

## On $\theta$ -Convergence and $S_{2\frac{1}{2}}$ Spaces

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### Abstract

In this paper we obtain some characterizations of  $S_{2\frac{1}{2}}$  spaces. We obtain conditions for a compact set and a point not in the set for having disjoint closed neighborhoods in  $S_{2\frac{1}{2}}$  spaces. We have also obtained a characterization for an  $S_1$  space to be  $S_{2\frac{1}{2}}$ .

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### 1. Introduction and Preliminaries

In [2], Dorsett introduced the concept of weakly Urysohn spaces and showed that these spaces lie strictly between the  $S_3$  and  $S_2$  of Császár [1] and were weaker than the well known separation axiom of Urysohn ( $T_{2\frac{1}{2}}$ ). Also it was proved that for rim-compact spaces the concepts of  $S_3$ ,  $S_2$  and weakly Urysohn coincide. In [9], weakly Urysohn was introduced in a refined form and was utilized to obtain some map gluing theorems on  $s\theta$ -continuity of maps. In [3], Dorsett obtained some characterizations of  $R_0$  and  $R_1$  spaces in terms of nets and closures. In [5], Dube has given several conditions for a compact set and a point outside the set to have disjoint neighborhoods in an  $R_1$  space and proved that the set of points whose images under two given continuous functions into an  $R_1$  space have the same closure, is closed. In [6], Dunham introduced the concept of weakly Hausdorff spaces and proved it to be equivalent to  $R_1$  space.

As weakly Urysohn spaces are obtained from  $T_{2\frac{1}{2}}$ , and lie strictly between the  $S_3$  and  $S_2$  separation axioms we preferred to call them  $S_{2\frac{1}{2}}$  spaces in [10]. In this paper analogous to weakly Hausdorff spaces we have defined weakly  $\theta$ -Urysohn spaces and have proved it to be equivalent to  $S_{2\frac{1}{2}}$  spaces [Theorem 2.3 below]. We have also given some conditions for a compact set and a singleton disjoint from it to have disjoint closed

neighborhoods in an  $S_{2\frac{1}{2}}$  space [Theorem 2.4 below] and have proved that the set of points whose images under two given continuous functions into an  $S_{2\frac{1}{2}}$  space have the same closure, is  $\theta$ -closed [Theorem 2.5 below]. Further a condition was obtained where the  $S_1$  and  $S_{2\frac{1}{2}}$  separation axioms coincide [Theorem 2.9 below]. A characterization of  $S_{2\frac{1}{2}}$  space was obtained in terms of regular open sets [Theorem 2.10 below].

Throughout, by a space  $X$  we shall mean a topological space and  $cl(A)$ ,  $int(A)$  and  $A^C$  will denote the closure, interior the complement of  $A$  in  $X$  respectively.

For a topological space  $X$  and a subset  $A$  of  $X$ , a point  $x \in X$  is said to be in the  $\theta$ -closure of  $A$  denoted by  $cl_\theta(A)$  if for every neighborhood  $U$  of  $x$  we have  $cl(U) \cap A \neq \phi$ . The subset  $A$  is  $\theta$ -closed if  $A = cl_\theta(A)$  and regular open if  $A = int(cl(A))$  or equivalently if it is interior of some closed set. Also, a point  $x \in ker(A)$  if  $cl\{x\} \cap A \neq \phi$  and  $\langle x \rangle = cl\{x\} \cap ker\{x\}$ . A point  $x \in X$  is a  $\theta$ -convergent point of a net  $P$  in  $X$ , if the net is eventually in the closure of every neighborhood containing  $x$ . A set which can be expressed as the closure of a singleton is said to be a point closure set. Further a space  $X$  is said to be,

1. Urysohn ( $T_{2\frac{1}{2}}$ ) space [9] if for every pair of distinct points  $x$  and  $y$  in  $X$  there exist neighborhoods  $U$  of  $x$  and  $V$  of  $y$  such that  $cl(U) \cap cl(V) = \phi$ .
2.  $S_3$  (regular) space [1] if for any point  $x$  and a closed set  $F$  not containing  $x$  there exist disjoint neighborhoods containing them.
3.  $S_{2\frac{1}{2}}$  space [1] ( $S$ - $S_2$  in sense of [9], weakly Urysohn in sense of [2]) if for every pair of distinct points  $x$  and  $y$  in  $X$ , whenever  $cl\{x\} \neq cl\{y\}$  then there exist neighborhoods  $U$  of  $x$  and  $V$  of  $y$  such that  $cl(U) \cap cl(V) = \phi$ .
4.  $S_2$  space [1] ( $R_1$  in sense of [2] [3] [5] [7] [8]) if for every pair of distinct  $x$  and  $y$  in  $X$ , whenever  $cl\{x\} \neq cl\{y\}$  then there exist disjoint neighborhoods containing them.
5.  $S_1$  space [1] ( $R_0$  in sense of [3] [4]) if for every pair of distinct points  $x$  and  $y$ , whenever  $x$  has a neighborhood not containing  $y$ , then  $y$  has a neighborhood not containing  $x$ .

