A Review on Various Job Scheduling Algorithms

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Abstract
Complex computational environment exists where jobs cannot be processed by single processor. Multi cluster environment is one such environment in which computational intensive task exists. Job scheduling in multi cluster environment is critical factor. Users from various locations submit their jobs to multi clusters. This provides the challenge to schedule the resources among the jobs. An efficient job scheduling increases the performance of considered environment. The proposed work deals with the study of various techniques used for job scheduling in multi cluster environment. The comparative survey of techniques is presented so that optimal technique can be selected for future research.

Keywords: Computational Environment; Multi Cluster; Job Scheduling; Resource

I. INTRODUCTION
Scheduling in multi cluster environment is critical area of research. Legion of scheduling algorithms are playing a part to schedule resources in multi cluster environment. Job can arrive from geographical large area and this present a challenge
that which job must be given a resource at first place. In multi cluster environment Computer, data, and other resources are shared [1]. The service provider and consumers must agree upon what to be shared within given environment. The global nature of resource sharing is unique facility provided within multi cluster environment. The resource may be present within different administrative domain and demanded by node belonging to some other domain[2]. Scheduling henceforth becomes important for optimal and deadlock free system.

Scheduling is the process of assigning resources to jobs based on objective functions defined. Type of scheduling depends upon the objective function associated with the resource. Scheduling resources has following phases associated with it.

- Resource Discovery
- Resource Filtering
- Resource Selection
- Resource Scheduling Policy

Before allocation within multi cluster environment, resources must be discovered. Resource may or may not be available [1]. Hence this phase becomes critical for monitoring of resource within the system [3]. The available resources must be checked to determine whether they satisfy the requirements or not. Hence filtering is compulsory. Resource selection out of available resources is next phase. This phase is critical since out of available resources of same type resource with optimal condition is selected for allocation. This is required so that job can be completed well within time. Healthier resource selection is the target of this phase. Scheduling policy decides the resource allocation is primitive or not. Resource allocation is said to be primitive if once allocation resource can be prompted from job even if it is not yet fully completed.

It is possible that multiple objective functions are associated with the resource. Multi heuristic job scheduling algorithms are followed in such situations. Proposed work deals with the study of various algorithms used for scheduling resources among jobs. Rest of the paper is organized as follows: Section II provides details of various algorithms used for job allocation. Section III provides comparison of various techniques used for scheduling, section IV provides conclusion and future scope whereas section V provides references used within the proposed work.

II. JOB SCHEDULING ALGORITHMS

The critical part of parallel system is mechanism of distributing jobs within the parallel systems. Legions of algorithms utilized for this purpose. The algorithms which take part in the parallel system are described in this section.
A. **BAT ALGORITHM**

It is a meta heuristic algorithm used to optimally allocate resources to tasks. It is based on echolocation behaviour of BATS in terms of varying pulse rate of emission and loudness. BAT algorithm has the advantage of simplicity and flexibility. Because of simplicity and flexibility BAT algorithm can be used to solve wide range of problems[4].

B. **CUCKOO ALGORITHM**

This algorithm is also meta heuristic in nature. Cuckoo algorithm starts with the initial population. The cuckoo lays its eggs and then competition to survive begun. Cuckoo lays its eggs in nest of other birds. Hence cuckoo has to preserve eggs from
the birds whose nest it uses. The process continues and at the end cuckoo with same profit values survive and algorithm converges[5].

C. ANT COLONY OPTIMIZATION
This algorithm is considered one of the best algorithms in order to schedule the resources and allocate jobs to the processors. The characteristics of ants are followed in this case. The ants communicate with each other and let the information spread to detect optimal path. The base of parallel ant colony is implemented using parallel construction phase. In parallel ant colony algorithm multiple colonies are built simultaneously. The output of all the colonies is compared with each other. The output generated by colonies is checked for optimality. [7]

The only problem with the ACO is the convergence of ant colony algorithm is slow. The distance covered using this algorithm is less. In order to resolve the problem honey bee algorithm can be utilized.

D. HONEY BEE ALGORITHM
This algorithm utilizes better features of Ant Colonies algorithm along with high distance capabilities. The Honey bee algorithm utilizes optimal path finding along with distance coverage. It utilizes the foraging system associated with honey bees to find the path out of available alternatives. This algorithm converges much faster as compared to existing ant colony algorithm.[8]

E. GANG SCHEDULING
This scheduling produces optimal result as compared to all other parallel scheduling algorithms. This algorithm is primitive in nature. Hence deadlock never occurs within the system. The tasks that form a job are grouped together and then scheduled in this approach. The job priority is also considered in this case. The job with highest priority is executed at first place in this case. In the early system this approach produces optimal results. But nowadays more advanced algorithms exists which produces better result as compared to this algorithm. [9]

F. GENETIC ALGORITHM FOR PARALLEL SCHEDULING
The genetic algorithm has phases associated with it. The algorithm continues until optimal result is obtained. The phases associated with genetic algorithms are initialization, mutation crossover etc. The genetic algorithm goes through the generations and in case of complex problems consumes large amount of time. So for smaller problems genetic algorithm is not preferred. The genetic algorithm terminates when solution reaches satisfactory level. The prescribed tolerance hence plays critical part in terminating genetic algorithm. [10]–[12]
The approach using ant colony and honey bee algorithm can be used in order to enhance job scheduling performance. The ant colony algorithm utilizes to select path which is optimal in nature. The ant colony algorithm however is distance dependent. In order to resolve the problem honey bee algorithm is utilized. Honey bee may not always give optimal path but speed is enhanced considerable. The honey bee algorithm is not distance dependent. Parallel ant colony algorithm is need of the hour in which multiple process can be executed at the same time [7], [8], [13].

