

New System of a Parametric General Regularized Nonconvex Variational Inequalities in Banach Spaces

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Abstract

In this paper, we study the behaviour of solution sets for a new system of parametric general regularized nonconvex variational inequalities in q -uniformly smooth Banach spaces with locally relaxed (φ, ψ) -cocoercive mappings.

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1. Introduction

Sensitivity analysis for the solutions of variational inequalities and inclusions have been studied by many authors via quite different methods. By the projection methods, Anastassiou et al. [2], Balooee and Kim [3], Chang et al. [7], Dafermos [9], Faraj and Salahuddin [10], Khan and Salahuddin [13], Lee and Salahuddin [18], Mohapatra and Verma [20], Pan [22], Qiu and Magnanti [23], Salahuddin [25, 26], Verma [27], and Yen [28] studied the sensitivity analysis for the solutions of some variational inequalities with single-valued mappings or set-valued mappings in finite dimensional spaces, or Hilbert spaces. By using the resolvent operator techniques, Agarwal et al. [1], Jeong [11, 12], Kim et al. [14], and Kim and Kim [16, 17] studied a new system of parametric generalized mixed quasi variational inclusions in Hilbert spaces and in L_p ($p \geq 2$) spaces, respectively.

In this paper, we study the behaviour and sensitivity analysis of the solution set for a new system of parametric general regularized nonconvex variational inequalities with locally relaxed (φ, ψ) -cocoercive mappings in Banach spaces.

Let \mathcal{X} be a real Banach space with dual space \mathcal{X}^* , the norm $\|\cdot\|$ and a dual pairing $\langle \cdot, \cdot \rangle$ between \mathcal{X} and \mathcal{X}^* . Let $CB(\mathcal{X})$ denotes the family of all nonempty closed bounded subsets of \mathcal{X} and let $\mathfrak{D}(\cdot, \cdot)$ be the Hausdorff metric on $CB(\mathcal{X})$, that is, for all $A, B \in CB(\mathcal{X})$,

$$\mathfrak{D}(A, B) = \max \left\{ \sup_{x \in A} \inf_{y \in B} \|x - y\|, \sup_{y \in B} \inf_{x \in A} \|x - y\| \right\}.$$

The generalized duality mapping $J_q : \mathcal{X} \rightarrow 2^{\mathcal{X}^*}$ is defined by

$$J_q(x) = \{f^* \in \mathcal{X}^* : \langle x, f^* \rangle = \|x\|^q, \|f^*\| = \|x\|^{q-1}\}, \quad \forall x \in \mathcal{X}$$

where $q > 1$ is a constant. In particular, J_2 is a usual normalized duality mapping. It is known that in general $J_q(x) = \|x\|^{q-2} J_2(x)$ for all $x \neq 0$ and J_q is single-valued if \mathcal{X}^* is strictly convex.

In the sequel, we always assume that \mathcal{X} is a real Banach space such that J_q is single-valued. If \mathcal{X} is a Hilbert space, then J_q becomes the identity mapping on \mathcal{X} . The modulus of smoothness of \mathcal{X} is the function $\rho_{\mathcal{X}} : [0, \infty) \rightarrow [0, \infty)$ defined by

$$\rho_{\mathcal{X}}(t) = \sup \left\{ \frac{1}{2} (\|x + y\| + \|x - y\|) - 1 : \|x\| \leq 1, \|y\| \leq t \right\}.$$

A Banach space \mathcal{X} is called uniformly smooth if

$$\lim_{t \rightarrow 0} \frac{\rho_{\mathcal{X}}(t)}{t} = 0.$$

\mathcal{X} is called q -uniformly smooth if there exists a constant $c > 0$ such that

$$\rho_{\mathcal{X}}(t) < ct^q, \quad q > 1.$$

Note that J_q is single-valued if \mathcal{X} is uniformly smooth. Concerned with the characteristic inequalities in q -uniformly smooth Banach spaces. Xu [29] proved the following results.

