

Connected Edge-Vertex Mixed Domination on S -Valued Graphs

S. Kiruthiga Deepa

*Bharath Niketan College of Engineering,
Aundipatti - 625536, Tamilnadu, INDIA.*

M. Chandramouleeswaran

*Saiva Bhanu Kshatriya College,
Aruppukottai - 626101, Tamilnadu, INDIA.*

Abstract

In this paper we discuss the notion of connected ev -weight m -domination set on the S -valued graph, G^S .

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Keywords: S -valued graphs, ev -weight m -domination number, connected ev -weight m -domination set..

1. Introduction

Corresponding to a given graph $G = (V, E)$, Chandramouleeswaran et al., [5] introduced the concept of S -valued graph $G^S = (V, E, \sigma, \psi)$, where σ is a mapping from $V \rightarrow S$ and ψ is a mapping from $E \rightarrow S$, called respectively the σ -set and ψ -set. In [2] we have discussed the notion of edge-vertex mixed domination on G^S . In [1] the authors discussed the notion of connected weight domination vertex set and in [4] the authors discussed on connected weight domination edge set of G^S . Motivated by this, in this paper we discuss the notion of connected ev -weight m -domination set on G^S .

2. Preliminaries

In this section, we recall some basic definitions that are needed for our work.

Definition 2.1. A semiring $(S, +, \cdot)$ is an algebraic system with a non-empty set S together with two binary operations $+$ and \cdot such that

1. $(S, +, 0)$ is a monoid.
2. (S, \cdot) is a semigroup.
3. For all $a, b, c \in S$, $a \cdot (b + c) = a \cdot b + a \cdot c$ and $(a + b) \cdot c = a \cdot c + b \cdot c$.
4. $0 \cdot x = x \cdot 0 = 0 \forall x \in S$.

Definition 2.2. Let $(S, +, \cdot)$ be a semiring. A Canonical Pre-order \preceq in S defined as follows: for $a, b \in S$, $a \preceq b$ if and only if, there exists an element $c \in S$ such that $a + c = b$.

Definition 2.3. [5] Let $G = (V, E \subset V \times V)$ be a given graph with $V, E \neq \phi$. For any semiring $(S, +, \cdot)$, a semiring-valued graph (or a S -valued graph), G^S , is defined to be the graph $G^S = (V, E, \sigma, \psi)$ where $\sigma : V \rightarrow S$ and $\psi : E \rightarrow S$ is defined to be

$$\psi(x, y) = \begin{cases} \min \{\sigma(x), \sigma(y)\} & \text{if } \sigma(x) \preceq \sigma(y) \text{ or } \sigma(y) \preceq \sigma(x) \\ 0 & \text{otherwise} \end{cases}$$

for every unordered pair (x, y) of $E \subset V \times V$. We call σ , a S -vertex set and ψ , a S -edge set of G^S .

Definition 2.4. [5] Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$. The length of the path $P^S(uv)$, denoted by $l(P^S(uv))$, is defined to be the number of edges along the path $P^S(uv)$.

Definition 2.5. [2] Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$. Let $T \subseteq E$. If every vertex of G^S is weight m -dominated by any edge in T , then T is said to be a ev -weight m -dominating set.

Definition 2.6. [3] Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$. The edge-vertex mixed domination number of G^S denoted by $\gamma_{EV}^S(G^S)$ is defined by $\gamma_{EV}^S(G^S) = (|T|_S, |T|)$, where T is the minimal ev -weight m -dominating set.

3. Connected Vertex-Edge Mixed Domination on S -valued Graphs

In this section, we introduce the notion of connected edge-vertex mixed domination in S -valued graph, analogous to the notion in crisp graph theory, and prove some simple results.

Definition 3.1. Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$. A ev -weight m -dominating set $T \subseteq E$ of G^S is said to be a connected ev -weight m -dominating set if $\langle T \rangle^S$ is connected in G^S .

