

Symmetric Generalized Bi- (σ, τ) -Reverse Derivations in Prime and Semiprime Rings

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Abstract: Let R be a 2-torsion free prime and semiprime ring and G be a symmetric generalized bi- (σ, τ) - reverse derivation of R with associated symmetric bi- (σ, τ) - reverse derivation B . (i) If $G([x, y], [u, v]) = 0$ for all $x, y, u, v \in R$ (ii) If $G((xoy), [u, v]) = 0$ for all $x, y, u, v \in R$ (iii) If $G([x, y], (uov)) = 0$ for all $x, y, u, v \in R$ (iv) If $G((xoy), (uov)) = 0$ for all $x, y, u, v \in R$, then either R is commutative or G acts as a bi-multiplier.

Keywords: Prime ring, Semiprime ring, Symmetric bi- (σ, τ) -reverse derivation, Symmetric generalized bi- (σ, τ) -reverse derivation.

1. INTRODUCTION

The notion of reverse derivation has been introduced by Bresar and Vukman in [4] and the reverse derivations on semi prime rings have been studied by Samman and Alyamani in [13]. The concept of a symmetric bi-derivation has been introduced Maksa in [10], [11]. Ozturk and Jun in [12] have introduced the concept of symmetric bi-derivation of a near ring and studied some properties. The notion of generalized symmetric biderivations introduced by Argac [2]. Ceven and Ozturk in [5] introduce the concepts of symmetric bi- (σ, τ) -derivation of a near ring and gave some properties. In 2011, the concepts of (θ, φ) -reverse derivation and generalized (θ, φ) -reverse derivation has been introduced by Anwar Khaleel Faraj in [1]. In 2016, Jaya Subba Reddy et.al in [6, 8] has studied symmetric reverse bi-derivations on prime

rings and semiprime rings, Results of Symmetric Reverse Bi-Derivations on Prime Rings [9] and also proved important results on Symmetric Bi- (σ, τ) -Derivations in Prime Rings [7]. In 2018, Asma Ali et.al in [3] has proved some results on generalized biderivations on prime and semiprime rings. In this paper we proved some results on symmetric generalized bi- (σ, τ) -reverse derivations in prime and semiprime rings.

2. PRELIMINARIES

Throughout this paper R will represent an associative ring with center $Z(R)$. A ring R is said to be prime (resp. semiprime) if $aRb = 0$ implies that either $a = 0$ or $b = 0$ (resp. $aRa = 0$ implies that $a = 0$). A ring R to be 2-torsion free if $2x = 0$ implies $x = 0$, for all $x \in R$. For any $x, y \in R$, the symbol $[x, y]$ stands for the commutator $xy - yx$ and the symbol (xoy) stands for the anti commutator $xy + yx$. A mapping $B(.,.): R \times R \rightarrow R$ is called a symmetric if $B(x, y) = B(y, x)$, for all $x, y, z \in N$. A mapping $b: R \rightarrow R$ is said to be trace of B if $b(x) = B(x, x)$, for all $x \in R$, where $B(.,.): R \times R \rightarrow R$ is a symmetric bi-additive mapping. The trace of B satisfies the relation $b(x + y) = b(x) + 2B(x, y) + b(y)$, for all $x, y \in R$. An additive mapping $b: R \rightarrow R$ is called a reverse derivation if $b(xy) = b(y)x + yb(x)$, for all $x, y \in R$. A symmetric bi-additive mapping $B(.,.): R \times R \rightarrow R$ is called a symmetric bi-reverse derivation if $B(xz, y) = B(z, y)x + zB(x, y)$, for all $x, y, z \in R$. An additive mapping $b: R \rightarrow R$ is called a (σ, τ) -reverse derivation if $b(xy) = b(y)\sigma(x) + \tau(y)b(x)$, for all $x, y \in R$, where σ and τ to be a automorphisms of R . A symmetric bi-additive mapping $B(.,.): R \times R \rightarrow R$ is called a symmetric bi- (σ, τ) -reverse derivation if there exists functions $\sigma, \tau: R \rightarrow R$ such that $B(xz, y) = B(z, y)\sigma(x) + \tau(y)B(x, y)$, for all $x, y, z \in R$. An additive mapping $F: R \rightarrow R$ is called a generalized reverse derivation, if there exists a reverse derivation $b: R \rightarrow R$ such that $F(xy) = F(y)x + yb(x)$, for all $x, y \in R$. A symmetric bi-additive mapping $G(.,.): R \times R \rightarrow R$ is called a symmetric generalized bi-reverse derivation if there exists a symmetric bi-reverse derivation $B(.,.): R \times R \rightarrow R$ such that $G(xz, y) = G(z, y)x + zB(x, y)$, for all $x, y, z \in R$. An additive mapping $F: R \rightarrow R$ is said to be a generalized (σ, τ) -reverse derivation of R , if there exists a (σ, τ) -reverse derivation $b: R \rightarrow R$ such that $F(xy) = F(y)\sigma(x) + \tau(y)b(x)$, for all $x, y \in R$, where σ and τ are automorphisms of R . A symmetric bi-additive mapping $G(.,.): R \times R \rightarrow R$ is called a symmetric generalized bi- (σ, τ) -reverse derivation if there exists a symmetric bi- (σ, τ) -reverse derivation $B(.,.): R \times R \rightarrow R$ such that $G(xz, y) = G(z, y)\sigma(x) + \tau(z)B(x, y)$, for all $x, y, z \in R$, where σ and τ to be a automorphisms of R . An additive mapping $h: R \rightarrow R$ is called left (resp. right) multiplier of R if $h(xy) = h(x)y$ (resp. $h(xy) = xh(y)$) for all $x, y \in R$. A biadditive mapping $H: R \times R \rightarrow R$ is said to be a left (resp. right) bi-multiplier of R if $H(x, yz) = H(x, y)z$ (resp. $H(xz, y) = xH(z, y)$) for all $x, y, z \in R$. Throughout the present paper, we will make extensive use of the following basic identities:

