x_2)_X \geq m \left(\|u_1 - u_2\|_V^2 + \|\varphi_1 - \varphi_2\|_W^2 + \|\theta_1 - \theta_2\|_Q^2 \right).$$

Thus, it follows from (5.8) that

$$(Ax_1 - Ax_2, x_1 - x_2)_X \geq m \|x_1 - x_2\|_X^2. \quad (5.15)$$

In the same way, H_1 and H_3 imply that there exists $c_4 > 0$ such that

$$(Ax_1 - Ax_2, y)_X \leq c_4 \left(\|u_1 - u_2\|_V \|v\|_V + \|u_1 - u_2\|_V \|\xi\|_W + \|\theta_1 - \theta_2\|_Q \|\eta\|_Q + \|\varphi_1 - \varphi_2\|_W \|\xi\|_W + \|\varphi_1 - \varphi_2\|_W \|v\|_V \right).$$

Then, we obtain

$$(Ax_1 - Ax_2, y)_X \leq 5 c_4 \|x_1 - x_2\|_X \|y\|_X, \quad \forall y \in X.$$

However, if we set $y = Ax_1 - Ax_2$ and $M = 5 c_4$, we find

$$\|Ax_1 - Ax_2\|_X \leq M \|x_1 - x_2\|_X \quad (5.16)$$

and thus the lemma 5.3 is established. \square

Next, we recall that the functional J defined by (5.12) and (3.13), satisfies (h_6) . Moreover, we have

Lemma 5.4. *The functional J satisfies the assumptions (J_1) , (J_2) and (J_3) .*

Proof. The proof of this lemma can be found in [5].

Lemma 5.5. *If the assumption (H_6) hold, then the functional J satisfies the inequality*

$$J(x, y) - J(x, x) + J(y, x) - J(y, y) \leq \alpha \|x - y\|_X^2, \quad \forall x, y \in X. \quad (5.17)$$

Proof. The proof of this lemma can be found in [5] with $\alpha = c_0^2(L_\nu + L_\tau)$.

Lemma 5.6. *The operator $B : X \rightarrow X$ satisfies the conditions (h_2) , (h_3) and (h_5) .*

Proof. Using the assumptions on \mathcal{P} (see (H_2)), we obtain

$$\begin{aligned} (\mathcal{P}\theta, \nabla\varphi)_H + (\mathcal{P}\nabla\varphi, \theta)_{L^2(\Omega)} &= 2(\mathcal{P}\theta, \nabla\varphi)_H \\ &\leq 2M_{\mathcal{P}} \|\nabla\varphi\|_H \|\theta\|_{L^2(\Omega)} \\ &\leq 2M_{\mathcal{P}} \|\varphi\|_W \|\theta\|_Q \\ &\leq C \|x\|_X^2 \end{aligned}$$

where $C = 2M_{\mathcal{P}}$. Then

$$-(\mathcal{P}\theta, \nabla\varphi)_H - (\mathcal{P}\nabla\varphi, \theta)_{L^2(\Omega)} \geq -C \|x\|_X^2. \quad (5.18)$$

Combined with $(\mathcal{M}\theta, \varepsilon(u))_H = (\mathcal{M}\varepsilon(u), \theta)_{L^2(\Omega)}$ and $(\theta, \theta)_{L^2(\Omega)} \geq 0$, we get

$$(Bx, x)_X \geq -C \|x\|_X^2, \quad \forall x \in X \quad (5.19)$$

and then (h_2) is satisfied. Let us now consider the sequence $x_n = (u_n, \varphi_n, \theta_n)$ of X such that

$$x_n = (u_n, \varphi_n, \theta_n) \rightharpoonup x = (u, \varphi, \theta) \in X.$$

It follows from (5.8) and (5.11) that there exists a constant $c_6 \geq 0$ such that

$$\begin{aligned} (Bx_n - Bx, y)_X &= -(\mathcal{P}\theta_n - \mathcal{P}\theta, \nabla\xi)_H - (\mathcal{P}\nabla\varphi_n - \mathcal{P}\nabla\varphi, \eta)_{L^2(\Omega)} + (\theta_n - \theta, \eta)_{L^2(\Omega)} \\ &\quad - (\mathcal{M}\theta_n - \mathcal{M}\theta, \varepsilon(v))_H + (\mathcal{M}\varepsilon(u_n) - \mathcal{M}\varepsilon(u), \eta)_{L^2(\Omega)} \\ &\leq c_6 \|x_n - x\|_X \|y\|_X, \quad \forall y = (v, \xi, \eta) \in X. \end{aligned}$$

Taking $y = Bx_n - Bx$ in the previous inequality, we have

$$\|Bx_n - Bx\|_X \leq c_6 \|x_n - x\|_X. \quad (5.20)$$

On the other hand, it comes from (5.14) where $x_z^{i+1} \in X$ is still denoted $x \in X$ that

$$(Ax_n - Ax, x_n - x)_X + (Bx_n - Bx, x_n - x)_X \leq J(x, x_n) - J(x, x) + J(x_n, x) - J(x_n, x_n),$$

Applying (5.15), (5.17) and (5.19), we obtain

$$(m - C) \|x_n - x\|_X^2 \leq (L_\nu + L_\tau) \|x_n - x\|_Y^2$$

and since $\alpha \leq (m - C)$, we have

$$\alpha \|x_n - x\|_X^2 \leq (L_\nu + L_\tau) \|x_n - x\|_Y^2.$$

Then

$$\begin{aligned} \|x_n - x\|_X &\leq \sqrt{\frac{(L_\nu + L_\tau)}{\alpha}} \|x_n - x\|_Y \\ &\leq \frac{1}{c_0} \|x_n - x\|_Y \end{aligned} \quad (5.21)$$

Combining (5.23) and (5.24), we deduce

$$\|Bx_n - Bx\|_X \leq \frac{1}{c_0} \|x_n - x\|_Y. \quad (5.22)$$

Since the trace map $\gamma : X \rightarrow Y$ is compact operator, the weak convergence $x_n \rightharpoonup x$ leads to the strong convergence $x_n \rightarrow x$ in Y . So, we conclude that $Bx_n \rightarrow Bx$ in X strongly for a subsequence and that prove the condition (h_3) . Finally, for all $x_1 = (u_1, \varphi_1, \theta_1)$, $x_2 = (u_2, \varphi_2, \theta_2)$ of X , (5.11) implies that

$$\begin{aligned} (Bx_1 - Bx_2, x_2 - x_1)_X &= 2(\mathcal{P}\theta_1 - \mathcal{P}\theta_2, \nabla\varphi_1 - \nabla\varphi_2)_H \\ &\leq C \|x_1 - x_2\|_X \\ &\leq \beta \|x_1 - x_2\|_X. \end{aligned}$$

where $\beta = C > 0$ and since $\alpha + C \leq m$ we have $0 \leq \beta \leq m - \alpha$. Thus, the condition (h_5) is satisfied.