Example 3.2. Let $(S = \{0, a, b, c\}, +, \cdot)$ be a semiring with the following Cayley Tables:

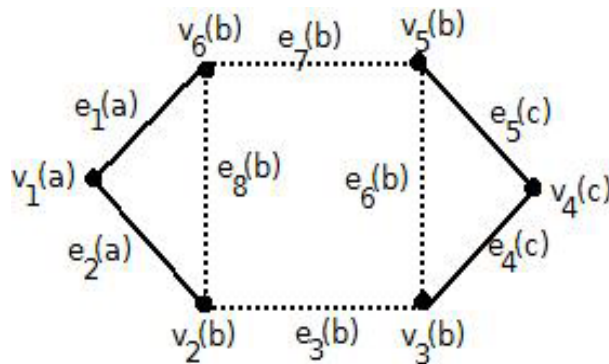
+	0	a	b	c
0	0	a	b	c
a	a	a	b	c
b	b	b	b	b
c	c	c	b	c

·	0	a	b	c
0	0	0	0	0
a	0	0	a	0
b	0	a	b	c
c	0	0	c	c

Let \preceq be a canonical pre-order in S , given by

$$0 \preceq 0, 0 \preceq a, 0 \preceq b, 0 \preceq c, a \preceq a, a \preceq b, a \preceq c, b \preceq b, c \preceq b, c \preceq c$$

Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$.



Define $\sigma : V \rightarrow S$ by

$$\sigma(v_1) = a, \sigma(v_2) = \sigma(v_3) = \sigma(v_5) = \sigma(v_6) = b, \sigma(v_4) = c$$

and $\psi : E \rightarrow S$ by

$$\psi(e_1) = \psi(e_2) = a, \psi(e_3) = \psi(e_6) = \psi(e_7) = \psi(e_8) = b, \psi(e_4) = \psi(e_5) = c$$

Consider the set $T_1 = \{e_3, e_6\}$.

Here the vertices v_1, v_2, v_3, v_4, v_5 and $v_6 \in \langle N_S[e_3] \rangle$,

$$\text{also } \sigma(v_1) = a \preceq b = \psi(e_3)$$

$$\sigma(v_2) = b \preceq b = \psi(e_3)$$

$$\sigma(v_3) = b \preceq b = \psi(e_3)$$

$$\sigma(v_4) = c \preceq b = \psi(e_3)$$

$$\sigma(v_5) = b \preceq b = \psi(e_3)$$

$$\sigma(v_6) = b \preceq b = \psi(e_3)$$

\therefore The edge e_3 is a ev -weight m -dominating edge of the vertices v_1, v_2, v_3, v_4, v_5 and v_6 .
And the vertices v_2, v_3, v_4, v_5 and $v_6 \in \langle N_S[e_6] \rangle$,

also $\sigma(v_2) = b \leq b = \psi(e_6)$

$\sigma(v_3) = b \leq b = \psi(e_6)$

$\sigma(v_4) = c \leq b = \psi(e_6)$

$\sigma(v_5) = b \leq b = \psi(e_6)$

$\sigma(v_6) = b \leq b = \psi(e_6)$

\therefore The edge e_6 is a ev -weight m -dominating edge of the vertices v_2, v_3, v_4, v_5 and v_6 .

Hence $T_1 = \{e_3, e_6\}$ is a ev -weight m -dominating set. Also $\langle T_1 \rangle^S$ is connected.

Therefore T_1 is a connected ev -weight m -dominating set.

Similarly $T_2 = \{e_6, e_7\}$, $T_3 = \{e_7, e_8\}$, $T_4 = \{e_3, e_8\}$, $T_5 = \{e_3, e_6, e_7\}$, $T_6 = \{e_6, e_7, e_8\}$,
 $T_7 = \{e_3, e_7, e_8\}$, $T_8 = \{e_3, e_6, e_8\}$, $T_9 = \{e_3, e_6, e_7, e_8\}$ are all connected ev -weight
 m -dominating sets.

Remark 3.3. From the definition, we have, every connected ev -weight m -dominating set is a ev -weight m -dominating set. But the converse need not be true as shown in the following example.

In example 3.2, clearly $T_{10} = \{e_3, e_7\}$ and $T_{11} = \{e_6, e_8\}$ are ev -weight m -dominating sets, and also $\langle T_{10} \rangle^S, \langle T_{11} \rangle^S$ are not connected. Hence T_{10}, T_{11} are not connected ev -weight m -dominating sets.

Definition 3.4. Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$. A subset $T \subseteq E$ is said to be a minimal connected ev -weight m -dominating set, if

1. T is a connected ev -weight m -dominating set.
2. No proper subset of T is a connected ev -weight m -dominating set.

In example 3.2, clearly T_1, T_2, T_3, T_4 are minimal connected ev -weight m -dominating sets.