$$[x, yz] = y[x, z] + [x, y]z,$$

$$[xy, z] = [x, z]y + x[y, z],$$

$$xo(yz) = (xoy)z - y[x, z] = y(xoz) + [x, y]z,$$

$$(xy)oz = x(yoz) - [x, z]y = (xoz)y + x[y, z].$$

3. MAIN RESULTS

Theorem 3.1: Let R be a 2-torsion free semiprime ring and G be a symmetric generalized bi- (σ, τ) -reverse derivation of R with associated symmetric bi- (σ, τ) -reverse derivation B . If $G([x, y], [u, v]) = 0$ for all $x, y, u, v \in R$, then either R is commutative or G acts as a bi-multiplier.

Proof: We have $G([x, y], [u, v]) = 0$ for all $x, y, u, v \in R$. (3.1)

Replacing y by xy in equation (3.1), we get $G(x[x, y], [u, v]) = 0$ for all $x, y, u, v \in R$.

$$G([x, y], [u, v])\sigma(x) + \tau[x, y]B(x, [u, v]) = 0 \text{ for all } x, y, u, v \in R.$$

Using equation (3.1) in the above equation, we get

$$\tau[x, y]B(x, [u, v]) = 0 \text{ for all } x, y, u, v \in R. \quad (3.2)$$

Replacing u by vu in equation (3.2), we get

$$\tau[x, y]B(x, v[u, v]) = 0 \text{ for all } x, y, u, v \in R.$$

$$\tau[x, y]B(x, [u, v])\sigma(v) + \tau[x, y]\tau[u, v]B(x, v) = 0 \text{ for all } x, y, u, v \in R.$$

Using equation (3.2) in the above equation, we get

$$\tau[x, y]\tau[u, v]B(x, v) = 0 \text{ for all } x, y, u, v \in R. \quad (3.3)$$

Substitute yr for y in equation (3.3), we get

$$\tau(y)\tau[x, r]\tau[u, v]B(x, v) + \tau[x, y]\tau(r)\tau[u, v]B(x, v) = 0 \text{ for all } x, y, u, v, r \in R.$$

Using equation (3.3) in the above equation, we get

$$\tau[x, y]\tau(r)\tau[u, v]B(x, v) = 0 \text{ for all } x, y, u, v, r \in R. \quad (3.4)$$

Replacing $\tau(r)$ by $B(x, v)\tau(r)$ in equation (3.4), we get

$$\tau[x, y]B(x, v)\tau(r)\tau[u, v]B(x, v) = 0 \text{ for all } x, y, u, v, r \in R.$$

$$\tau[x, y]B(x, v)R\tau[u, v]B(x, v) = 0 \text{ for all } x, y, u, v \in R. \quad (3.5)$$

Using semi primeness of R , we have either $\tau[x, y] = 0$ or $B(x, v) = 0$ for all $x, y, v \in R$.