At the end, using the lemmas 5.1-5.6 and the theorem 4.1 to deduce that problem PV_z^i has a unique solution and it is easy to show that this solution depends Lipschitz continuously on $z^{i+1} \in L^2(\Gamma_C)^3$. In the next step, we consider the following operator

$$\Lambda : L^2(\Gamma_C) \times L^2(\Gamma_C) \times L^2(\Gamma_C) \rightarrow L^2(\Gamma_C) \times L^2(\Gamma_C) \times L^2(\Gamma_C)$$

such that for all $z = (z_1, z_2, z_3) \in L^2(\Gamma_C)^3$, we have

$$\Lambda z = \left[p_\tau(u_{z_1\nu}^{i+1} - g) S_C(\cdot, \frac{1}{\Delta t} \|u_{z_1\tau}^{i+1} - u^i\|); \right. \\ \left. \psi(u_{z_2\nu} - g) \phi_L(\varphi_{z_2}^{i+1} - \varphi_F); k_c(u_{z_3\nu} - g) \phi_L(\theta_{z_3}^{i+1} - \theta_F) \right].$$

Now, let's majorate the quantity $I = \|\Lambda z_1^{i+1} - \Lambda z_2^{i+1}\|_{L^2(\Gamma_C)^3}$, we have

$$I \leq \left\| [p_\tau(u_{z_1\nu}^{i+1} - g) - p_\tau(u_{z_1'\nu}^{i+1} - g)] S_C(\cdot, \frac{1}{\Delta t} \|u_{z_1\tau}^{i+1} - u^i\|) \right\|_{L^2(\Gamma_C)} \\ + \left\| \mu p_\nu(u_{z_1\nu}^{i+1} - g) [S_C(\cdot, \frac{1}{\Delta t} \|u_{z_1\tau}^{i+1} - u^i\|) - S_C(\cdot, \frac{1}{\Delta t} \|u_{z_1'\tau}^{i+1} - u^i\|)] \right\|_{L^2(\Gamma_C)} \\ + \left\| [\psi(u_{z_2\nu}^{i+1} - g) - \psi(u_{z_2'\nu}^{i+1} - g)] \phi_L(\varphi_{z_2}^{i+1} - \varphi_F) \right\|_{L^2(\Gamma_C)} \\ + \left\| \psi(u_{z_2\nu}^{i+1} - g) [\phi_L(\varphi_{z_2}^{i+1} - \varphi_F) - \phi_L(\varphi_{z_2'}^{i+1} - \varphi_F)] \right\|_{L^2(\Gamma_C)} \\ + \left\| [k_c(u_{z_3\nu}^{i+1} - g) - k_c(u_{z_3'\nu}^{i+1} - g)] \phi_L(\theta_{z_3}^{i+1} - \theta_F) \right\|_{L^2(\Gamma_C)} \\ + \left\| k_c(u_{z_3\nu}^{i+1} - g) [\phi_L(\theta_{z_3}^{i+1} - \theta_F) - \phi_L(\theta_{z_3'}^{i+1} - \theta_F)] \right\|_{L^2(\Gamma_C)}.$$

Using (H_4) - (H_8) and the Lipschitz-continuously dependence of the x_z^{i+1} on z^{i+1} , we deduce that there exists a constant $c_7 > 0$ such that

$$\left\| \Lambda z - \Lambda z' \right\|_{L^2(\Gamma_C)^3} \\ \leq c(\bar{\mu} + L_\tau) \|z_1 - z_1'\|_{L^2(\Gamma_C)} + (L_\psi L + M_\psi) \|z_2 - z_2'\|_{L^2(\Gamma_C)} \\ + (L_{k_c} L + M_{k_c}) \|z_3 - z_3'\|_{L^2(\Gamma_C)} \\ \leq c_7(\bar{\mu} + L_\tau + L_\psi L + M_\psi + L_{k_c} L + M_{k_c}) \|z - z'\|_{L^2(\Gamma_C)^3}.$$

We pose $L^* = \frac{1}{c_7}$, hence if $\bar{\mu} + L_\tau + L_\psi L + M_\psi + L_{k_c} L + M_{k_c} \leq L^*$, we deduce that Λ is a contraction operator. Then, it comes from Banach fixed point theorem that Λ has a unique fixed point z^* ($\Lambda z^* = z^*$) and therefore $x_{z^*}^{i+1} = (u_{z^*}^{i+1}, \varphi_{z^*}^{i+1}, \theta_{z^*}^{i+1}) \in X$ is the unique solution of the Problem (PV^i) .

6. CONVERGENCE ANALYSIS

For all $i = 0, \dots, n-1$, let $x^{i+1} = (u^{i+1}, \varphi^{i+1}, \theta^{i+1})$ be the unique solution of the problem (PV^i) . In order to study the convergence of $\{x^{i+1}\}_{i=0, \dots, n-1}$ when $n \rightarrow \infty$, we introduce the following continuous functions defined on $[t_i, t_{i+1}]$ ($i = 0, \dots, n-1$) by

$$u^n(t) = u^i + \frac{t - t_i}{\Delta t} \Delta u^i, \quad \varphi^n(t) = \varphi^i + \frac{t - t_i}{\Delta t} \Delta \varphi^i, \quad \theta^n(t) = \theta^i + \frac{t - t_i}{\Delta t} \Delta \theta^i \quad (6.1)$$

and the following piecewise constant functions defined on $(t_i, t_{i+1}]$ ($i = 0, \dots, n-1$) as follows

$$\bar{u}^n(t) = u^{i+1}, \quad \bar{\varphi}^n(t) = \varphi^{i+1}, \quad \bar{\theta}^n(t) = \theta^{i+1}, \quad \bar{g}^n(t) = g^{i+1} \quad (6.2)$$

where $g : [0, T] \rightarrow X$ given by

$$g = (f, q_e, \tilde{\Theta}) = (f, q_e, \Delta t \Theta) \in C([0, T], X). \quad (6.3)$$

Using some elementary manipulations, we have the following results.

Lemma 6.1. *There exists $k_1 \geq 0$ and $k_2 \geq 0$ such that*

$$\|x^{i+1}\|_X \leq k_1 \sum_{j=0}^{i+1} \|g^j\|_X + k_2. \quad (6.4)$$

Proof. Taking (5.10)-(5.12), then from (5.1)-(5.3) that for all $y = (v, \xi, \eta) \in X$, we have

$$\begin{aligned} & (Ax^{i+1}, y - x^{i+1})_X + (Bx^{i+1}, y - x^{i+1})_X + J(x^{i+1}, y - x^i) - J(x^{i+1}, x^{i+1} - x^i) \\ & \quad - \Delta t \tilde{\chi}(x^{i+1}, y - x^{i+1}) + \Delta t \tilde{\omega}(x^{i+1}, y - x^{i+1}) + \tilde{\ell}(x^{i+1}, y - x^{i+1}) \\ & \geq (g^{i+1}, y - x^{i+1})_X + (\theta^i, \eta - \theta^{i+1})_{L^2(\Omega)} + (\mathcal{M} \varepsilon(u^i), \eta - \theta^{i+1})_{L^2(\Omega)} \\ & \quad - (\mathcal{P} \nabla \varphi^i, \eta - \theta^{i+1})_{L^2(\Omega)}, \end{aligned} \quad (6.5)$$

where the functionals $\tilde{\chi}$, $\tilde{\omega}$ and $\tilde{\ell}$ are given by

$$\begin{aligned} \tilde{\chi}(x^{i+1}, y - x^{i+1}) &= \chi(u^{i+1}; \frac{u^{i+1} - u^i}{\Delta t}; \eta - \theta^{i+1}), \\ \tilde{\omega}(x^{i+1}, y - x^{i+1}) &= \omega((u^{i+1}, \theta^{i+1}), \eta - \theta^{i+1}), \\ \tilde{\ell}(x^{i+1}, y - x^{i+1}) &= \ell((u^{i+1}, \varphi^{i+1}), \xi - \varphi^{i+1}). \end{aligned}$$