Definition 3.5. Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$. A subset $T \subseteq E$ is said to be a maximal connected ev -weight m -dominating set, if

1. T is a connected ev -weight m -dominating set.
2. there is no connected ev -weight m -dominating set $T' \subset E$ such that $T \subset T' \subset E$.

In example 3.2, clearly T_9 is a maximal connected ev -weight m -dominating set.

Definition 3.6. Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$. The connected edge-vertex mixed domination number of G^S is defined by $\gamma_{CEV}^S(G^S) = (|T|_S, |T|)$, where T is the minimal connected ev -weight m -dominating set.

In example 3.2, the connected edge-vertex mixed domination number is $\gamma_{CEV}^S(G^S) = (|T_1|_S, |T_1|) = (|T_2|_S, |T_2|) = (|T_3|_S, |T_3|) = (|T_4|_S, |T_4|) = (b, 2)$.

Theorem 3.7. A S -valued graph G^S will have a connected ev -weight m -dominating set if and only if G^S is connected.

Proof. Let $C_i^S = (V_i, E_i, \sigma_i, \psi_i)$ be the connected components of $G^S, i = 1, 2, \dots, m$ where $\sigma_i = \sigma \setminus v_i, \psi_i = \psi \setminus E_i$.

Let T_i be the ev -weight m -dominating set of C_i^S whose elements have maximal S -value. Since a ev -weight m -dominating set T of G^S will have an edge from every component of $G^S, T = \cup_{i=1}^m T_i$.

Now T is a connected ev -weight m -dominating set $\Leftrightarrow \langle T \rangle^S$ is connected.

\Leftrightarrow there is a common vertex between $e_i \in T_i$ and $e_j \in T_j, i \neq j, i, j = 1, 2, \dots, m$

$\Leftrightarrow G^S$ is connected. ■

Theorem 3.8. For a S -valued graph $G^S = (V, E, \sigma, \psi)$,

$$\gamma_{EV}^S(G^S) \leq \gamma_{CEV}^S(G^S) \leq 3\gamma_{EV}^S(G^S) + 2(0, -1)$$

Proof. By definition, Every connected ev -weight m -dominating set is necessarily a ev -weight m -dominating set $\Rightarrow \gamma_{EV}^S(G^S) \leq \gamma_{CEV}^S(G^S)$.

Let T be a ev -weight m -dominating set of G^S , such that $\gamma_{EV}^S(G^S) = (|T|_S, |T|)$, and let the induced subgraph $\langle T \rangle^S$ have m components, then $|T| \geq m$.

Claim: There exists two components C_i^S and C_j^S where $i \neq j$ of $\langle T \rangle^S$ such that the length of a shortest path between C_i^S and C_j^S is atmost 3 in G^S . Assume that there exists a shortest path between C_i^S and C_j^S of length atleast 4. Let P_S be the shortest of all shortest path between two distinct components of $\langle T \rangle^S$. Hence we can find a edge $(e, \psi(e))$ in the path P_S such that e is at a distance of atleast 2 from the end points of P_S . Since T is a ev -weight m -dominating set, then the edge e must be at a distance of atmost 1 from a component. Thus the edge e lies on a path P'_S between the two components C_i^S and $C_j^S, (i \neq j)$ such that $l(P'_S) \leq l(P_S)$. This contradicts the assumption that the length of the path P_S is atleast 4. This proves that, there exists two components C_i^S and C_j^S where $i \neq j$ of $\langle T \rangle^S$ such that the path between them has length atmost 3. Adding an edge in the path P to the ev -weight m -dominating set T , decreases the number of components of $\langle T \rangle^S$ by 1. Continuing this procedure, we obtain only one component in $\langle T \rangle^S$, proving that T is a ev -weight m -dominating set. Thus we can add atmost $2(m - 1)$ edges to the ev -weight m -dominating set T , so as to form a connected ev -weight m -dominating set.

$$\text{Thus } \gamma_{CEV}^S(G^S) \leq (|T|_S, |T|) + 2\left(\sum_{i=1}^{m-1} \psi(e_i), m - 1\right)$$

$$\leq (|T|_S, |T|) + 2\left(\sum_{e \in T} \psi(e) + 0, (|T| - 1)\right)$$

$$\leq (|T|_S, |T|) + 2((|T|_S, |T|) + (0, -1))$$

$$= \gamma_{EV}^S(G^S) + 2(\gamma_{EV}^S(G^S) + (0, -1))$$

$$= 3\gamma_{EV}^S(G^S) + 2(0, -1).$$

Hence $\gamma_{EV}^S(G^S) \preceq \gamma_{CEV}^S(G^S) \preceq 3\gamma_{EV}^S(G^S) + 2(0, -1)$. ■

4. Some Discussion on Mixed Domination Numbers on S -Valued Graphs

In this section, we discuss and compare the mixed domination numbers. In particular we establish the following theorem.

