

Common fixed point theorems of bivariate and self maps in d –metric spaces

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Abstract

In this paper, weakly compatible and occasionally weakly compatible mappings are discussed in detail and generalize common fixed point theorems of bivariate and self maps, $T : X \times X \rightarrow X$ and $S : X \rightarrow X$ are proved in Dislocated metric space with E.A property. Our results extends and generalists many well known results.

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1. Introduction

In the last two decades many fixed point theorems for contractions in dislocated metric spaces appeared (see [3]–[18]). Hitzler and Seda introduced the concept of dislocated metric space and studied the dislocated topologies which is a generalization of the conventional topologies and can be thought of as underlying the notion of dislocated metrics. They also proved a generalized version of Banach contraction mapping theorem which was applied to obtain fixed point semantics for logic programs. In this paper we have discussed the dislocated topologies associated with a Dislocated metric space and also proved a common fixed point theorem of bivariate and self maps with E. A property which extends and generalizes the well known Banach contraction principle and known results.

2. Preliminaries

Definition 1. Let X be a nonempty set, let $d : X \times X \rightarrow [0, \infty)$ be a function satisfying following conditions.

- (i) $d(x, y) = d(y, x) = 0$ implies $x = y$,
- (ii) $d(x, y) \leq d(x, z) + d(z, y)$ for all $x, y, z \in X$.
- (iii) $d(x, y) = d(y, x)$ for all $x, y \in X$.

Then d is called a dislocated metric spaces or d-metric on X .

Definition 2. [3] A sequence $\{x_n\}$ in dislocated metric spaces (X, d) is said to be a Cauchy sequence if for given $\epsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that $\forall m, n \geq n_0$, implies $d(x_m, x_n) < \epsilon$.

Definition 3. [3] A sequence $\{x_n\}$ in dislocated metric spaces (X, d) is said to be a Convergent to x if $\lim_{n \rightarrow \infty} d(x_n, x) = 0$.

In this case, x is called limit of $\{x_n\}$ and we write $x_n \rightarrow x$.

Definition 4. [3] A dislocated metric spaces (X, d) is said to be a Complete if every cauchy sequence is convergent in X .

Definition 5. Let T and S be self maps of a set X . Maps T and S are said to be commuting if $STx = T Sx$ for all $x \in X$.

Definition 6. Let T and S be self maps of a set X . If $w = Tx = Sx$ for some $x \in X$, then x is called a coincidence point of T and S , and w is called a point of coincidence of T and S .

Example 7. Take $X = [0, 1]$, $Sx = x^2$, $Tx = \frac{x}{2}$. It is clear that $\{0, \frac{1}{2}\}$ is the set of coincidence points of S and T and 0 is the unique common fixed point.

Definition 8. The mappings S and T are said to be weakly compatible if and only if they commute at their coincidence points.

Definition 9. The mappings S and T are said to be occasionally weakly compatible if and only if they commute at some coincidence point of S and T , i.e. $STu = T Su$ for some coincidence point u .

Lemma 10. [6] If a weakly compatible pair (S, T) of self maps has a unique point of coincidence, then the point of coincidence is a unique common fixed point of S and T .

Example 11. Take $X = [0, 1]$, $Sx = x^2$, $Tx = \frac{x}{2}$. It is clear that $\{0, \frac{1}{2}\}$ is the set of coincidence points of S and T , $ST0 = T S0$ but $ST\frac{1}{2} \neq T S\frac{1}{2}$ and so S and T are

occasionally weakly compatible but not weakly compatible.

Lemma 12. [6] Let S and T be occasionally weakly compatible mappings of X . If S and T have a unique point of coincidence then S and T are weakly compatible.

Definition 13. Let (X, d) be a dislocated metric Space (or d -metric Space), $T : X \times X \rightarrow X$ and $S : X \rightarrow X$ be mappings. A point $z \in X$ is said to be a coincidence point of S and T if $T(z, z) = Sz$. z is said to be a common fixed point of S and T if $T(z, z) = Sz = z$.

3. Main results

Consider a function $\phi : [0, 1]^2 \rightarrow [0, 1]$ such that

- (a) ϕ is an increasing function, i.e $x_1 \leq y_1, x_2 \leq y_2$ implies $\phi(x_1, x_2) \leq \phi(y_1, y_2)$.
- (b) $\phi(t, t) \leq t$, for all $t \in [0, 1]$
- (c) ϕ is continuous in both variables.