If $\tau[x, y] = 0$, then R is commutative. In the later case we get G acts as a bi-multiplier.

Corollary 3.1: Let R be a 2-torsion free semiprime ring and G be a symmetric generalized bi- (σ, τ) -reverse derivation of R with associated symmetric bi- (σ, τ) -reverse derivation B . If $G([x, y], z) = 0$ for all $x, y, z \in R$, then either R is commutative or G acts as a bi-multiplier.

Theorem 3.2: Let R be a 2-torsion free semiprime ring and G be a symmetric generalized bi- (σ, τ) -reverse derivation of R with associated symmetric bi- (σ, τ) -reverse derivation B . If $G((xoy), [u, v]) = 0$ for all $x, y, u, v \in R$, then either R is commutative or G acts as a bi-multiplier.

Proof: We have $G((xoy), [u, v]) = 0$ for all $x, y, u, v \in R$. (3.6)

Replacing y by xy in equation (3.6), we get $G(x(xoy), [u, v]) = 0$ for all $x, y, u, v \in R$.

$$G((xoy), [u, v])\sigma(x) + \tau(xoy)B(x, [u, v]) = 0 \text{ for all } x, y, u, v \in R.$$

Using equation (3.6) in the above equation, we get

$$\tau(xoy)B(x, [u, v]) = 0 \text{ for all } x, y, u, v \in R. \quad (3.7)$$

Replacing u by vu in equation (3.7), we get

$$\tau(xoy)B(x, v[u, v]) = 0 \text{ for all } x, y, u, v \in R.$$

$$\tau(xoy)B(x, [u, v])\sigma(v) + \tau(xoy)\tau[u, v]B(x, v) = 0 \text{ for all } x, y, u, v \in R.$$

Using equation (3.7) in the above equation, we get

$$\tau(xoy)\tau[u, v]B(x, v) = 0 \text{ for all } x, y, u, v \in R. \quad (3.8)$$

Substitute yr for y in equation (3.8), we get

$$\tau(y)\tau(xor)\tau[u, v]B(x, v) + \tau[x, y]\tau(r)\tau[u, v]B(x, v) = 0 \text{ for all } x, y, u, v, r \in R.$$

Using equation (3.8) in the above equation, we get

$$\tau[x, y]\tau(r)\tau[u, v]B(x, v) = 0 \text{ for all } x, y, u, v, r \in R \quad (3.9)$$

The equation (3.9) is same as equation (3.4) in theorem 3.1. Hence the result is proved.

Theorem 3.3: Let R be a 2-torision free prime ring and G be a symmetric generalized bi- (σ, τ) -reverse derivation of R with associated symmetric bi- (σ, τ) -reverse derivation B . If $G([x, y], (uov)) = 0$ for all $x, y, u, v \in R$, then either R is commutative or G acts as a bi-multiplier.

Proof: We have $G([x, y], (uov)) = 0$ for all $x, y, u, v \in R$. (3.10)

Replacing y by xy in equation (3.10), we get $G(x[x, y], (uov)) = 0$ for all $x, y, u, v \in R$.

$$G([x, y], [u, v])\sigma(x) + \tau[x, y]B(x, (uov)) = 0 \text{ for all } x, y, u, v \in R.$$

Using equation (3.10) in the above equation, we get

$$\tau[x, y]B(x, (uov)) = 0 \text{ for all } x, y, u, v \in R. \quad (3.11)$$

Replacing u by vu in equation (3.11), we get

$$\tau[x, y]B(x, v(uov)) = 0 \text{ for all } x, y, u, v \in R.$$

$$\tau[x, y]B(x, (uov))\sigma(v) + \tau[x, y]\tau(uov)B(x, v) = 0 \text{ for all } x, y, u, v \in R.$$

Using equation (3.11) in the above equation, we get

$$\tau[x, y]\tau(uov)B(x, v) = 0 \text{ for all } x, y, u, v \in R. \quad (3.12)$$

Substitute yr for y in equation (3.12), we get

$\tau(y)\tau[x, r]\tau(uov)B(x, v) + \tau[x, y]\tau(r)\tau(uov)B(x, v) = 0$ for all $x, y, u, v, r \in R$.