Lemma 1.1. [29] The real Banach space \mathcal{X} is q -uniformly smooth if and only if there exists a constant $c_q > 0$ such that for all $x, y \in \mathcal{X}$

$$\|x + y\|^q \leq \|x\|^q + q\langle y, J_q(x) \rangle + c_q\|y\|^q.$$

Definition 1.2. Let \mathcal{K} be a nonempty closed subset of a Banach space \mathcal{X} . The proximal normal cone of \mathcal{K} at a point $u \in \mathcal{X}$ with $u \notin \mathcal{K}$ is given by

$$N_{\mathcal{K}}^P(u) = \{\zeta \in \mathcal{X} : u \in P_{\mathcal{K}}(u + \alpha\zeta) \text{ for some } \alpha > 0\},$$

where

$$P_{\mathcal{K}}(u) = \{v \in \mathcal{K} : d_{\mathcal{K}}(u) = \|u - v\|\}.$$

Here $d_{\mathcal{K}}(\cdot)$ is the usual distance function to the subset \mathcal{K} , i.e.,

$$d_{\mathcal{K}}(u) = \inf_{v \in \mathcal{K}} \|u - v\|.$$

We have the characterizations for the proximal normal cone $N_{\mathcal{K}}^P(u)$.

Lemma 1.3. [8] Let \mathcal{K} be a nonempty closed subset in \mathcal{X} . Then $\zeta \in N_{\mathcal{K}}^P(u)$ if and only if there exists a constant $\alpha = \alpha(\zeta, u) > 0$ such that

$$\langle \zeta, j_q(v - u) \rangle \leq \alpha\|v - u\|^q, \quad \forall v \in \mathcal{K}.$$

Lemma 1.4. [8] Let \mathcal{K} be a nonempty closed and convex subset in \mathcal{X} . Then $\zeta \in N_{\mathcal{K}}^P(u)$ if and only if

$$\langle \zeta, j_q(v - u) \rangle \leq 0, \quad \forall v \in \mathcal{K}.$$

The Clarke normal cone $N_{\mathcal{K}}^C(u)$ is defined by

$$N_{\mathcal{K}}^C(u) = \overline{\text{co}}\{N_{\mathcal{K}}^P(u)\},$$

where $\overline{\text{co}}$ is the closure of the convex hull. Clearly $N_{\mathcal{K}}^P(u) \subseteq N_{\mathcal{K}}^C(u)$, but the converse is not true in general. Note that $N_{\mathcal{K}}^C(u)$ is always closed and convex whereas $N_{\mathcal{K}}^P(u)$ is always convex but may not be closed (see [4, 5, 6, 8, 24]).

Definition 1.5. [8, 24] For any $r \in (0, +\infty]$, a subset \mathcal{K}_r of \mathcal{X} is said to be normalized uniformly r -prox regular (or uniformly r -prox regular) if and only if every nonzero proximal normal to \mathcal{K}_r can be realized by an r -ball, that is, for all $u \in \mathcal{K}_r$ and all $0 \neq \zeta \in N_{\mathcal{K}_r}^P(u)$ with $\|\zeta\| = 1$,

$$\langle \zeta, v - u \rangle \leq \frac{1}{2r}\|v - u\|^2, \quad v \in \mathcal{K}_r.$$

Lemma 1.6. [8] A closed set $\mathcal{K} \subseteq \mathcal{X}$ is convex if and only if it is proximally smooth of radius r for every $r > 0$.

If $r = \infty$ then uniformly prox regularity of \mathcal{K}_r is equivalent to the convexity of \mathcal{K} . If \mathcal{K}_r is a uniformly prox regular set, then the proximal normal cone $N_{\mathcal{K}_r}^P(u)$ is closed as a set-valued mapping. If we take $\eta = \frac{1}{2r}$, it is clear that $r \rightarrow \infty$ then $\eta = 0$.