Theorem 1. Let (X, d) be a dislocated metric space. Let $S : X \rightarrow X$ and $T : X \times X \rightarrow X$ be mappings Such that $T(X \times X) \subseteq S(X)$, $S(X)$ is complete and $d(T(x_1, x_2), T(x_2, x_3)) \leq \alpha \phi[d(Sx_1, Sx_2), d(Sx_2, Sx_3)]$ where x_1, x_2, x_3 are arbitrary elements in X , $0 < \alpha < \frac{1}{2}$. Then T and S have a coincidence point in X .

Proof. Let x_1, x_2 be arbitrary points in X , and a sequence $\{y_n\} \in X$ such that

$$y_{n+2} = Sx_{n+2} = T(x_n, x_{n+1})$$

for $n = 0, 1, \dots$

$$\text{Let } d_n = d(y_n, y_{n+1})$$

$$\begin{aligned} d_n &= d(Sx_n, Sx_{n+1}) \\ &= d(T(x_{n-1}, x_{n-2}), T(x_n, x_{n-1})) \\ &\leq \alpha \phi[d(Sx_{n-2}, Sx_{n-1}), d(Sx_{n-1}, Sx_n)] \\ &= \alpha \phi[d(y_{n-2}, y_{n-1}), d(y_{n-1}, y_n)] \end{aligned}$$

By the method of mathematical induction we will prove that,

$$d_n \leq \left(\frac{L - \delta^n}{L + \delta^n} \right)^2 \tag{1}$$

where

$$\delta = \frac{1}{\alpha},$$

$$L = \min \left\{ \frac{\delta(1 + \sqrt{d_1})}{1 - \sqrt{d_1}}, \frac{\delta^2(1 + \sqrt{d_2})}{1 - \sqrt{d_2}} \right\}.$$

It is clear that (1) is true for $n = 1, 2$. there fore

$$d_{n+1} \leq \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2$$

be the induction hypothesis. Then we have

$$\begin{aligned} d_{n+2} &= d(y_{n+2}, y_{n+3}) \\ &= d(T(x_{n+1}, x_n), T(x_{n+2}, x_{n+1})) \\ &\leq \alpha \phi[d(Sx_n, Sx_{n+1}), d(Sx_{n+1}, Sx_{n+2})] \\ &\leq \phi[d_n, d_{n+1}] \\ &\leq \phi \left\{ \left(\frac{L - \delta^n}{L + \delta^n} \right)^2, \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2 \right\} \\ &\leq \phi \left\{ \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2, \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2 \right\} \\ &\leq \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2 \leq \left(\frac{L - \delta^{n+2}}{L + \delta^{n+2}} \right)^2. \end{aligned}$$

Now, for $p \in N$ it follows

$$\begin{aligned} d(y_n, y_{n+p}) &\leq d(y_n, y_{n+1}) + d(y_{n+1}, y_{n+2}) + \cdots + d(y_{n+p-1}, y_{n+p}) \\ &\leq \left(\frac{L - \delta^n}{L + \delta^n} \right)^2 + \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2 + \cdots + \left(\frac{L - \delta^{n+p-1}}{L + \delta^{n+p-1}} \right)^2. \end{aligned}$$

$\therefore d(y_n, y_{n+p}) \rightarrow 0$ as $n \rightarrow \infty$. Hence $\{y_n\}$ is a Cauchy sequence in $S(X)$, and since $S(X)$ is complete, there exist $z \in S(X)$ such that $\lim_{n \rightarrow \infty} y_n = z$. Let $z = Su$ for some $u \in X$. Then we have

$$\begin{aligned} d(T(u, u), Su) &= \lim_{n \rightarrow \infty} d(T(u, u), y_{n+2}) \\ &= \lim_{n \rightarrow \infty} d(T(u, u), T(x_n, x_{n+1})) \\ &\leq \lim_{n \rightarrow \infty} [d(T(u, u), T(u, x_n)) + d(T(u, x_n), T(x_n, x_{n+1}))] \\ &\leq \lim_{n \rightarrow \infty} \alpha[\phi(d(Su, Su), d(Su, Sx_n)) + \phi(d(Su, Sx_n), d(Sx_n, Sx_{n+1}))] \\ &\rightarrow 0 \end{aligned}$$

