

## Conditional energy stability of the zero solution to the boundary-initial value problem

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### Abstract

In this paper we examine the stability of the zero solution to the boundary-initial value problem. In order to investigate the effect of a nonlinear term on the stability of a solution to a partial differential equation (PDE).

**AMS subject classification:**

**Keywords:** The energy method, stability of the solution.

### 1. Introduction

We apply the energy method to study the stability of the solution to the boundary-initial value problem,

$$u_t = u_{xx} + au^3 - \frac{1}{2}tu, \quad x \in (0, 1), \quad t > 0, \quad (1)$$

where  $a$  is a positive constant, suppose now (1) holds on the spatial region  $(0,1)$  with boundary conditions

$$u(0, t) = u(1, t) = 0 \quad (2)$$

and suppose we wish to investigate the behaviour of  $u$  subject to initial data

$$u(x, 0) = \varphi(x) \quad (3)$$

Even though we know  $u \equiv 0$  is a stable solution to (1), (3) we shall obtain this result directly using an energy method, choosing a problem to illustrate the technique.

Let now  $u$  be a solution to (1), (3) that satisfies arbitrary initial data  $\varphi(x)$ . We define an energy  $F(t)$  by

$$F(t) = \frac{1}{2} \int_0^1 u^2 \quad (4)$$

where  $\| \cdot \|$  denotes the norm on  $L^2(0, 1)$  more precisely,

$$\| u \|^2 = \int_0^1 u^2 dx.$$

Multiply the differential equation (1) by  $u$  and integrate over  $(0, 1)$  to find

$$\int_0^1 u_t u dx = \int_0^1 u u_{xx} dx + a \int_0^1 u^4 dx - \frac{1}{2} t \int_0^1 u^2 dx$$

by use of the Cauchy-Schwarz inequality. From the Sobolev embedding inequality we know that (see the [1])

$$\int_0^1 u^4 dx \leq \frac{1}{4} \left( \int_0^1 u_x^2 dx \right)^2. \quad (5)$$

Hence, with

$$E(t) = \frac{1}{2} \| u \|^2 \left( = \int_0^1 u^2 dx \right).$$

this equation becomes (after integration by parts as before)

$$\frac{d}{dt} E(t) \leq - \| u_x \|^2 + a \| u_x \|^4 - t E(t).$$

this equation becomes

$$\frac{d}{dt} F(t) \leq -a \| u_x \|^2 \left( \frac{1}{a} - \| u_x \|^2 \right). \quad (6)$$

Next, from Poincaré's inequality,  $\pi^2 \| u \|^2 \leq \| u_x \|^2$ . Now, use this in (0.6),

$$\frac{d}{dt} F(t) \leq -a\pi^2 \| u \|^2 \left( \frac{1}{a} - \pi^2 \| u \|^2 \right), \quad (7)$$

if  $0 < \frac{1}{a} - \pi^2 \| u \|^2 = \eta$  then

$$\frac{d}{dt} F(t) \leq -a\pi^2 \| u \|^2 \left( \frac{1}{a^{\frac{1}{2}}} - \pi \| u \| \right) \left( \frac{1}{a^{\frac{1}{2}}} + \pi \| u \| \right),$$

$$\frac{d}{dt} F(t) \leq -\eta a \pi^2 \| u \|^2, \quad (8)$$

so (0.8) shows

$$\frac{d}{dt} F(t) \leq 0, \text{ for } \epsilon < t \quad (9)$$

Hence,

$$\| u(t) \| \leq \| u(\epsilon) \|$$

with same consideration that we have

$$\frac{d}{dt} F(t) \leq -a\pi^2 \|u\|^2 \eta \tag{10}$$

Further,

$$\frac{dF}{F} \leq -c \frac{dt}{t}, \text{ where } c = 2a\pi^2\eta$$

we find

$$d \ln(F(t)) \leq d \ln(t^{-c}),$$

Using an integrating factor we may obtain from this inequality

$$\ln\left(\frac{F(t)}{F(\epsilon)}\right) \leq \ln\left(\frac{t^{-c}}{\epsilon^{-c}}\right),$$

Next,

$$F(t) \leq F(\epsilon) \times \frac{\epsilon^c}{t^c} \tag{11}$$

which in turn integrates to

$$\|u(t)\|^2 \leq 2 \frac{\epsilon^\gamma}{t^\gamma} \|u(\epsilon)\|^2, \text{ where } \gamma = c + 1. \tag{12}$$

What we have shown is that if  $\|u(\epsilon)\| < \frac{1}{2a}$ , then  $\|u(t)\| \rightarrow 0$  as  $t \rightarrow \infty$ . And the zero solution to (0.1), (0.3) is stable.

Again, the equation (0.4) becomes (after integration by parts as before)

$$\frac{d}{dt} E(t) \leq -\|u_x\|^2 + a \|u^2\|^2 - t E(t).$$

this equation becomes

$$\frac{d}{dt} F(t) \leq -\|u_x\|^2 + a \|u^2\|^2 .$$

$$\frac{d}{dt} F(t) \leq -a \|u_x\|^2 \left( \frac{1}{a} - \max_{S_{adm}} \frac{\|u^2\|^2}{\|u_x\|^2} \right)$$

where  $S_{adm}$  is the space of admissible functions over which we seek a maximum. Set

$$S_{adm} = \{u \in C^2 \mid u = 0 \text{ when } x = 0, 1\}.$$

Now define  $R_F$  by

$$\frac{1}{R_F} = \max_{S_{adm}} \frac{\|u^2\|^2}{\|u_x\|^2},$$

then the energy inequality (0.5) may be rewritten

$$\frac{d}{dt}F(t) \leq -a \|u_x\|^2 \left( \frac{1}{a} - \frac{1}{R_F} \right),$$