Proposition 1.7. [24] Let $r > 0$ and \mathcal{K}_r be a nonempty closed and uniformly r -prox regular subset of \mathcal{X} . Set

$$\mathcal{U}(r) = \{u \in \mathcal{X} : 0 \leq d_{\mathcal{K}_r}(u) < r\}.$$

Then the following statements hold.

- (i) For all $u \in \mathcal{K}_r$, we have $P_{\mathcal{K}_r}(u) \neq \emptyset$;
- (ii) For all $r' \in (0, r)$, $P_{\mathcal{K}_r}$ is a Lipschitz continuous mapping with constant $\delta = \frac{r}{r - r'}$ on $\mathcal{U}(r') = \{u \in \mathcal{X} : 0 \leq d_{\mathcal{K}_r}(u) < r'\}$;
- (iii) The proximal normal cone is closed as a set-valued mapping.

2. Sensitivity Analysis of Solution Sets

Now we consider a system of parametric general regularized nonconvex variational inequalities in a q -uniformly smooth Banach space \mathcal{X} . Let Ω and \wedge be two nonempty open subsets of \mathcal{X} in which the parameter λ and η take values, respectively. Let $h : \Omega \times \mathcal{X} \rightarrow \mathcal{X}$, $p : \wedge \times \mathcal{X} \rightarrow \mathcal{X}$ are single-valued mappings and $T : \wedge \times \mathcal{X} \rightarrow 2^{\mathcal{X}}$, $G : \Omega \times \mathcal{X} \rightarrow 2^{\mathcal{X}}$ be the set-valued mappings. For any constants $\rho > 0$ and $\mu > 0$, we consider the problem of finding $(u, v) \in \mathcal{X} \times \mathcal{X}$ and $x \in T(u, \eta)$, $y \in G(v, \lambda)$ such that $h(u, \lambda), p(v, \eta) \in \mathcal{K}_r$ and for all $(u, \lambda) \in \mathcal{X} \times \Omega$, $(v, \eta) \in \mathcal{X} \times \wedge$, $u^*, v^* \in \mathcal{K}_r$,

$$\begin{aligned} \langle \rho U(u, y, \lambda) + h(u, \lambda) - u, u^* - h(u, \lambda) \rangle + \frac{1}{2r} \|u^* - h(u, \lambda)\|^2 &\geq 0, \\ \langle \mu V(x, v, \eta) + p(v, \eta) - v, v^* - p(v, \eta) \rangle + \frac{1}{2r} \|v^* - p(v, \eta)\|^2 &\geq 0, \end{aligned} \quad (1)$$

where $U : \mathcal{X} \times \mathcal{X} \times \Omega \rightarrow \mathcal{X}$ and $V : \mathcal{X} \times \mathcal{X} \times \wedge \rightarrow \mathcal{X}$. The problem (1) is called a system of parametric general regularized nonconvex variational inequalities.

Definition 2.1. Let $h : \mathcal{X} \times \Omega \rightarrow \mathcal{X}$ be an operator. Then the operator $h(\cdot, \lambda)$ is said to be

- (i) locally α_h -strongly accretive if there exists a constant $\alpha_h > 0$ such that for all $\lambda \in \Omega$, $u, v \in \mathcal{X}$,

$$\langle h(u, \lambda) - h(v, \lambda), j_q(u - v) \rangle \geq \alpha_h \|u - v\|^q,$$

- (ii) locally β_h -Lipschitz continuous if there exists a constant $\beta_h > 0$ such that for all $\lambda \in \Omega, u, v \in \mathcal{X}$,

$$\|h(u, \lambda) - h(v, \lambda)\| \leq \beta_h \|u - v\|,$$

- (iii) locally α_h -relaxed accretive if there exists a constant $\alpha_h > 0$ such that for all $\lambda \in \Omega, u, v \in \mathcal{X}$,

$$\langle h(u, \lambda) - h(v, \lambda), j_q(u - v) \rangle \geq -\alpha_h \|u - v\|^q.$$