Taking $y = 0$ in (6.5), we find

$$\begin{aligned}
& (Ax^{i+1}, x^{i+1})_X + (Bx^{i+1}, x^{i+1})_X \\
& \leq (g^{i+1}, x^{i+1})_X + J(x^{i+1}, x^i) - J(x^{i+1}, x^{i+1} - x^i) + \Delta t \tilde{\chi}(x^{i+1}, x^{i+1}) + \Delta t \tilde{\omega}(x^{i+1}, x^{i+1}) \\
& \quad + \tilde{\ell}(x^{i+1}, x^{i+1}) + (\theta^i, \theta^{i+1})_{L^2(\Omega)} + (\mathcal{M} \varepsilon(u^i), \theta^{i+1})_{L^2(\Omega)} - (\mathcal{P} \nabla \varphi^i, \theta^{i+1})_{L^2(\Omega)}.
\end{aligned} \tag{6.6}$$

Using (3.4), (3.13), (5.12) and the assumption $(H_6)(c)$, we obtain

$$\begin{aligned}
J(x^{i+1}, x^i) - J(x^{i+1}, x^{i+1} - x^i) &= j(u^{i+1}, u^i) - j(u^{i+1}, u^{i+1} - u^i) \\
&\leq c_0^2(L_\nu + L_\tau) \|x^{i+1}\|_X^2.
\end{aligned} \tag{6.7}$$

Moreover, we have

$$\begin{aligned}
\Delta t \tilde{\chi}(x^{i+1}, x^{i+1}) &= \Delta t \chi(u^{i+1}; \frac{u^{i+1} - u^i}{\Delta t}; \theta^{i+1}) \\
&= \Delta t \int_{\Gamma_C} \mu p_\nu(u_\nu^{i+1}) S_c(\cdot, \frac{1}{\Delta t} \|u_\tau^{i+1} - u_\tau^i\|) \theta^{i+1} da \\
&\leq \Delta t c_2 c_0 \bar{\mu} L_\nu S^* \|x^{i+1}\|_X^2.
\end{aligned} \tag{6.8}$$

and

$$\begin{aligned}
\Delta t \tilde{\omega}(x^{i+1}, x^{i+1}) &= \Delta t \omega((u^{i+1}, \theta^{i+1}), \theta^{i+1}) \\
&= \Delta t \int_{\Gamma_C} k_c(u_\nu^{i+1}) \phi_L(\theta^{i+1} - \theta_F) \theta^{i+1} da \\
&\leq \Delta t c_2 L M_{k_c} \|x^{i+1}\|_X.
\end{aligned} \tag{6.9}$$

and

$$\begin{aligned}
\tilde{\ell}(x^{i+1}, x^{i+1}) &= \ell((u^{i+1}, \varphi^{i+1}), \varphi^{i+1}) \\
&= \int_{\Gamma_C} k_c(u_\nu^{i+1} - g) \phi_L(\theta^{i+1} - \theta_F) \varphi^{i+1} da \\
&\leq M_{k_c} L (\text{mes}(\Gamma_C))^{\frac{1}{2}} c_1 \|x^{i+1}\|_X.
\end{aligned} \tag{6.10}$$

We combine (5.15), (5.19) and (6.6)-(6.10) to get

$$\begin{aligned}
(m - C) \|x^{i+1}\|_X^2 &\leq \|g^{i+1}\|_X \|x^{i+1}\|_X + M_{k_c} L (\text{mes}(\Gamma_C))^{\frac{1}{2}} c_1 \|x^{i+1}\|_X \\
&\quad + \Delta t c_2 L M_{k_c} \|x^{i+1}\|_X \\
&\quad + c_0^2(L_\nu + L_\tau) \|x^{i+1}\|_X^2 + \Delta t c_2 c_0 \bar{\mu} L_\nu S^* \|x^{i+1}\|_X^2 \\
&\quad + \sqrt{3} \max(1, M_{\mathcal{P}}, M_{\mathcal{M}}) \|x^i\|_X \|x^{i+1}\|_X
\end{aligned}$$

Hence

$$\begin{aligned} & [[(m - C) - c_0^2(L_\nu + L_\tau)] - \bar{\mu}\Delta t c_2 c_0 L_\nu S^*] \|x^{i+1}\|_X \\ & \leq \|g^{i+1}\|_X + [\sqrt{3} \max(1, M_{\mathcal{P}}, M_{\mathcal{M}}) + M_{k_c} L (\text{mes}(\Gamma_C))^{\frac{1}{2}} c_1 + \Delta t c_2 L M_{k_c}] \|x^i\|_X \end{aligned}$$

and then, the lemma 6.1 is established.

Lemma 6.2. *There exists $k_3 \geq 0$ such that*

$$\|\Delta x^i\|_X \leq k_3 \sum_{j=0}^i \|\Delta g^j\|_X \quad (6.11)$$

Proof. Taking (6.5) at time t_{i+1} and t_i , we find for all $y \in X$ that

$$\begin{aligned} & (Ax^{i+1}, y - x^{i+1})_X + (Bx^{i+1}, y - x^{i+1})_X + J(x^{i+1}, y - x^i) - J(x^{i+1}, x^{i+1} - x^i) \\ & \quad - \Delta t \tilde{\chi}(x^{i+1}, y - x^{i+1}) + \Delta t \tilde{\omega}(x^{i+1}, y - x^{i+1}) + \tilde{\ell}(x^{i+1}, y - x^{i+1}) \\ & \geq (g^{i+1}, y - x^{i+1})_X + (\theta^i, \eta - \theta^{i+1})_{L^2(\Omega)} + (\mathcal{M}\varepsilon(u^i), \eta - \theta^{i+1})_{L^2(\Omega)} \\ & \quad - (\mathcal{P}\nabla\varphi^i, \eta - \theta^{i+1})_{L^2(\Omega)}, \end{aligned} \quad (6.12)$$

and

$$\begin{aligned} & (Ax^i, y - x^i)_X + (Bx^i, y - x^i)_X + J(x^i, y - x^{i-1}) - J(x^i, x^i - x^{i-1}) \\ & \quad - \Delta t \tilde{\chi}(x^i, y - x^i) + \Delta t \tilde{\omega}(x^i, y - x^i) + \tilde{\ell}(x^i, y - x^i) \\ & \geq (g^i, y - x^i)_X + (\theta^{i-1}, \eta - \theta^i)_{L^2(\Omega)} + (\mathcal{M}\varepsilon(u^{i-1}), \eta - \theta^i)_{L^2(\Omega)} \\ & \quad - (\mathcal{P}\nabla\varphi^{i-1}, \eta - \theta^i)_{L^2(\Omega)}, \end{aligned} \quad (6.13)$$