Similarly it can be shown that $d(T(u, u), Su) \rightarrow 0$. Hence z is the coincidence point of T and S . ■

Theorem 2. Let (X, d) be a dislocated metric space. Let $S : X \rightarrow X$ and $T : X \times X \rightarrow X$ be mappings such that $T(X \times X) \subseteq S(X)$, $S(X)$ is complete and $d(T(x_1, x_2), T(x_3, x_1)) \leq \alpha \phi[d(Sx_1, Sx_3), d(Sx_2, Sx_1)]$ where x_1, x_2, x_3 are arbitrary elements in X , $0 < \alpha < \frac{1}{2}$. Then T and S have a coincidence point in X .

Proof. Let x_1, x_2 be arbitrary points in X , and a sequence $\{y_n\} \in X$ such that $y_{n+2} = Sx_{n+2} = T(x_n, x_{n+1})$ for $n = 0, 1, \dots$

Let $d_n = d(y_{n+1}, y_n)$. As proceed in above theorem. By the method of mathematical induction we will prove that,

$$d_n \leq \left(\frac{L - \delta^n}{L + \delta^n} \right)^2 \tag{1}$$

where

$$\delta = \frac{1}{\alpha},$$

$$L = \min \left\{ \frac{\delta(1 + \sqrt{d_1})}{1 - \sqrt{d_1}}, \frac{\delta^2(1 + \sqrt{d_2})}{1 - \sqrt{d_2}} \right\}.$$

It is clear that (1) is true for $n = 1, 2$. there fore

$$d_{n+1} \leq \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2$$

be the induction hypothesis. Then we have

$$\begin{aligned} d_{n+2} &= d(y_{n+3}, y_{n+2}) \\ &= d(T(x_{n+1}, x_{n+2}), T(x_n, x_{n+1})) \\ &\leq \alpha \phi[d(Sx_{n+1}, Sx_n), d(Sx_{n+2}, Sx_{n+1})] \\ &\leq \phi[d_n, d_{n+1}] \\ &\leq \phi \left\{ \left(\frac{L - \delta^n}{L + \delta^n} \right)^2, \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2 \right\} \\ &\leq \phi \left\{ \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2, \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2 \right\} \\ &\leq \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2 \leq \left(\frac{L - \delta^{n+2}}{L + \delta^{n+2}} \right)^2. \end{aligned}$$

Now, for $p \in \mathbb{N}$ it follows

$$\begin{aligned} d(y_{n+p}, y_n) &\leq d(y_{n+p}, y_{n+p-1}) + d(y_{n+p-1}, y_{n+p-2}) + \dots + d(y_{n+1}, y_n) \\ &\leq \left(\frac{L - \delta^{n+p-1}}{L + \delta^{n+p-1}} \right)^2 + \left(\frac{L - \delta^{n+p-2}}{L + \delta^{n+p-2}} \right)^2 + \dots + \left(\frac{L - \delta^{n+1}}{L + \delta^{n+1}} \right)^2. \end{aligned}$$

$\therefore d(y_{n+p}, y_n) \rightarrow 0$ as $n \rightarrow \infty$. Hence $\{y_n\}$ is a Cauchy sequence in $S(X)$, and since $S(X)$ is complete, there exist $z \in S(X)$ such that $\lim_{n \rightarrow \infty} y_n = z$. Let $z = Su$ for some $u \in X$. Then we have

$$\begin{aligned} d(T(u, u), Su) &= \lim_{n \rightarrow \infty} d(T(u, u), y_{n+2}) \\ &= \lim_{n \rightarrow \infty} d(T(u, u), T(x_n, x_{n+1})) \\ &\leq \lim_{n \rightarrow \infty} [d(T(u, u), T(u, x_{n+1})) + d(T(u, x_{n+1}), T(x_n, x_{n+1}))] \\ &\leq \lim_{n \rightarrow \infty} \alpha[\phi(d(Su, Sx_{n+1}), d(Su, Su)) + \phi(d(Sx_n, Sx_{n+1}), d(Su, Sx_{n+1}))] \rightarrow 0 \end{aligned}$$

Similarly it can be shown that $d(T(u, u), Su) \rightarrow 0$. Hence z is the coincidence point of T and S . \blacksquare