Definition 2.2. A single-valued mapping $U : \mathcal{X} \times \mathcal{X} \times \Omega \rightarrow \mathcal{X}$ is said to be

- (i) locally relaxed (φ_U, ψ_U) -cocoercive with respect to the first variable of U if there exist the constants $\varphi_U > 0$ and $\psi_U > 0$ such that for all $u_1, u_2, v \in \mathcal{X}, \lambda \in \Omega$,

$$\begin{aligned} \langle U(u_1, v, \lambda) - U(u_2, v, \lambda), j_q(u_1 - u_2) \rangle &\geq -\varphi_U \|U(u_1, v, \lambda) - U(u_2, v, \lambda)\|^q \\ &\quad + \psi_U \|u_1 - u_2\|^q, \end{aligned}$$

- (ii) locally ζ_U -Lipschitz continuous with respect to the first variable of U if there exists a constant $\zeta_U > 0$ such that for all $u_1, u_2, v \in \mathcal{X}, \lambda \in \Omega$,

$$\|U(u_1, v, \lambda) - U(u_2, v, \lambda)\| \leq \zeta_U \|u_1 - u_2\|,$$

- (iii) locally κ_U -Lipschitz continuous with respect to the second variable of U if there exists a constant $\kappa_U > 0$ such that for all $v_1, v_2, u \in \mathcal{X}, \lambda \in \Omega$,

$$\|U(u, v_1, \lambda) - U(u, v_2, \lambda)\| \leq \kappa_U \|v_1 - v_2\|.$$

Similarly we can define the locally relaxed (φ_V, ψ_V) -cocoercivity and locally ζ_V -Lipschitz continuity of V .

Definition 2.3. Let $G : \mathcal{X} \times \Omega \rightarrow 2^{\mathcal{X}}$ be a set-valued mapping. Then G is called locally $\xi_G - \mathfrak{D}$ -Lipschitz continuous in the first argument if there exists a constant $\xi_G > 0$ such that for all $u, v \in \mathcal{X}, \lambda \in \Omega$,

$$\mathfrak{D}(G(u, \lambda), G(v, \lambda)) \leq \xi_G \|u - v\|,$$

where $\mathfrak{D} : 2^{\mathcal{X}} \times 2^{\mathcal{X}} \rightarrow (-\infty, +\infty) \cup \{+\infty\}$ is the Hausdorff metric *i.e.*, for all $A, B \in 2^{\mathcal{X}}$,

$$\mathfrak{D}(A, B) = \max \left\{ \sup_{u \in A} \inf_{v \in B} \|u - v\|, \sup_{u \in B} \inf_{v \in A} \|u - v\| \right\}.$$

Lemma 2.4. [19] Let (\mathcal{X}, d) be a complete metric space and $T_1, T_2 : \mathcal{X} \rightarrow CB(\mathcal{X})$ be two set-valued contraction mappings with the same constant $\theta \in (0, 1)$ *i.e.*,

$$\mathfrak{D}(T_i(u), T_i(v)) \leq \theta d(u, v), \forall u, v \in \mathcal{X}, i = 1, 2.$$

Then

$$\mathfrak{D}(F(T_1), F(T_2)) \leq \frac{1}{1-\theta} \sup_{u \in \mathcal{X}} \mathfrak{D}(T_1(u), T_2(v)),$$

where $F(T_1)$ and $F(T_2)$ are fixed point sets of T_1, T_2 , respectively.

Lemma 2.5. If \mathcal{K}_r is a uniformly r -prox regular set, then problem (1) is equivalent to that of finding $(\lambda, \eta) \in \Omega \times \Lambda, (u, v) \in \mathcal{X} \times \mathcal{X}, x \in T(u, \eta), y \in G(v, \lambda)$ such that $h(u, \lambda), p(v, \eta) \in \mathcal{K}_r$ and

$$\begin{aligned} 0 &\in \rho U(u, y, \lambda) + h(u, \lambda) - u + N_{\mathcal{K}_r}^P(h(u, \lambda)), \\ 0 &\in \mu V(x, v, \eta) + p(v, \eta) - v + N_{\mathcal{K}_r}^P(p(v, \eta)), \end{aligned} \quad (2)$$

where $N_{\mathcal{K}_r}^P(s)$ denotes the P -normal cone of \mathcal{K}_r at s in the sense of nonconvex analysis.