We take $y = x^i$ in (6.12) and $y = x^{i+1}$ in (6.13) to get

$$\begin{aligned} & (Ax^{i+1} - Ax^i, x^{i+1} - x^i)_X + (Bx^{i+1} - Bx^i, x^{i+1} - x^i)_X \\ & \leq (g^{i+1} - g^i, x^{i+1} - x^i)_X + J(x^i, \Delta x^i + \Delta x^{i-1}) - J(x^i, \Delta x^{i-1}) - J(x^{i+1}, \Delta x^i) \\ & \quad + \Delta t \tilde{\chi}(x^{i+1}, \Delta x^i) - \Delta t \tilde{\chi}(x^i, \Delta x^i) + \Delta t \tilde{\omega}(x^{i+1}, \Delta x^i) - \Delta t \tilde{\omega}(x^i, \Delta x^i) \\ & \quad + \tilde{\ell}(x^{i+1}, \Delta x^i) - \tilde{\ell}(x^i, \Delta x^i) + (\Delta\theta^{i-1}, \Delta\theta^i)_{L^2(\Omega)} \\ & \quad + (\mathcal{M}\varepsilon(u^i) - \mathcal{M}\varepsilon(u^{i-1}), \Delta\theta^i)_{L^2(\Omega)} - (\mathcal{P}\nabla\varphi^i - \mathcal{P}\nabla\varphi^{i-1}, \Delta\theta^i)_{L^2(\Omega)}. \end{aligned} \quad (6.14)$$

Moreover, using the propriety of J and $\left| |u_\tau^{i+1} - u_\tau^{i-1}| - |u_\tau^i - u_\tau^{i-1}| \right| \leq |u_\tau^{i+1} - u_\tau^i|$ to deduce

$$\begin{aligned} J(x^i, \Delta x^i + \Delta x^{i-1}) - J(x^i, \Delta x^{i-1}) &= j(u^i, \Delta u^i + \Delta u^{i-1}) - j(u^i, \Delta u^{i-1}) \\ &\leq j(u^i, \Delta u^i) \\ &\leq J(x^i, \Delta x^i) \end{aligned}$$

and

$$\begin{aligned} J(x^i, \Delta x^i) - J(x^{i+1}, \Delta x^i) &= j((u^i, \Delta u^i) - j(u^{i+1}, \Delta u^i) \\ &= \int_{\Gamma_C} [p_\nu(u_\nu^i - g) - p_\nu(u_\nu^{i+1} - g)] \Delta u_\nu^i da \\ &\quad + \int_{\Gamma_C} [p_\tau(u_\tau^i - g) - p_\tau(u_\tau^{i+1} - g)] \|\Delta u_\tau^i\| da \quad (6.15) \\ &\leq c_0^2 (L_\nu + L_\tau) \|\Delta x^i\|_X^2. \end{aligned}$$

On another hand, we have

$$\begin{aligned} \tilde{\chi}(x^{i+1}, \Delta x^i) - \tilde{\chi}(x^i, \Delta x^i) &= \chi(u^{i+1}; \frac{u^{i+1} - u^i}{\Delta t}; \Delta \theta^i) - \chi(u^i; \frac{u^i - u^{i-1}}{\Delta t}; \Delta \theta^i) \\ &= \int_{\Gamma_C} [p_\tau(u^{i+1} - g) - p_\tau(u^i - g)] S_c(\cdot, \frac{1}{\Delta t} \|u_\tau^{i+1} - u_\tau^i\|) \Delta \theta^i da \\ &\quad + \int_{\Gamma_C} \mu p_\nu(u^i - g) [S_c(\cdot, \frac{1}{\Delta t} \|u_\tau^{i+1} - u_\tau^i\|) - S_c(\cdot, \frac{1}{\Delta t} \|u_\tau^i - u_\tau^{i-1}\|)] \Delta \theta^i da \\ &\leq c_2 S^* L_\tau c_0 \|\Delta x^i\|_X^2 \\ &\quad + \int_{\Gamma_C} \mu p_\nu(u^i - g) [S_c(\cdot, \frac{1}{\Delta t} \|\Delta u_\tau^i\|) - S_c(\cdot, \frac{1}{\Delta t} \|\Delta u_\tau^{i-1}\|)] \Delta \theta^i da \\ &\leq c_2 S^* L_\tau c_0 \|\Delta x^i\|_X^2 + \bar{\mu} L_{p_\nu} \frac{L_{s_c}}{\Delta t} \int_{\Gamma_C} \|u_\tau^{i+1} - u_\tau^{i-1}\| \Delta \theta^i da \\ &\leq c_2 S^* L_\tau c_0 \|\Delta x^i\|_X^2 + c_0 c_2 \bar{\mu} L_{p_\nu} \frac{L_{s_c}}{\Delta t} \|\Delta x^{i+1}\|_X^2 + c_0 c_2 \bar{\mu} L_{p_\nu} \frac{L_{s_c}}{\Delta t} \|\Delta x^i\|_X \|\Delta x^{i-1}\|_X. \end{aligned}$$

Hence

$$\begin{aligned} \Delta t \tilde{\chi}(x^{i+1}, \Delta x^i) - \Delta t \tilde{\chi}(x^i, \Delta x^i) &\leq \Delta t c_2 S^* L_\tau c_0 \|\Delta x^i\|_X^2 \\ &\quad + c_0 c_2 \bar{\mu} L_{p_\nu} L_{s_c} \|\Delta x^{i+1}\|_X^2 + c_0 c_2 \bar{\mu} L_{p_\nu} L_{s_c} \|\Delta x^i\|_X \|\Delta x^{i-1}\|_X. \quad (6.16) \end{aligned}$$

$$\begin{aligned} \tilde{\omega}(x^{i+1}, \Delta x^i) - \tilde{\omega}(x^i, \Delta x^i) &= \omega((u^{i+1}, \theta^{i+1}), \Delta \theta^i) - \omega((u^i, \theta^i), \Delta \theta^i) \\ &\leq (L_{k_c} L c_0 c_2 + M_{k_c} c_2^2) \|\Delta x^{i+1}\|_X^2, \quad (6.17) \end{aligned}$$

and

$$\begin{aligned} \tilde{\ell}(x^{i+1}, \Delta x^i) - \tilde{\ell}(x^i, \Delta x^i) &= \ell((u^{i+1}, \varphi^{i+1}), \Delta \varphi^i) - \ell((u^i, \varphi^i), \Delta \varphi^i) \\ &\leq (L_\psi L c_0 c_1 + M_{k_c} c_1^2) \|\Delta x^{i+1}\|_X^2. \end{aligned} \quad (6.18)$$

and by using (6.12)-(6.22), we obtain that there exists a positive constant L^* such that

$$\begin{aligned} (m - C) \|\Delta x^i\|_X^2 &\leq \|\Delta g^i\|_X \|\Delta x^i\|_X + L^*(\bar{\mu} + L_\tau + LL_{k_c} + LL_\psi + M_{k_c} + M_\psi) \|\Delta x^{i+1}\|_X^2 \\ &\quad + c_0^2 (L_\nu + L_\tau) \|\Delta x^{i+1}\|_X^2 + c_0 c_2 \bar{\mu} L_{p_\nu} L_{s_c} \|\Delta x^i\|_X \|\Delta x^{i-1}\|_X \\ &\quad + \sqrt{3} c_2 \max(1, M_{\mathcal{P}}, M_{\mathcal{M}}) \|\Delta x^i\|_X \|\Delta x^{i-1}\|_X. \end{aligned}$$