Theorem 4.1. For any S -valued graph G^S , we have

$$\gamma_{EV}^S(G^S) \preceq \gamma_{CEV}^S(G^S) \preceq \gamma_{VE}^S(G^S) \preceq \gamma_{CVE}^S(G^S).$$

First we discuss some examples.

Example 4.2. Let $(S = \{0, a, b, c\}, +, \cdot)$ be a semiring with the following Cayley Tables:

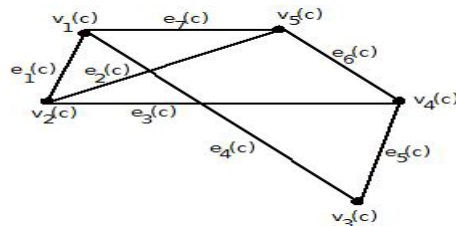
+	0	a	b	c
0	0	a	b	c
a	a	b	c	c
b	b	c	c	c
c	c	c	c	c

·	0	a	b	c
0	0	0	0	0
a	0	a	b	c
b	0	b	c	c
c	0	c	c	c

Let \preceq be a canonical pre-order in S , given by

$$0 \preceq 0, 0 \preceq a, 0 \preceq b, 0 \preceq c, a \preceq a, a \preceq b, a \preceq c, b \preceq b, b \preceq c, c \preceq c$$

Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$



Clearly $D = \{v_1, v_2, v_3\}$ is the minimal ve -weight m -dominating set and $\gamma_{VE}^S(G^S) = (c, 3)$. Also $\langle D \rangle^S$ is connected. Hence D is a minimal connected ve -weight m -dominating set and $\gamma_{CVE}^S(G^S) = (c, 3)$. Clearly $T = \{e_1\}$ is the minimal ev -weight m -dominating set and $\gamma_{EV}^S(G^S) = (c, 1)$. Also $\langle T \rangle^S$ is connected. Hence T is a minimal connected ev -weight m -dominating set and $\gamma_{CEV}^S(G^S) = (c, 1)$. Hence we conclude that, if G^S is a vertex S -regular and an edge S -regular graph, then

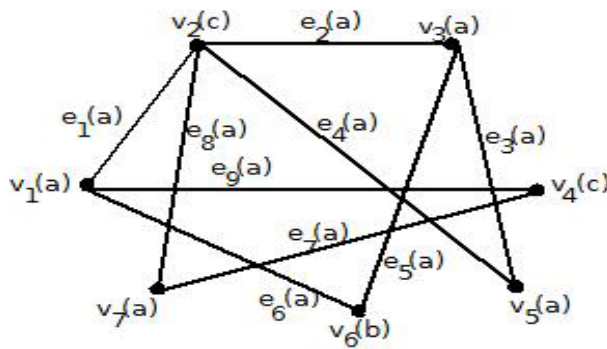
$$\gamma_{EV}^S(G^S) \preceq \gamma_{CEV}^S(G^S) \preceq \gamma_{VE}^S(G^S) \preceq \gamma_{CVE}^S(G^S).$$

Remark 4.3. If G^S is not a vertex regular but an edge regular graph, then

$$\gamma_{EV}^S(G^S) \preceq \gamma_{CEV}^S(G^S) \preceq \gamma_{VE}^S(G^S) \preceq \gamma_{CVE}^S(G^S).$$

For an edge regular graph G^S , which is not a vertex S -regular, we have $\gamma_{EV}^S(G^S) = \gamma_{CEV}^S(G^S) = (\psi(e), 0)$ where $\psi(e) \in S$ is smaller, for some $e \in E$. This is illustrated by the following example.