Lemma 2.6. Let $U : \mathcal{X} \times \mathcal{X} \times \Omega \rightarrow \mathcal{X}$ and $V : \mathcal{X} \times \mathcal{X} \times \Lambda \rightarrow \mathcal{X}$ be two mappings. Let $h : \Omega \times \mathcal{X} \rightarrow \mathcal{X}, p : \mathcal{X} \times \Lambda \rightarrow \mathcal{X}$ be the single-valued mappings and let $T : \Lambda \times \mathcal{X} \rightarrow 2^{\mathcal{X}}, G : \Omega \times \mathcal{X} \rightarrow 2^{\mathcal{X}}$ be the set-valued mappings. Then (u, v, x, y) with $u, v \in \mathcal{X}, h(u, \lambda) \in \mathcal{K}_r$ and $x \in T(u, \eta), y \in G(v, \eta)$ is a solution of system (2) if and only if

$$\begin{aligned} h(u, \lambda) &= P_{\mathcal{K}_r}(u - \rho U(u, y, \lambda)), \\ p(v, \eta) &= P_{\mathcal{K}_r}(v - \mu V(x, v, \eta)), \end{aligned} \quad (3)$$

where $P_{\mathcal{K}_r}$ is the projection of \mathcal{X} on the uniformly r -prox regular set \mathcal{K}_r and $\rho, \mu > 0$ on $(\lambda, \eta) \in \Omega \times \Lambda$.

Theorem 2.7. Let $U : \mathcal{X} \times \mathcal{X} \times \Omega \rightarrow \mathcal{X}$ and $V : \mathcal{X} \times \mathcal{X} \times \Lambda \rightarrow \mathcal{X}$ be two mappings. Let $h : \Omega \times \mathcal{X} \rightarrow \mathcal{X}, p : \mathcal{X} \times \Lambda \rightarrow \mathcal{X}$ be the single-valued mappings and let $T : \Lambda \times \mathcal{X} \rightarrow 2^{\mathcal{X}}, G : \Omega \times \mathcal{X} \rightarrow 2^{\mathcal{X}}$ be the set-valued mappings. Assume that the mappings satisfy the following conditions:

- (i) U is a locally relaxed (φ_U, ψ_U) -cocoercive mapping with respect to the first variable of U with constants $\varphi_U, \psi_U > 0$, respectively;
- (ii) U is a locally ζ_U -Lipschitz continuous with respect to the first variable of U with constant $\zeta_U > 0$ and locally κ_U -Lipschitz continuous mapping with respect to the second variable of U with constant $\kappa_U > 0$;
- (iii) V is a locally relaxed (φ_V, ψ_V) -cocoercive mapping with respect to the second variable of V with constants $\varphi_V, \psi_V > 0$, respectively;
- (iv) V is a locally ζ_V -Lipschitz continuous with respect to the first variable of V with constant $\zeta_V > 0$ and locally κ_V -Lipschitz continuous mapping with respect to the second variable of V with constant $\kappa_V > 0$;
- (v) T is a locally $\vartheta_T - \mathfrak{D}$ -Lipschitz continuous mapping with constant $\vartheta_T > 0$;

- (vi) G is a locally $\vartheta_G - \mathfrak{D}$ -Lipschitz continuous mapping with constant $\vartheta_G > 0$;
- (vii) h is a locally α_h -strongly accretive with respect to constant $\alpha_h > 0$ and locally β_h -Lipschitz continuous mapping with constant $\beta_h > 0$;
- (viii) p is a locally α_p -relaxed accretive and locally β_p -Lipschitz continuous mapping with constants $\alpha_p > 0$ and $\beta_p > 0$, respectively.