Thus

$$\begin{aligned} ((m - C) - c_0^2 (L_\nu + L_\tau) - L^*(\bar{\mu} + L_\tau + LL_{k_c} + LL_\psi + M_{k_c} + M_\psi)) \|\Delta x^i\|_X^2 \\ \leq \|\Delta g^i\|_X \|\Delta x^i\|_X + c_0 c_2 \bar{\mu} L_{p_\nu} L_{s_c} \|\Delta x^i\|_X \|\Delta x^{i-1}\|_X \\ + \sqrt{3} c_2 \max(1, M_{\mathcal{P}}, M_{\mathcal{M}}) \|\Delta x^i\|_X \|\Delta x^{i-1}\|_X. \end{aligned}$$

Finally, for $\bar{\mu} + L_\tau + LL_{k_c} + LL_\psi + M_{k_c} + M_\psi$ sufficiently small, the lemma 6.2 is proved. \square

Proposition 6.1. *From the sequences (u^n) , (φ^n) and (θ^n) , we can extract subsequences, still denoted (u^n) , (φ^n) and (θ^n) such that*

$$\begin{aligned} u^n &\rightarrow u \quad \text{weak * in } L^\infty(0, T; V), \\ \varphi^n &\rightarrow \varphi \quad \text{weak * in } L^\infty(0, T; W), \\ \theta^n &\rightarrow \theta \quad \text{weak * in } L^\infty(0, T; Q). \end{aligned} \quad (6.19)$$

and

$$\begin{aligned} \dot{u}^n &\rightarrow \dot{u} \quad \text{weak * in } L^\infty(0, T; V), \\ \dot{\varphi}^n &\rightarrow \dot{\varphi} \quad \text{weak * in } L^\infty(0, T; W), \\ \dot{\theta}^n &\rightarrow \dot{\theta} \quad \text{weak * in } L^\infty(0, T; Q). \end{aligned} \quad (6.20)$$

Proof. using (6.2) and the assumption (H_8) , we find that $g \in W^{1,\infty}(0, T; X)$. Then, we get

$$\|g^i\|_X \leq \|g\|_{L^\infty(0, T; X)}, \quad \left\| \frac{\Delta g^i}{\Delta t} \right\|_X \leq \|\dot{g}\|_{L^\infty(0, T; X)}. \quad (6.21)$$

Let $x^n = x^i + \frac{t - t_i}{\Delta t} \Delta x^i$, by lemmas 6.1 and 6.2 we find that there exists a constant $d > 0$ such that

$$\|x^n\|_{W^{1,\infty}(0, T; X)} \leq d. \quad (6.22)$$

Applying (5.8), we deduce that

$$\begin{aligned} \|u^n\|_{W^{1,\infty}(0,T;V)} &\leq d \\ \|\varphi^n\|_{W^{1,\infty}(0,T;W)} &\leq d \\ \|\theta^n\|_{W^{1,\infty}(0,T;Q)} &\leq d \end{aligned} \tag{6.23}$$

and then, the sequences (u^n) , (φ^n) and (θ^n) are uniformly bounded, respectively in $W^{1,\infty}(0, T; V)$, $W^{1,\infty}(0, T; W)$ and $W^{1,\infty}(0, T; Q)$. Hence, we can extract from it subsequences still denoted (u^n) , (φ^n) and (θ^n) such that (6.19) and (6.20) and thus the proposition 6.1 is proved. \square

Proposition 6.2. *There exists subsequences of (\bar{u}^n) , $(\bar{\varphi}^n)$ and $(\bar{\theta}^n)$, still denoted (\bar{u}^n) , $(\bar{\varphi}^n)$ and $(\bar{\theta}^n)$ such that for almost every $t \in [0, T]$ we have*

$$\begin{aligned} \bar{u}^n(t) &\rightarrow u(t) \quad \text{weak in } V \\ \bar{\varphi}^n(t) &\rightarrow \varphi(t) \quad \text{weak in } W \\ \bar{\theta}^n(t) &\rightarrow \theta(t) \quad \text{weak in } Q. \end{aligned} \tag{6.24}$$

Proof. It comes from (6.21) that (\bar{u}^n) is uniformly bounded in $L^\infty(0, T; V)$ and then (\bar{u}^n) converges weak * for subsequence in $L^\infty(0, T; V)$. Moreover, we have

$$\|u^n(t) - \bar{u}^n(t)\|_V \leq \frac{T}{n} \|\dot{u}^n(t)\|_V, \quad \forall t \in [0, T].$$

This inequality combined with (6.23) leads to

$$\|u^n(t) - \bar{u}^n(t)\|_{L^\infty(0,T;V)} \leq d \frac{T}{n}. \tag{6.25}$$

We thus deduce from (6.19) that

$$(\bar{u}^n) \rightarrow u \quad \text{weak * for subsequence in } L^\infty(0, T; V). \tag{6.26}$$

On another hand, (6.19), (6.20) and $W^{1,\infty}(0, T; V) \subset C(0, T; V)$ imply that

$$u^n(t) \rightarrow u(t) \quad \text{weak in } V \quad \text{for a.e } t \in [0, T]. \tag{6.27}$$

We conclude from (6.25)-(6.27) that for almost every $t \in [0, T]$, we have $\bar{u}^n(t) \rightarrow u(t)$ weak in V for a subsequence. Finally, by the same manner, the proof is finished. \square

Remark. *Let $\bar{f}^n(t) = f^{i+1}$, $\bar{q}_e^n(t) = q_e^{i+1}$ and $\bar{\Theta}^n(t) = \Theta^{i+1}$ for all $t \in [t_i, t_{i+1}]$. Under the assumption (H_8) , we have $f \in W^{1,\infty}(0, T; V)$, $q_e \in W^{1,\infty}(0, T; W)$ and $\Theta \in W^{1,\infty}(0, T; Q)$. Then*

$$\begin{aligned} \bar{f}^n &\rightarrow f \quad \text{strongly in } L^2(0, T; V) \\ \bar{q}_e^n &\rightarrow q_e \quad \text{strongly in } L^2(0, T; W) \\ \bar{\Theta}^n &\rightarrow \Theta \quad \text{strongly in } L^2(0, T; Q). \end{aligned} \tag{6.28}$$

Proposition 6.3. *The triple $(u, \varphi, \theta) \in L^2(0, T; V \times W \times Q)$ is solution of the problem (PV).*