Example 4.4. Let $(S = \{0, a, b, c\}, +, \cdot)$ be a semiring with the canonical preorder given in example 4.2. Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$



Clearly $D = \{v_1, v_2, v_3, v_4\}$ is the minimal ve -weight m -dominating set and $\gamma_{VE}^S(G^S) = (c, 4)$. Also $\langle D \rangle^S$ is connected. Hence D is a minimal connected ve -weight m -dominating set and $\gamma_{CVE}^S(G^S) = (c, 4)$. Clearly G^S is an edge regular graph with minimal S -value a . So any edge of G^S can not weight m -dominate some vertex of G^S , since it is not a vertex S -regular graph. Therefore there will be no ev -weight m -dominating set. Hence $\gamma_{EV}^S(G^S) = \gamma_{CEV}^S(G^S) = (a, 0)$. Hence we conclude that

$$\gamma_{EV}^S(G^S) \preceq \gamma_{CEV}^S(G^S) \preceq \gamma_{VE}^S(G^S) \preceq \gamma_{CVE}^S(G^S).$$

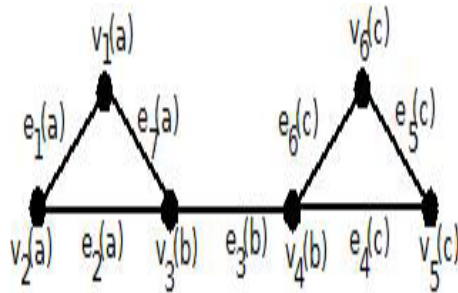
Remark 4.5. If G^S is not a vertex regular and not an edge regular graph, then

$$\gamma_{EV}^S(G^S) \preceq \gamma_{CEV}^S(G^S) \preceq \gamma_{VE}^S(G^S) \preceq \gamma_{CVE}^S(G^S).$$

We illustrate this in the following example.

Example 4.6. Let $(S = \{0, a, b, c\}, +, \cdot)$ be a semiring with the canonical preorder given in example 3.2

Consider the S -valued graph $G^S = (V, E, \sigma, \psi)$.



Clearly $D = \{v_3, v_4\}$ is the minimal ve -weight m -dominating set and $\gamma_{VE}^S(G^S) = (b, 2)$. Also $\langle D \rangle^S$ is connected. Hence D is a minimal connected ve -weight m -dominating set and $\gamma_{CVE}^S(G^S) = (b, 2)$. Clearly $T = \{e_3\}$ is the minimal ev -weight m -dominating set and $\gamma_{EV}^S(G^S) = (b, 1)$. Also $\langle T \rangle^S$ is connected. Hence T is a minimal connected ev -weight m -dominating set and $\gamma_{CEV}^S(G^S) = (b, 1)$. Hence we conclude that

$$\gamma_{EV}^S(G^S) \leq \gamma_{CEV}^S(G^S) \leq \gamma_{VE}^S(G^S) \leq \gamma_{CVE}^S(G^S).$$

Now we give the proof of the theorem 4.1.

Proof of Theorem 4.1:

Since every connected ve -weight m -dominating set is, by definition, a ve -weight m -dominating set, we have $\gamma_{VE}^S(G^S) \leq \gamma_{CVE}^S(G^S)$. Similarly every connected ev -weight m -dominating set is, by definition, a ev -weight m -dominating set, we have $\gamma_{EV}^S(G^S) \leq \gamma_{CEV}^S(G^S)$. To prove the theorem, it is enough to prove that $\gamma_{CEV}^S(G^S) \leq \gamma_{VE}^S(G^S)$. Let $D \subseteq V$ be a minimal ve -weight m -dominating set, so that

$$\gamma_{VE}^S(G^S) = (\sum_{v_i \in D} \sigma(v_i), |D|).$$

Let $T \subseteq E$ be a minimal connected ev -weight m -dominating set. For any $e \in T$, the end vertices will dominate the other edges. And T will have minimum number of edges of G^S that are connected whose end vertices will dominate other edges. In that way, the end vertices of the edges in T will be an element of D . However all these vertices need not dominate the edges not in T . For, let $f \in E$ such that $f \notin T$. If the end vertex of f dominate the edges that are in T , then there is nothing to prove. Otherwise, if the end vertex of f dominate the edges that are not in T , then those vertices will be in D . Hence we need more vertices which will dominate the edges that are not in T . Hence $|D| \geq |V(\langle T \rangle^S)|$. Therefore $\gamma_{VE}^S(G^S) \geq \gamma_{CEV}^S(G^S)$. ■

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