If the constants $\rho > 0$ and $\mu > 0$ satisfy the following conditions:

$$\begin{aligned}\pi_h &= \sqrt[q]{1 - q\alpha_h + \beta_h^q}, \quad \pi_p = \sqrt[q]{1 + q\alpha_p + \beta_p^q}, \\ \sigma_1 &= 1 - \pi_h + \delta\mu\zeta_V\vartheta_T, \quad \sigma_2 = 1 - \pi_p + \delta\rho\kappa_U\vartheta_G, \\ \sqrt[q]{1 - q\rho(\psi_U - \varphi_U\zeta_U^q) + c_q\rho^q\zeta_U^q} &< \sigma_1\delta^{-1}, \\ \sqrt[q]{1 - q\mu(\psi_V - \varphi_V\kappa_V^q) + c_q\mu^q\kappa_V^q} &< \sigma_2\delta^{-1},\end{aligned}\tag{4}$$

where $r' \in (0, r)$, then for each $(\lambda, \eta) \in \Omega \times \wedge$, the system of parametric general regularized nonconvex variational inequalities (1) has a nonempty solution set $S(\lambda, \eta)$ which is a closed subset of $\mathcal{X} \times \mathcal{X}$.

Proof. From (3) we define $F_1 : \mathcal{X} \times \mathcal{X} \times \mathcal{X} \times \Omega \rightarrow \mathcal{X}$, $F_2 : \mathcal{X} \times \mathcal{X} \times \mathcal{X} \times \wedge \rightarrow \mathcal{X}$ as for all $(u, v, \lambda, \eta) \in \mathcal{X} \times \mathcal{X} \times \Omega \times \wedge$, $x \in T(u, \eta)$, $y \in G(v, \lambda)$,

$$\begin{aligned}F_1(u, v, y, \lambda) &= u - h(u, \lambda) + P_{\mathcal{K}_r}(u - \rho U(u, y, \lambda)), \\ F_2(u, v, x, \eta) &= v - p(v, \eta) + P_{\mathcal{K}_r}(v - \mu V(x, v, \eta)).\end{aligned}\tag{5}$$

Now we define $\|\cdot\|_1$ on $\mathcal{X} \times \mathcal{X}$ by

$$\|(u, v)\|_1 = \|u\| + \|v\|, \quad \forall (u, v) \in \mathcal{X} \times \mathcal{X}.$$

Then we know that $(\mathcal{X} \times \mathcal{X}, \|\cdot\|_1)$ is a Banach space. And also, for any $\rho > 0$, $\mu > 0$, we can define $F : \mathcal{X} \times \mathcal{X} \times \Omega \times \wedge \rightarrow 2^{\mathcal{X}} \times 2^{\mathcal{X}}$ by

$$F(u, v, \lambda, \eta) = \{(F_1(u, v, y, \lambda), F_2(u, v, x, \eta)) : x \in T(u, \eta), y \in G(v, \lambda)\}$$

for every $(u, v, \lambda, \eta) \in \mathcal{X} \times \mathcal{X} \times \Omega \times \wedge$. Since $T(u, \eta) \in CB(\mathcal{X})$, $G(v, \lambda) \in CB(\mathcal{X})$ and $h, p, P_{\mathcal{K}_r}$ are continuous mappings, we have

$$F(u, v, \lambda, \eta) \in CB(\mathcal{X} \times \mathcal{X}), \quad \text{for every } (u, v, \lambda, \eta) \in \mathcal{X} \times \mathcal{X} \times \Omega \times \wedge.$$