Theorem 3. Let (X, d) be a dislocated metric space. Let $S : X \rightarrow X$ and $T : X \times X \rightarrow X$ be mappings such that $T(X \times X) \subseteq S(X)$, $S(X)$ is complete and

$$d(T(x_1, x_2), T(x_3, x_1)) \leq \alpha\phi[d(Sx_1, Sx_3), d(Sx_2, Sx_1)]$$

where x_1, x_2, x_3 are arbitrary elements in X , $0 < \alpha < \frac{1}{2}$. Then the sequence $\{y_n\} \in X$ defined by $y_{n+2} = Sx_{n+2} = T(x_n, x_{n+1})$, $n = 0, 1, \dots$ converges to a unique common fixed point in X .

Proof. Proceeding as same as in the proof of above Theorem [3.2], we see that sequence $\{y_n\}$ converges to z which is a point of coincidence of S and T . And suppose there exists $z' \in X$ such that $S(u') = T(u', u') = z'$ for some coincidence point u' .

$$\begin{aligned} d(z, z') &= d(T(u, u), T(u', u')) \\ &\leq d(T(u, u), T(u, u')) + d(T(u, u'), T(u', u')) \\ &\leq \alpha[\phi(d(Su, Su), d(Su, Su')) + \phi(d(Su, Su'), d(Su', Su'))] \\ &\leq 2\alpha[\phi(d(Su, Su'), d(Su, Su')) + \phi(d(Su, Su'), d(Su, Su'))] \\ &\leq 2\alpha[d(Su, Su') + d(Su, Su')] \\ &= 2^2\alpha d(Su, Su') \\ &= 2^2\alpha d(T(u, u), T(u', u')) \\ &\leq 2^2\alpha[d(T(u, u), T(u, u')) + d(T(u, u'), T(u', u'))] \\ &\leq 2^2\alpha^2[\phi(d(Su, Su), d(Su, Su')) + \phi(d(Su, Su'), d(Su', Su'))] \\ &\leq 2^3\alpha^2[\phi(d(Su, Su'), d(Su, Su')) + \phi(d(Su, Su'), d(Su, Su'))] \\ &\leq 2^4\alpha^2 d(Su, Su') \end{aligned}$$

Repeating the above process n times we get

$$d(z, z') \leq 2^{n+1}\alpha^{n-1}d(Su, Su')$$

Taking the limit as $n \rightarrow \infty$ we get $d(z, z') \rightarrow 0$, and so $z = z'$, i.e. z is the unique point of coincidence of S and T . Hence by above lemmas, z is a unique common fixed point of S and T . ■

Definition 4. An element $(x, y) \in X \times X$, is called a coupled fixed point of mapping $S : X \times X \rightarrow X$ if $S(x, y) = x$ and $S(y, x) = y$.

Definition 5. An element $(x, y) \in X \times X$, is called a coupled coincident point of mapping $S : X \times X \rightarrow X$ and $T : X \rightarrow X$ if $S(x, y) = T(x)$ and $S(y, x) = T(y)$.

Definition 6. The mappings S and T where $S : X \times X \rightarrow X$ and $T : X \rightarrow X$, are said to be compatible if

$$\lim_{n \rightarrow \infty} d(T(S(x_n, y_n)), S(T(x_n), T(y_n))) = 0$$

and $\lim_{n \rightarrow \infty} d(T(S(y_n, x_n)), S(T(y_n), T(x_n))) = 0$. whenever $\{x_n\}$ and $\{y_n\}$ are sequences in X , such that

$$\lim_{n \rightarrow \infty} S(x_n, y_n) = T(x_n) = x$$

and $\lim_{n \rightarrow \infty} S(y_n, x_n) = T(y_n) = y$, for all $x, y \in X$ are satisfied.

Definition 7. The bivariate self mapping, i.e., $S : X \times X \rightarrow X$ and self mapping $T : X \rightarrow X$ of a dislocated metric space (X, d) are said to be weakly compatible if they commute at there coincidence points, that is, if for all $x, y \in X$

$$S(x, y) = T(x) \text{ for some } x \in X, \text{ then } S(T(x), T(y)) = T(S(x, y)).$$

and

$$S(y, x) = T(y) \text{ for some } y \in X, \text{ then } S(T(y), T(x)) = T(S(y, x)).$$

Definition 8. The mappings S and T where $S : X \times X \rightarrow X$ and $T : X \rightarrow X$, of an dislocated metric space (X, d) satisfy E.A. property, if there exist sequences $\{x_n\}$ and $\{y_n\}$ in X , such that

$$S(x_n, y_n) = T(x_n) = T(u)$$

and $S(y_n, x_n) = T(y_n) = T(v)$ for $u, v \in X$.