In this paper we shall use the following results.

**Lemma 1.1. [8]** For each  $x, y \in X$ ,  $\langle x \rangle = \langle y \rangle$  if and only if  $cl\{x\} = cl\{y\}$  if and only if  $ker\{x\} = ker\{y\}$ .

**Lemma 1.2. [1]** In an  $S_2$  space  $X$  and  $K \subset X$  if  $K$  is compact then  $cl(K)$  is compact.

**Lemma 1.3. [4]** For any space  $X$  the following statements are equivalent:

- (a)  $X$  is  $S_1$ .
- (b) For any  $x, y \in X$ ,  $y \in cl\{x\}$  if and only if  $cl\{x\} = cl\{y\}$ .

**Lemma 1.4.** [8] For any topological space  $X$  the following statements are equivalent:

- (a)  $X$  is  $S_2$ .
- (b) For any  $x \in X$ ,  $cl\{x\} = cl_\theta\{x\}$ .

**Lemma 1.5.** A map  $f : X \rightarrow Y$  is continuous if and only if  $cl(f^{-1}(B)) \subset f^{-1}(cl(B))$  for all  $B \subset Y$ .

## 2. Results

**Definition 2.1.** A space  $X$  is weakly  $\theta$ -Urysohn if and only if for any  $x, y \in X$ ,  $cl\{x\} = cl\{y\}$  whenever there is a net  $P : D \rightarrow X$  in  $X$  which  $\theta$ -converges to both  $x$  and  $y$ .

**Theorem 2.2.**  $X$  is weakly  $\theta$ -Urysohn if and only if for each  $x, y \in X$  one of the following holds.

- (a)  $cl\{x\} = cl\{y\}$ .
- (b) There exist neighborhoods  $U$  of  $x$  and  $V$  of  $y$  such that  $cl(U) \cap cl(V) = \phi$ .

*Proof.* The proof is similar to [6, Theorem 2.2], and hence is omitted. ■

**Theorem 2.3.**  $X$  is weakly  $\theta$ -Urysohn if and only if  $S_{\frac{1}{2}}$ .

*Proof.* The proof follows from Theorem 2.2 and is similar to [6, Theorem 2.7] and hence is omitted. ■

**Theorem 2.4.** In an  $S_{2\frac{1}{2}}$  space, for a compact set  $F$  and  $x \in X$  such that  $x \notin F$ , have disjoint closed neighborhoods for the following cases:

- (a)  $x \notin cl\{F\}$ .
- (b)  $y \in F$  implies  $cl\{y\} \subset F$ .
- (c)  $y \in F$  implies  $ker\{x\} \neq ker\{y\}$ .
- (d)  $y \in F$  implies  $cl\{x\} \neq cl\{y\}$ .
- (e)  $y \in F$  implies  $\langle x \rangle \neq \langle y \rangle$ .

*Proof.* The proof follows from Lemma 1.1 and Lemma 1.2, is straightforward and hence is omitted. ■

**Theorem 2.5.** If  $f$  and  $g$  are two continuous functions from a topological space  $(X, T)$  to an  $S_{2\frac{1}{2}}$  topological space  $(X^*, T^*)$  then the set  $A = \{x \in X : clf(x) = clg(x)\}$  is  $\theta$ -closed in  $X$ .

*Proof.* The proof follows from Lemma 1.5 is similar to [5, Theorem 3.5] and hence is omitted. ■

In [7], it is proved that a space  $X$  is  $S_2$  is equivalent to the condition that for any  $x, y \in X$ ,  $y \in cl_\theta\{x\}$  if and only if every net which converges to  $y$  converges to  $x$ . We prove that in an  $S_2$  space for any points  $x, y \in X$ ,  $y$  is in the  $\theta$ -closure of  $x$  if and only if every net which  $\theta$ -converges to  $y$   $\theta$ -converges to  $x$ . We also show that unlike above in [7] this condition in terms of  $\theta$ -convergence is not equivalent for a space to be  $S_2$ .

**Theorem 2.6.** For any  $S_2$  space  $X$  and  $x, y \in X$ ,  $y \in cl_\theta\{x\}$  if and only if every net which  $\theta$ -converges to  $y$   $\theta$ -converges to  $x$ .

*Proof.* Let  $y \in cl_\theta\{x\}$ . Let  $P : D \rightarrow X$  be a net in  $X$  such that  $P$   $\theta$ -converges to  $y$ . Since  $y \in cl_\theta\{x\}$  implies  $x \in cl_\theta\{y\}$ . As space  $X$  is  $S_2$ , by Lemma 1.4 we have  $x \in cl\{y\}$ . Thus  $P$   $\theta$ -converges to  $x$ .

Conversely, let every net which  $\theta$ -converges to  $y$   $\theta$ -converges to  $x$ . Let  $P = y$ , be a constant net in  $X$  which  $\theta$ -converges to  $y$  and thus  $\theta$ -converges to  $x$  which implies  $x \in cl_\theta\{y\}$  and hence  $y \in cl_\theta\{x\}$ . ■

The following example shows that the converse of Theorem 2.6 does not hold.