G. FIFO JOB SCHEDULING

In this job scheduling algorithm job is distributed to the processor within the system on the first come first serve basis. This algorithm may or may not yield optimal solutions. [6] The allocated processor release the job when the job burst time finishes. This algorithm is strictly non primitive in nature. It is hence rarely utilized in the parallel environment.

H. TIME SHARING

In this scheduling time is shared among multiple jobs. The time sharing system utilizes time quantum. The processor is switched among the processors based on time quantum. The process continues until all the jobs finish execution. The time sharing system involves states such as waiting, active and ready. The time scheduling on parallel system can be implemented using local scheduling. The processing node has processors associated with them. Threads ready to be executed are placed within first come first serve buffer.[7] When the processor is available thread is fetched from the queue and executed. The time sharing environment generally adopt pipeline concept for executing instructions concurrently within uniprocessor systems.

Combination of BAT and CUCKOO algorithm hybridization can be used in future end ever since it is not yet demonstrated and can become hot topic of research in future.

III. PERFORMANCE COMPARISON

The analysis of various algorithm distinguished on the basis of performance is highlighted in this section. The genetic algorithm comes into existence as a need to resolve multi objective problems. The problem with genetic algorithm is its poor convergence rate. The hybrid approach is used along with many distinguish algorithms to resolve the problems of genetic approach. Comparison of performance is given in terms of convergence rate. Convergence rate of single objective algorithm is better as compared to meta heuristic algorithm. The algorithms and their description given in the section II is concluded in this section. Also type of algorithm is given through performance table in this section.
The performance comparison of multi heuristic and single objective approach is presented in this section. The performance comparison gives best possible algorithms to be used in the future endeavours.

Table 1: Comparison of Convergence of various algorithms

<table>
<thead>
<tr>
<th>ALGORITHM</th>
<th>Convergence</th>
<th>Problem Solving</th>
</tr>
</thead>
<tbody>
<tr>
<td>Genetic algorithm</td>
<td>Depends upon the problems in which it is utilized</td>
<td>Meta Heuristic</td>
</tr>
<tr>
<td>ACO</td>
<td>Good for distance less then 14km</td>
<td>Meta Heuristic</td>
</tr>
<tr>
<td>Honey Bee</td>
<td>Good for longer Distances</td>
<td>Meta Heuristic</td>
</tr>
<tr>
<td>BAT</td>
<td>Good for job allocation</td>
<td>Meta Heuristic</td>
</tr>
<tr>
<td>Cuckoo</td>
<td>Good for resource Searching</td>
<td>Meta Heuristic</td>
</tr>
<tr>
<td>FIFO</td>
<td>Optimality is not guaranteed</td>
<td>Single Objective</td>
</tr>
<tr>
<td>Time Sharing</td>
<td>Good for Parallel Job Execution</td>
<td>Single Objective</td>
</tr>
</tbody>
</table>

IV. COMPARISON OF VARIOUS JOB SCHEDULING ALGORITHM

This section provides the comparison of various algorithms to evaluate their performance so that optimal algorithm can be selected for future job allocation process.

Table 2: Comparison of various Job Scheduling Algorithms

<table>
<thead>
<tr>
<th>S.NO</th>
<th>TECHNIQUE</th>
<th>PARAMETERS OF SCHEDULING</th>
<th>FACTS DISCOVERED</th>
<th>METHODOLOGY</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>FIRST COME FIRST SERVE[2]</td>
<td>TIME OF SUBMISSION, PROCESSING TIME, FINISH TIME</td>
<td>UTILIZATION OF RESOURCES IS LOW</td>
<td>MATLAB, NS2, CTC SP2</td>
</tr>
<tr>
<td>2</td>
<td>BACKFILLING ALGORITHM[14]</td>
<td>JOB BURST TIME</td>
<td>SHORTEST JOB MOVE AHEAD OF OTHER JOBS</td>
<td>SIMULATION IS EVENT BASED</td>
</tr>
<tr>
<td>3</td>
<td>CONSERVATIVE BACKFILLING ALGORITHM[15]</td>
<td>ARRIVAL TIME, PROCESSING TIME, FINISH TIME</td>
<td>RESOURCE UTILIZATION IS IMPROVED</td>
<td>SIMULATION IS EVENT BASED</td>
</tr>
<tr>
<td>4</td>
<td>GANG SCHEDULING[9], [16]</td>
<td>AVERAGE TIME INTERVALS ARE CONSIDERED</td>
<td>IMPROVED AVERAGE WAITING AND TURNAROUND TIME</td>
<td>SIMULATION IS DISCRETE IN NATURE</td>
</tr>
</tbody>
</table>
V. CONCLUSION AND FUTURE SCOPE

Job allocation and scheduling in multi cluster environment is critical. This allocation and scheduling must be performed carefully so that Makespan and Flowtime can be reduced. Waiting time associated with the task must also be reduced. This is possible only if correct algorithm can be selected for the job. Hybrid approach by combining various optimal algorithms can be used to optimize scheduling.

In the future BAT and Cuckoo algorithm can be combined together to generate optimal solution.

REFERENCES


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