Proof. If we substitute v by $u^i + v \Delta t$ in (5.1) and divide the resulting inequality by Δt and if we divide (5.1) by Δt , the problem (PV^i) will be written for all $v \in L^2(0, T; V)$, $\xi \in L^2(0, T; W)$ and $\eta \in L^2(0, T; Q)$ as follows

$$\begin{aligned}
& (\mathfrak{F} \varepsilon(\bar{u}^n(t)), \varepsilon(v(t)) - \varepsilon(\frac{d}{dt}u^n(t)))_{\mathcal{H}} + (\mathcal{E}^* \nabla \bar{\varphi}^n(t), \varepsilon(v(t)) - \varepsilon(\frac{d}{dt}u^n(t)))_H \\
& - (\mathcal{M} \bar{\theta}^n(t), \varepsilon(v(t)) - \varepsilon(\frac{d}{dt}u^n(t)))_H + j(\bar{u}^n(t), v(t)) - j(\bar{u}^n(t), \frac{d}{dt}u^n(t)) \\
& \geq (\bar{f}^n(t), v(t) - \frac{d}{dt}u^n(t))_V \\
& (\beta \nabla \bar{\varphi}^n(t), \nabla \xi(t))_H - (\mathcal{E} \varepsilon(\bar{u}^n(t)), \nabla \xi(t))_H - (\mathcal{P} \bar{\theta}^n(t), \nabla \xi(t))_H + l((\bar{u}^n(t), \bar{\varphi}^n(t)); \xi(t)) \\
& = (\bar{q}_e^n(t), \xi(t))_W \\
& (\frac{d}{dt}\bar{\theta}^n(t), \eta(t))_{L^2(\Omega)} + (\mathcal{K} \nabla \bar{\theta}^n(t), \nabla \eta(t))_H + (\mathcal{M} \varepsilon(\frac{d}{dt}u^n(t)), \eta(t))_{L^2(\Omega)} \\
& - (\mathcal{P} \nabla \frac{d}{dt}\varphi^n(t), \eta(t))_{L^2(\Omega)} - \chi(\bar{u}^n(t); \frac{d}{dt}u^n(t); \eta(t)) + \omega((\bar{u}^n(t), \bar{\theta}^n(t)), \eta(t)) \\
& = (\bar{\Theta}^n(t), \eta(t))_{L^2(\Omega)}
\end{aligned}$$

Integrating both sides of the previous inequalities on $[0, T]$, we find that

$$\begin{aligned}
& \int_0^T (\mathfrak{F} \varepsilon(\bar{u}^n(t)), \varepsilon(v(t)) - \varepsilon(\frac{d}{dt}u^n(t)))_{\mathcal{H}} dt + \int_0^T (\mathcal{E}^* \nabla \bar{\varphi}^n(t), \varepsilon(v(t)) - \varepsilon(\frac{d}{dt}u^n(t)))_H dt \\
& - \int_0^T (\mathcal{M} \bar{\theta}^n(t), \varepsilon(v(t)) - \varepsilon(\frac{d}{dt}u^n(t)))_H dt + \int_0^T j(\bar{u}^n(t), v(t)) dt - \int_0^T j(\bar{u}^n(t), \frac{d}{dt}u^n(t)) dt \\
& \geq \int_0^T (\bar{f}^n(t), v(t) - \frac{d}{dt}u^n(t))_V dt \\
& \int_0^T (\beta \nabla \bar{\varphi}^n(t), \nabla \xi(t))_H dt - \int_0^T (\mathcal{E} \varepsilon(\bar{u}^n(t)), \nabla \xi(t))_H dt - \int_0^T (\mathcal{P} \bar{\theta}^n(t), \nabla \xi(t))_H dt \\
& + \int_0^T l((\bar{u}^n(t), \bar{\varphi}^n(t)); \xi(t)) dt = \int_0^T (\bar{q}_e^n(t), \xi(t))_W dt \\
& \int_0^T (\frac{d}{dt}\bar{\theta}^n(t), \eta(t))_{L^2(\Omega)} dt + \int_0^T (\mathcal{K} \nabla \bar{\theta}^n(t), \nabla \eta(t))_H dt + \int_0^T (\mathcal{M} \varepsilon(\frac{d}{dt}u^n(t)), \eta(t))_{L^2(\Omega)} dt \\
& - \int_0^T (\mathcal{P} \nabla \frac{d}{dt}\varphi^n(t), \eta(t))_{L^2(\Omega)} dt - \int_0^T \chi(\bar{u}^n(t); \frac{d}{dt}u^n(t); \eta(t)) dt \\
& + \int_0^T \omega((\bar{u}^n(t), \bar{\theta}^n(t)), \eta(t)) dt = \int_0^T (\bar{\Theta}^n(t), \eta(t))_{L^2(\Omega)} dt
\end{aligned}$$

By adding the previous inequalities, we obtain

$$\begin{aligned}
& \int_0^T (\mathfrak{F} \varepsilon(\bar{u}^n(t)), \varepsilon(v(t)) - \varepsilon(\frac{d}{dt}u^n(t)))_{\mathcal{H}} dt + \int_0^T (\beta \nabla \bar{\varphi}^n(t), \nabla \xi(t))_H dt \\
& + \int_0^T (\mathcal{K} \nabla \bar{\theta}^n(t), \nabla \eta(t))_H dt + \int_0^T \omega((\bar{u}^n(t), \bar{\theta}^n(t)), \eta(t)) dt \\
& + \int_0^T (\frac{d}{dt}\theta^n(t), \eta(t))_{L^2(\Omega)} dt + \int_0^T (\mathcal{E}^* \nabla \bar{\varphi}^n(t), \varepsilon(v(t)) - \varepsilon(\frac{d}{dt}u^n(t)))_H dt \\
& - \int_0^T (\mathcal{E} \varepsilon(\bar{u}^n(t)), \nabla \xi(t))_H dt - \int_0^T (\mathcal{M} \bar{\theta}^n(t), \varepsilon(v(t)) - \varepsilon(\frac{d}{dt}u^n(t)))_H dt \quad (6.29) \\
& + \int_0^T (\mathcal{M} \varepsilon(\frac{d}{dt}u^n(t)), \eta(t))_{L^2(\Omega)} dt - \int_0^T (\mathcal{P} \bar{\theta}^n(t), \nabla \xi(t))_H dt \\
& - \int_0^T (\mathcal{P} \nabla \frac{d}{dt}\varphi^n(t), \eta(t))_{L^2(\Omega)} dt + \int_0^T j(\bar{u}^n(t), v(t)) - \int_0^T j(\bar{u}^n(t), \frac{d}{dt}u^n(t)) dt \\
& - \int_0^T \chi(\bar{u}^n(t); \frac{d}{dt}u^n(t); \eta(t)) dt + \int_0^T l((\bar{u}^n(t), \bar{\varphi}^n(t)); \xi(t)) dt \\
& \geq \int_0^T (\bar{f}^n(t), v(t) - \frac{d}{dt}u^n(t))_V + \int_0^T (\bar{q}_e^n(t), \xi)_W dt + \int_0^T (\bar{\Theta}^n(t), \eta(t))_{L^2(\Omega)} dt.
\end{aligned}$$