**Example 2.7.** Let  $X = \{0, 1\}$ , together with the topology  $T = \{\phi, \{0\}, X\}$ . Such a topological space is well known as Siperinski space. This space satisfies the condition that for any  $x, y \in X$ ,  $y \in cl_\theta\{x\}$  if and only if every net which  $\theta$ -converges to  $y$   $\theta$ -converges to  $x$ . But since  $cl\{0\} \neq cl\{1\}$  and  $\{0\}, \{1\}$  do not have disjoint neighborhoods, the space is not  $S_2$ .

In the next example we show that Theorem 2.6 does not hold if the space is not  $S_2$ .

**Example 2.8.** Let  $X = \mathbf{Z}^+$ , the set of all positive integers together with the topology  $T = \{G \subset X : 0 \notin G\}$  i.e. all those sets are open which do not contain the point 0. Let  $x \in X$  be any point distinct from 0. Then as  $cl\{0\} \neq cl\{x\}$  and  $\{0\}, \{x\}$  do not have disjoint neighborhoods, the space is not  $S_2$ . As,  $\{0\} \in cl_\theta\{1\}$  and a sequence and hence a net defined as  $\{1, 2, 3, 4, \dots\}$   $\theta$ -converges to 0 but does not  $\theta$ -converges to 1, Theorem 2.6 does not hold.

**Theorem 2.9.** Any  $S_1$  topological space  $X$  is  $S_{2\frac{1}{2}}$  if and only if for every  $\theta$ -convergent net  $P$  in  $X$  the set of all  $\theta$ -convergent points of the net  $P$ , is a point closure set.

*Proof.* Let  $X$  be any  $S_1$  space which is also  $S_{2\frac{1}{2}}$ . Let  $P$  be a  $\theta$ -convergent net in  $X$  such that  $P$   $\theta$ -converges to some point  $x \in X$ . Let  $G$  be the set of all  $\theta$ -convergent points of the net  $P$  and let  $y \in G$ . Then by Theorem 2.3  $cl\{x\} = cl\{y\}$  which implies  $y \in cl\{x\}$  and thus  $G \subset cl\{x\}$ . If  $y \in cl\{x\} \subset cl_\theta\{x\}$  then  $x \in cl_\theta\{y\}$  and since every  $S_{2\frac{1}{2}}$  is  $S_2$  by Theorem 2.6 we have  $P$   $\theta$ -converges to  $y$ . Thus,  $y \in G$  and it implies  $cl\{x\} \subset G$ . Therefore,  $G = cl\{x\}$  and is a point closure set.

Converse follows from Lemma 1.3 and Theorem 2.3. ■

**Theorem 2.10.** For any topological space  $X$  the following statements are equivalent:

- (a)  $X$  is  $S_{2\frac{1}{2}}$ .
- (b) If  $x, y \in X$  such that  $cl\{x\} \neq cl\{y\}$  then there exists regular open sets  $U_1$  and  $U_2$  such that  $x \in U_1, y \notin U_1, y \in U_2, x \notin U_2$  such that  $X = U_1 \cup U_2$ .

*Proof.* (a)  $\Rightarrow$  (b) Let  $X$  is an  $S_{2\frac{1}{2}}$  space. Let for any  $x, y \in X$  be such that  $cl\{x\} \neq cl\{y\}$ . Then as space  $X$  is  $S_{2\frac{1}{2}}$ , there exist open sets  $V$  containing  $x$  and  $W$  containing  $y$  such that,  $cl(V) \cap cl(W) = \phi$ . Then,  $int(W^C) = U_1$  and  $int(V^C) = U_2$  being interior of closed sets are regular open sets such that  $x \in U_1, y \notin U_1, y \in U_2, x \notin U_2$  such that  $X = U_1 \cup U_2$ .

(b)  $\Rightarrow$  (a) Let  $x, y \in X$  be such that  $cl\{x\} \neq cl\{y\}$ . Then there exists regular open sets  $U_1$  and  $U_2$  such that  $x \in U_1, y \notin U_1, y \in U_2, x \notin U_2$  such that  $X = U_1 \cup U_2$ . Since regular open sets are open and  $(U_1)^C \cap (U_2)^C = \phi \Rightarrow (int(cl(U_1)))^C \cap (int(cl(U_2)))^C = \phi \Rightarrow cl(int(U_1^C)) \cap cl(int(U_2^C)) = \phi \Rightarrow cl(int(U_2)) \cap cl(int(U_1)) = \phi \Rightarrow cl(U_2) \cap cl(U_1) = \phi$ . Therefore, there exist open sets  $U_1$  containing  $x$  and  $U_2$  containing  $y$  such that,  $cl(U_1) \cap cl(U_2) = \phi$  and hence the space  $X$  is  $S_{2\frac{1}{2}}$ . ■

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