Using equation (3.12) in the above equation, we get

$$\tau[x, y]\tau(r)\tau(uov)B(x, v) = 0 \text{ for all } x, y, u, v, r \in R. \quad (3.13)$$

Replacing $\tau(r)$ by $B(w, z)\tau(r)$ in equation (3.13), we get

$$\tau[x, y]B(w, z)\tau(r)\tau(uov)B(x, v) = 0 \text{ for all } x, y, u, v, r, w, z \in R.$$

$$\tau[x, y]B(w, z)R\tau(uov)B(x, v) = 0 \text{ for all } x, y, u, v, w, z \in R. \quad (3.14)$$

Using primeness of R , we have either $\tau[x, y]B(w, z) = 0$ or $\tau(uov)B(x, v) = 0$ for all $x, y, u, v \in R$.

$$\text{Now first suppose that } \tau[x, y]B(w, z) = 0 \text{ for all } x, y, w, z \in R. \quad (3.15)$$

Substituting ys instead of y in equation (3.15), we get

$$\tau(y)\tau[x, s]B(w, z) + \tau[x, y]\tau(s)B(w, z) = 0 \text{ for all } x, y, w, z, s \in R.$$

Using equation (3.15) in the above equation, we get

$$\tau[x, y]\tau(s)B(w, z) = 0 \text{ for all } x, y, w, z, s \in R.$$

$$\tau[x, y]RB(w, z) = 0 \text{ for all } x, y, w, z \in R. \quad (3.16)$$

Using primeness of R , then either $\tau[x, y] = 0$ or $B(w, z) = 0$ for all $x, y, w, z \in R$.

If $\tau[x, y] = 0$, then R is commutative. In the later case G acts as a bi-multiplier.

$$\text{In second case suppose that } \tau(uov)B(x, v) = 0 \text{ for all } x, u, v \in R. \quad (3.17)$$

Substituting $\tau(uov)\tau(t)$ instead of $\tau(uov)$ in equation (3.17), we get

$$\tau(uov)\tau(t)B(x, v) = 0 \text{ for all } x, u, v, t \in R.$$

$$\tau(uov)RB(x, v) = 0 \text{ for all } x, u, v \in R. \quad (3.18)$$

Using primeness of R , then either $\tau(uov) = 0$ or $B(x, v) = 0$ for all $x, u, v \in R$.

If $\tau(uov) = 0$, then R is commutative. In the later case we get G acts as a bi-multiplier.

Theorem 3.4: Let R be a 2-torision free prime ring and G be a symmetric generalized bi- (σ, τ)-reverse derivation of R with associated symmetric bi- (σ, τ)-reverse derivation B . If $G((xoy), (uov)) = 0$ for all $x, y, u, v \in R$, then either R is commutative or G acts as a bi-multiplier.

$$\text{Proof: We have } G((xoy), (uov)) = 0 \text{ for all } x, y, u, v \in R. \quad (3.19)$$

Replacing y by xy in equation (3.19), we get $G(x(xoy), (uov)) = 0$ for all $x, y, u, v \in R$.

$$G((xoy), (uov))\sigma(x) + \tau(xoy)B(x, (uov)) = 0 \text{ for all } x, y, u, v \in R.$$

Using equation (3.19) in the above equation, we get

$$\tau(xoy)B(x, (uov)) = 0 \text{ for all } x, y, u, v \in R. \quad (3.20)$$

Replacing u by vu in equation (3.20), we get

$$\tau(xoy)B(x, v(uov)) = 0 \text{ for all } x, y, u, v \in R.$$

$$\tau(xoy)B(x, (uov))\sigma(v) + \tau(xoy)\tau(uov)B(x, v) = 0 \text{ for all } x, y, u, v \in R.$$

Using equation (3.20) in the above equation, we get

$$\tau(xoy)\tau(uov)B(x, v) = 0 \text{ for all } x, y, u, v \in R. \quad (3.21)$$

Substitute yr for y in equation (3.21), we get

$$\tau(y)\tau(xor)\tau(uov)B(x, v) + \tau[x, y]\tau(r)\tau(uov)B(x, v) = 0 \text{ for all } x, y, u, v, r \in R.$$

Using equation (3.21) in the above equation, we get

$$\tau[x, y]\tau(r)\tau(uov)B(x, v) = 0 \text{ for all } x, y, u, v, r \in R. \quad (3.22)$$

The equation (3.22) is same as equation (3.13) in theorem 3.2. Hence the result is proved.

Corollary 3.2: Let R be a 2-torsion free prime ring and G be a symmetric generalized bi- (σ, τ) -reverse derivation of R with associated symmetric bi- (σ, τ) -reverse derivation B . If $G((xoy), z) = 0$ for all $x, y, z \in R$, then either R is commutative or G acts as a bi-multiplier.

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