To finish the proof of the proposition 6.3, we use the following Lemmas

Lemma 6.3. *For any $v \in L^2(0, T; V)$, $\xi \in L^2(0, T; W)$ and $\eta \in L^2(0, T; Q)$, we have*

$$\lim_{n \rightarrow \infty} \int_0^T (\mathfrak{F} \varepsilon(\bar{u}^n(t)), \varepsilon(v(t)))_{\mathcal{H}} dt = \int_0^T (\mathfrak{F} \varepsilon(u(t)), \varepsilon(v(t)))_{\mathcal{H}} dt \quad (6.30)$$

$$\lim_{n \rightarrow \infty} \int_0^T (\mathcal{E}^* \nabla \bar{\varphi}^n(t), \varepsilon(v(t)) - \varepsilon(\dot{u}^n(t)))_H dt = \int_0^T (\mathcal{E}^* \nabla \varphi(t), \varepsilon(v(t)) - \varepsilon(\dot{u}(t)))_H dt \quad (6.31)$$

$$\lim_{n \rightarrow \infty} \int_0^T (\mathcal{M} \bar{\theta}^n(t), \varepsilon(v(t)) - \varepsilon(\dot{u}^n(t)))_H dt = \int_0^T (\mathcal{M} \theta(t), \varepsilon(v(t)) - \varepsilon(\dot{u}(t)))_H dt \quad (6.32)$$

$$\lim_{n \rightarrow \infty} \int_0^T (\beta \nabla \bar{\varphi}^n(t), \nabla \xi(t))_H dt = \int_0^T (\beta \nabla \varphi(t), \nabla \xi(t))_H dt \quad (6.33)$$

$$\lim_{n \rightarrow \infty} \int_0^T (\mathcal{E} \varepsilon(\bar{u}^n(t)), \nabla \xi(t))_H dt = \int_0^T (\mathcal{E} \varepsilon(u(t)), \nabla \xi(t))_H dt \quad (6.34)$$

and

$$\lim_{n \rightarrow \infty} \int_0^T (\mathcal{P} \bar{\theta}^n(t), \nabla \xi(t))_H dt = \int_0^T (\mathcal{P} \theta(t), \nabla \xi(t))_H dt \quad (6.35)$$

$$\lim_{n \rightarrow \infty} \int_0^T \left(\frac{d}{dt} \theta^n(t), \eta(t) \right)_{L^2(\Omega)} dt = \int_0^T (\dot{\theta}(t), \eta(t))_{L^2(\Omega)} dt \quad (6.36)$$

$$\lim_{n \rightarrow \infty} \int_0^T (\mathcal{K} \nabla \bar{\theta}^n(t), \nabla \eta(t))_H dt = \int_0^T (\mathcal{K} \nabla \theta(t), \nabla \eta(t))_H dt \quad (6.37)$$

$$\lim_{n \rightarrow \infty} \int_0^T (\mathcal{M} \varepsilon \left(\frac{d}{dt} u^n(t) \right), \eta(t))_{L^2(\Omega)} dt = \int_0^T (\mathcal{M} \varepsilon(\dot{u}(t)), \eta(t))_{L^2(\Omega)} dt \quad (6.38)$$

$$\lim_{n \rightarrow \infty} \int_0^T (\mathcal{P} \nabla \frac{d}{dt} \varphi^n(t), \eta(t))_{L^2(\Omega)} dt = \int_0^T (\mathcal{P} \nabla \dot{\varphi}(t), \eta(t))_{L^2(\Omega)} dt \quad (6.39)$$

$$\lim_{n \rightarrow \infty} \int_0^T \omega(\bar{u}^n(t), \bar{\theta}^n(t), \eta(t)) dt = \int_0^T \omega(u(t), \theta(t), \eta(t)) dt \quad (6.40)$$

$$\lim_{n \rightarrow \infty} \int_0^T j(\bar{u}^n(t), v(t)) dt = \int_0^T j(u(t), v(t)) dt, \quad (6.41)$$

$$\lim_{n \rightarrow \infty} \int_0^T l((\bar{u}^n(t), \bar{\varphi}^n(t)); \xi(t)) dt = \int_0^T l((u(t), \varphi(t)); \xi(t)) dt \quad (6.42)$$

$$\lim_{n \rightarrow \infty} \int_0^T (\bar{f}^n(t), v(t) - \frac{d}{dt} u^n(t))_V dt = \int_0^T (f(t), v(t) - \dot{u}(t))_V dt \quad (6.43)$$

$$\lim_{n \rightarrow \infty} \int_0^T (\bar{q}_e^n(t), \xi(t))_W dt = \int_0^T (q_e(t), \xi(t))_W dt \quad (6.44)$$

$$\lim_{n \rightarrow \infty} \int_0^T (\bar{\Theta}^n(t), \eta(t))_{L^2(\Omega)} dt = \int_0^T (\Theta(t), \eta(t))_{L^2(\Omega)} dt \quad (6.45)$$

Proof. It follows from (6.19) and (6.25) that,

$$\begin{aligned} \bar{u}^n &\rightharpoonup u && \text{weak in } L^2(0, T, V) \\ \bar{\varphi}^n &\rightharpoonup \varphi && \text{weak in } L^2(0, T, W) \\ \bar{\theta}^n &\rightharpoonup \theta && \text{weak in } L^2(0, T, Q) \end{aligned} \quad (6.46)$$

and the lemma 6.3 results from (6.46). \square

Lemma 6.4. For any $v \in L^2(0, T; V)$ and $\eta \in L^2(0, T; Q)$, we have

$$\liminf_{n \rightarrow \infty} \int_0^T (\mathfrak{F} \varepsilon(\bar{u}^n(t)), \varepsilon(\frac{d}{dt} u^n(t)))_{\mathcal{H}} dt \geq \int_0^T (\mathfrak{F} \varepsilon(u(t)), \varepsilon(\dot{u}(t)))_{\mathcal{H}} dt \quad (6.47)$$

$$\liminf_{n \rightarrow \infty} \int_0^T j(\bar{u}^n(t), \frac{d}{dt} u^n(t)) \geq \int_0^T j(u(t), \dot{u}(t)) dt \quad (6.48)$$

$$\liminf_{n \rightarrow \infty} \int_0^T \chi(\bar{u}^n(t); \frac{d}{dt} u^n(t); \eta(t)) dt \geq \int_0^T \chi(u(t); \dot{u}(t); \eta(t)) dt. \quad (6.49)$$

Proof. For the proof of (6.47), we refer to [7] and for (6.48), we write

$$j(\bar{u}^n(t), \frac{d}{dt}u^n(t)) = j(\bar{u}^n(t), \frac{d}{dt}u^n(t)) - j(u(t), \frac{d}{dt}u^n(t)) + j(u(t), \frac{d}{dt}u^n(t))$$

and

$$\begin{aligned} & \int_0^T j(\bar{u}^n(t), \frac{d}{dt}u^n(t)) - j(u(t), \frac{d}{dt}u^n(t)) dt \\ & \leq \bar{\mu} L_1 \|R(\sigma_\nu(\bar{u}^n) - \sigma_\nu(u))\|_{L^2(0,T;L^2(\Gamma_C))} \|\dot{u}_\tau^n\|_{L^2(0,T;L^2(\Gamma_C)^d)}. \end{aligned}$$

Keeping in mind that the mapping R is compact, we have $\lim_{n \rightarrow \infty} R(\sigma_\nu(\bar{u}^n) - \sigma_\nu(u)) = 0$.