Theorem 9. Let (X, d) be a dislocated metric space. Let $S : X \rightarrow X$ and $T : X \times X \rightarrow X$ be weakly compatible mappings of X Such that, for some $x, y, u, v \in X$,

$$d(S(x, y), S(u, v)) \leq \min\{d(T(x), T(u)), d(S(x, y), T(u)), d(S(u, v), T(u)), d(S(y, x), T(v)), d(S(x, y), T(u))\}.$$

If S and T satisfy E. A. property and T is a closed subspace of X , then S and T have a unique common fixed point.

Proof. Since S and T satisfy E. A. property, therefore, we can find sequences $\{x_n\}$ and $\{y_n\}$ in X and the point $u, v \in X$ such that

$$\lim_{n \rightarrow \infty} S(x_n, y_n) = \lim_{n \rightarrow \infty} T(x_n) = T(u)$$

and

$$\lim_{n \rightarrow \infty} S(y_n, x_n) = \lim_{n \rightarrow \infty} T(y_n) = T(v).$$

Then,

$$d(S(x_n, y_n), S(u, v)) \leq \min\{d(T(x_n), T(u)), d(S(x_n, y_n), T(u)), d(S(u, v), T(u)), d(S(y_n, x_n), T(v)), d(S(x_n, y_n), T(u))\}$$

Taking the limit as n tends to infinity in the above inequality,

$$\begin{aligned} d(T(u), S(u, v)) &\leq \min\{d(T(u), T(u)), d(T(u), T(u)), d(S(u, v), T(u)), \\ &\quad d(T(v), T(v)), d(T(u), T(u))\} \\ &\leq \min\{0, 0, d(S(u, v), T(u)), 0, 0\} \\ &\leq d(S(u, v), T(u)) \end{aligned}$$

Now, if $S(u, v) \neq T(u)$, then $d(S(u, v), T(u)) > d(S(u, v), T(u))$, contradicting the above inequality. This proves that $d(T(u), S(u, v)) = 0$, which implies $S(u, v) = T(u)$. Similarly, it can be proved that $S(v, u) = T(v)$. By denoting $S(u, v) = T(u) = z_1$ and $S(v, u) = T(v) = z_2$, Since S and T are weakly compatible then one obtain that $S(z_1, z_2) = Tz_1$ and $S(z_2, z_1) = Tz_2$. Let us prove that $z_1 = F(z_1, z_2)$.

Indeed, we obtain by (1)

$$\begin{aligned} d(S(z_1, z_2), z_1) &= d(S(z_1, z_2), S(u, v)) \\ &\leq \min\{d(T(z_1), T(u)), d(S(z_1, z_2), T(u)), d(S(u, v), T(u)), \\ &\quad d(S(v, u), T(v)), d(S(z_1, z_2), T(u))\}. \\ &= \min\{d(S(z_1, z_2), z_1), d(S(z_1, z_2), z_1), d(z_1, z_1), d(z_2, z_2), d(S(z_1, z_1), z_1))\}. \\ &= d(S(z_1, z_2), z_1). \end{aligned}$$

This implies that $S(z_1, z_2) = z_1$. Hence z_1 is a common fixed point of S and T . Similarly, it can be proved that z_2 is common fixed point of S and T .

Finally, we prove that common fixed point is unique i.e., $z_1 = z_2$.

Suppose that it not true. Then

$$\begin{aligned} d(z_1, z_2) &= d(S(z_1, z_2), S(z_2, z_1)) \\ &\leq \min\{d(T(z_1), T(z_2)), d(S(z_1, z_2), T(z_2)), d(S(z_2, z_1), T(z_2)), \\ &\quad d(S(z_1, z_2), T(z_1)), d(S(z_1, z_2), T(z_2))\} \\ &= \min\{d(z_1, z_2), d(z_1, z_2), d(z_2, z_2), d(z_1, z_1), d(z_1, z_2)\}. \\ &= d(z_1, z_2). \end{aligned}$$

which is a contradiction this concludes the proof. ■

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