The problem remains to find  $R_F$ . Recall that

$$R_F^{-1} = \max_{S_{adm}} \frac{\|u^2\|^2}{\|u_x\|^2},$$

Let  $\Lambda_1 = \|u^2\|^2$ ,  $\Lambda_2 = \|u_x\|^2$ . The Euler–Lagrange equations are found from

$$\begin{aligned} \frac{d}{d\epsilon} \frac{\Lambda_1(u + \epsilon\tau)}{\Lambda_1(u_x + \epsilon\tau_x)} \Big|_{\epsilon=0} &= \delta \left( \frac{\Lambda_1}{\Lambda_2} \right), \\ &= \frac{\Lambda_2 \delta \Lambda_1 - \Lambda_1 \delta \Lambda_2}{\Lambda_2^2} \\ &= \frac{1}{\Lambda_2} \left( \delta \Lambda_1 - \frac{\Lambda_1}{\Lambda_2} \Big|_{\max} \delta \Lambda_2 \right) \\ &= \frac{1}{\Lambda_2} \left( \delta \Lambda_1 - \frac{1}{R_F} \delta \Lambda_2 \right) \end{aligned}$$

(Since  $\delta$  refers to the *derivative* evaluated at  $\epsilon = 0$ .  $\frac{\Lambda_1}{\Lambda_2}$  Is here understood to be at the stationary value.) Therefore,

$$\delta \Lambda_1 - \frac{1}{R_F} \delta \Lambda_2 = 0 \tag{13}$$

Here

$$\delta \Lambda_1 = \frac{d}{d\epsilon} \int_0^1 (u + \epsilon\tau)^4 dx \Big|_{\epsilon=0},$$

where  $\tau$  is an arbitrary  $C^2(0, 1)$  function with  $\tau(0) = \tau(1) = 0$ , and

$$\delta \Lambda_1 = \frac{d}{d\epsilon} \int_0^1 (u_x + \epsilon\tau_x)^2 dx \Big|_{\epsilon=0}.$$

So (0.13) leads to

$$\int_0^1 2u^3 \tau - R_F^{-1} u_x \tau_x dx = 0.$$

Integration by parts shows that

$$\int_0^1 (u_{xx} + 2R_F u^3) \tau dx = 0.$$

Since  $\tau$  is arbitrary apart from the continuity and boundary condition requirements, we must have

$$u_{xx} + 2R_F u^3 = 0, \quad u(0) = u(1) = 0 \tag{14}$$

We now examine Eq. (0.14) within the framework of a 2 – dim phase–space.

The second-order differential equation, given in Eq. (0.14), may be reformulated to two first-order system equations

$$\frac{du}{dx} = v, \quad \frac{dv}{dx} = -2R_F u^3$$

subject to initial conditions

$$u(0) = u(1) = 0$$

then

$$\frac{dv}{du} = -2R_F \frac{u^3}{v}.$$

In general, this is a first–order, nonlinear differential equation, whose solutions are the curves of the solution trajectories in phase-space.

## 2. The harmonic balance method

The method of harmonic balance provides a general technique for calculating approximations to the periodic solutions of differential equations. It corresponds to a truncated Fourier series and allows for the systematic determination of the coefficients to the various harmonics and the angular frequency.

We begin by calculating the first-order harmonic balance approximation to the periodic solutions of

$$\frac{dv}{du} = -2R_F \frac{u^3}{v}, \tag{15}$$

$$u(0) = 0, \quad v(0) = a. \tag{16}$$

This approximation takes the form

$$u_1 = a \sin(\omega_1 x),$$

Observe that this expression automatically satisfies the initial conditions. Substituting Eq. (1.1) into Eq. (1.2) gives  $(\theta = \omega_1 x - \frac{\pi}{2})$

$$-a\omega_1^2 \cos(\theta) + a^3 \alpha \cos^3(\theta) \simeq 0, \quad \alpha = 2R_F.$$

$$-a\omega_1^2 \cos(\theta) + a^3 \alpha \left( \frac{3}{4} \cos(\theta) + \frac{1}{4} \cos(3\theta) \right) \simeq 0.$$

$$\left( \frac{3}{4} a^3 \alpha - a\omega_1^2 \right) \cos(\theta) + \text{higher harmonic} \simeq 0.$$

Setting the coefficient of  $\cos(\theta)$  to zero gives the first–approximation to the angular frequency

$$\omega_1(a) = a\sqrt{\frac{3}{4}\alpha}.$$

and

$$u_1 = a \sin\left(a\sqrt{\frac{3}{4}\alpha}x\right),$$

where we have taken  $a = 1$ , since we are primarily interested in  $R_F$  not  $u$ . The condition  $u(1) = 0$  then shows that

$$\sqrt{\frac{3}{2}}R_F = n\pi, \quad n = \pm 1, \pm 2, \dots$$

This gives an infinite sequence of values for  $R_F$  (corresponding to stationary values of the quotient  $\frac{\|u^2\|^2}{\|u_x\|^2}$ ),

$$R_F = \frac{2}{3}\pi^2, \frac{8}{3}\pi^2, \dots$$

For stability, we need  $a < R_F(\min)$ , and so  $R_F = \frac{2}{3}\pi^2$ . In particular, therefore,

$$a < \frac{2}{3}\pi^2.$$

yields stability of the zero solution to (0.1), (0.3).

## References

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