Thus

$$\liminf_{n \rightarrow \infty} \int_0^T j(\bar{u}^n(t), \frac{d}{dt}u^n(t)) - j(u(t), \frac{d}{dt}u^n(t)) dt \leq 0$$

and then, we conclude that

$$\liminf_{n \rightarrow \infty} \int_0^T j(u(t), \frac{d}{dt}u^n(t)) dt \geq \int_0^T j(u(t), \dot{u}(t)) dt$$

In the same way, we can prove (6.49) and that finish the proof of lemma 6.4. \square

Now, we come back to the proof of proposition 6.3. By passing to the limit in (6.29), we obtain

$$\begin{aligned} & \int_0^T (\mathfrak{F} \varepsilon(u(t)), \varepsilon(v(t)) - \varepsilon(\dot{u}(t)))_{\mathcal{H}} dt + \int_0^T (\beta \nabla \varphi(t), \nabla \xi(t))_H dt \\ & + \int_0^T (\mathcal{K} \nabla \theta(t), \nabla \eta(t))_H dt + \int_0^T \omega((u(t), \theta(t)), \eta(t)) dt + \int_0^T (\dot{\theta}(t), \eta(t))_{L^2(\Omega)} dt \\ & + \int_0^T (\mathcal{E}^* \nabla \varphi(t), \varepsilon(v(t)) - \varepsilon(\dot{u}(t)))_{\mathcal{H}} dt - \int_0^T (\mathcal{E} \varepsilon(u(t)), \nabla \xi(t))_H dt \\ & - \int_0^T (\mathcal{M} \theta(t), \varepsilon(v(t)) - \varepsilon(\dot{u}(t)))_{\mathcal{H}} dt + \int_0^T (\mathcal{M} \varepsilon(\dot{u}(t)), \eta(t))_{L^2(\Omega)} dt \quad (6.50) \\ & - \int_0^T (\mathcal{P} \theta(t), \nabla \xi(t))_H dt - \int_0^T (\mathcal{P} \nabla \dot{\varphi}(t), \eta(t))_{L^2(\Omega)} dt \\ & + \int_0^T j(u(t), v(t)) dt - \int_0^T j(u(t), \dot{u}(t)) dt \\ & - \int_0^T \chi(u(t); \dot{u}(t); \eta(t)) dt + \int_0^T l((u(t), \varphi(t)); \xi(t)) dt \\ & \geq \int_0^T (f(t), v(t) - \dot{u}(t))_V dt + \int_0^T (q_e(t), \xi(t))_W dt + \int_0^T (\Theta(t), \eta(t))_{L^2(\Omega)} dt. \end{aligned}$$

By the same method as in the proof of lemma 5.1, we find that

$$\begin{aligned}
& \int_0^T (\mathfrak{F} \varepsilon(u(t)), \varepsilon(v(t)) - \varepsilon(\dot{u}(t)))_{\mathcal{H}} dt + \int_0^T (\mathcal{E}^* \nabla \varphi(t), \varepsilon(v(t)) - \varepsilon(\dot{u}(t)))_{\mathcal{H}} dt \\
& - \int_0^T (\mathcal{M} \theta(t), \varepsilon(v(t)) - \varepsilon(\dot{u}(t)))_{\mathcal{H}} dt + \int_0^T j(u(t), v(t)) dt \\
& - \int_0^T j(u(t), \dot{u}(t)) dt \geq \int_0^T (f(t), v(t) - \dot{u}(t))_V dt, \\
& \int_0^T (\beta \nabla \varphi(t), \nabla \xi(t))_H dt - \int_0^T (\mathcal{E} \varepsilon(u(t)), \nabla \xi(t))_H dt - \int_0^T (\mathcal{P} \theta(t), \nabla \xi(t))_H dt \\
& + \int_0^T l((u(t), \varphi(t)); \xi(t)) dt = \int_0^T (q_e(t), \xi(t))_W dt, \\
& \int_0^T (\dot{\theta}(t), \eta(t))_{L^2(\Omega)} dt + \int_0^T (\mathcal{K} \nabla \theta(t), \nabla \eta(t))_H dt \\
& + \int_0^T (\mathcal{M} \varepsilon(\dot{u}(t)), \eta(t))_{L^2(\Omega)} dt - \int_0^T (\mathcal{P} \nabla \dot{\varphi}(t), \eta(t))_{L^2(\Omega)} dt \\
& - \int_0^T \chi(u(t); \dot{u}(t); \eta(t)) dt + \int_0^T \omega((u(t), \theta(t)), \eta(t)) dt \\
& = \int_0^T (\Theta(t), \eta(t))_{L^2(\Omega)} dt.
\end{aligned}$$

Setting in this inequalities that

$$v(t) = \begin{cases} v & \text{for } t \in (s, s + \lambda) \\ \dot{u}(t) & \text{elsewhere.} \end{cases} \quad \text{and} \quad \xi(t) = \xi, \quad \eta(t) = \eta \quad \text{for } t \in (s, s + \lambda).$$

Then, we obtain

$$\begin{aligned}
& \frac{1}{\lambda} \int_s^{s+\lambda} (\mathfrak{F} \varepsilon(u(t)), \varepsilon(v) - \varepsilon(\dot{u}(t)))_{\mathcal{H}} dt + \frac{1}{\lambda} \int_s^{s+\lambda} (\mathcal{E}^* \nabla \varphi(t), \varepsilon(v) - \varepsilon(\dot{u}(t)))_{\mathcal{H}} dt \\
& - \frac{1}{\lambda} \int_s^{s+\lambda} (\mathcal{M} \theta(t), \varepsilon(v) - \varepsilon(\dot{u}(t)))_{\mathcal{H}} dt + \frac{1}{\lambda} \int_s^{s+\lambda} j(u(t), v) dt \\
& - \frac{1}{\lambda} \int_s^{s+\lambda} j(u(t), \dot{u}(t)) dt \\
& \geq \frac{1}{\lambda} \int_s^{s+\lambda} (f(t), v - \dot{u}(t))_V dt, \\
& \frac{1}{\lambda} \int_s^{s+\lambda} (\beta \nabla \varphi(t), \nabla \xi)_H dt - \frac{1}{\lambda} \int_s^{s+\lambda} (\mathcal{E} \varepsilon(u(t)), \nabla \xi)_H dt - \frac{1}{\lambda} \int_s^{s+\lambda} (\mathcal{P} \theta(t), \nabla \xi)_H dt \\
& + \int_s^{s+\lambda} l((u(t), \varphi(t)); \xi(t)) dt = \frac{1}{\lambda} \int_s^{s+\lambda} (q_e(t), \xi)_W dt
\end{aligned}$$

and

$$\begin{aligned}
& \frac{1}{\lambda} \int_s^{s+\lambda} (\dot{\theta}(t), \eta)_{L^2(\Omega)} dt + \frac{1}{\lambda} \int_s^{s+\lambda} (\mathcal{K} \nabla \theta(t), \nabla \eta)_H dt \\
& + \frac{1}{\lambda} \int_s^{s+\lambda} (\mathcal{M} \varepsilon(\dot{u}(t)), \eta)_{L^2(\Omega)} dt - \frac{1}{\lambda} \int_s^{s+\lambda} (\mathcal{P} \nabla \dot{\varphi}(t), \eta)_{L^2(\Omega)} dt \\
& - \frac{1}{\lambda} \int_s^{s+\lambda} \chi(u(t); \dot{u}(t); \eta(t)) dt + \frac{1}{\lambda} \int_s^{s+\lambda} \omega((u(t), \theta(t)), \eta(t)) dt \\
& = \frac{1}{\lambda} \int_s^{s+\lambda} (\Theta(t), \eta)_{L^2(\Omega)} dt.
\end{aligned}$$

Using lebesgue's theorem, we pass to the limit with respect to s in the above inequalities, we deduce that (u, φ, θ) satisfies the Problem (PV) and thus, the proposition 6.3 is proved.

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