Now for each $(\lambda, \eta) \in \Omega \times \wedge$, we prove that $F(u, v, \lambda, \eta)$ is a multi-valued contractive mapping. In fact for any $(u_1, v_1, \lambda, \eta), (u_2, v_2, \lambda, \eta) \in \mathcal{X} \times \mathcal{X} \times \Omega \times \wedge$ and $(a_1, a_2) \in F(u_1, v_1, \lambda, \eta)$ there exists $x_1 \in T(u_1, \eta)$, $y_1 \in G(v_1, \lambda)$ such that

$$a_1 = u_1 - h(u_1, \lambda) + P_{\mathcal{K}_r}(u_1 - \rho U(u_1, y_1, \lambda)),$$

$$a_2 = v_1 - p(v_1, \eta) + P_{\mathcal{K}_r}(v_1 - \mu V(x_1, v_1, \eta)).$$

From the Nadler Theorem [21], there exists $x_2 \in T(u_2, \eta)$, $y_2 \in G(v_2, \lambda)$ such that

$$\begin{aligned} \|x_1 - x_2\| &\leq \mathfrak{D}(T(u_1, \eta), T(u_2, \eta)), \\ \|y_1 - y_2\| &\leq \mathfrak{D}(G(v_1, \lambda), G(v_2, \lambda)). \end{aligned} \quad (6)$$

Let

$$\begin{aligned} b_1 &= u_2 - h(u_2, \lambda) + P_{\mathcal{K}_r}(u_2 - \rho U(u_2, y_2, \lambda)), \\ b_2 &= v_2 - p(v_2, \eta) + P_{\mathcal{K}_r}(v_2 - \mu V(x_2, v_2, \eta)). \end{aligned}$$

Then we have $(b_1, b_2) \in F(u_2, v_2, \lambda, \eta)$. Therefore, from Proposition 1.7, we have

$$\begin{aligned} \|a_1 - b_1\| &\leq \|u_1 - u_2 - (h(u_1, \lambda) - h(u_2, \lambda))\| \\ &\quad + \|P_{\mathcal{K}_r}(u_1 - \rho U(u_1, y_1, \lambda)) - P_{\mathcal{K}_r}(u_2 - \rho U(u_2, y_2, \lambda))\| \\ &\leq \|u_1 - u_2 - (h(u_1, \lambda) - h(u_2, \lambda))\| \\ &\quad + \delta \|u_1 - u_2 - \rho(U(u_1, y_1, \lambda) - U(u_2, y_2, \lambda))\| \\ &\leq \|u_1 - u_2 - (h(u_1, \lambda) - h(u_2, \lambda))\| \\ &\quad + \delta \|u_1 - u_2 - \rho(U(u_1, y_1, \lambda) - U(u_2, y_1, \lambda))\| \\ &\quad + \rho \|U(u_2, y_1, \lambda) - U(u_2, y_2, \lambda)\| \end{aligned} \quad (7)$$

and

$$\begin{aligned} \|a_2 - b_2\| &\leq \|v_1 - v_2 - (p(v_1, \eta) - p(v_2, \eta))\| \\ &\quad + \|P_{\mathcal{K}_r}(v_1 - \mu V(x_1, v_1, \eta)) - P_{\mathcal{K}_r}(v_2 - \mu V(x_2, v_2, \eta))\| \\ &\leq \|v_1 - v_2 - (p(v_1, \eta) - p(v_2, \eta))\| \\ &\quad + \delta \|v_1 - v_2 - \mu(V(x_1, v_1, \eta) - V(x_2, v_2, \eta))\| \\ &\leq \|v_1 - v_2 - (p(v_1, \eta) - p(v_2, \eta))\| \\ &\quad + \delta \|v_1 - v_2 - \mu(V(x_1, v_1, \eta) - V(x_1, v_2, \eta))\| \\ &\quad + \mu \|V(x_1, v_2, \eta) - V(x_2, v_2, \eta)\|. \end{aligned} \quad (8)$$

Since h is a locally α_h -strongly accretive and locally β_h -Lipschitz continuous mapping with constants $\alpha_h > 0$ and $\beta_h > 0$ respectively, we have

$$\begin{aligned} &\|u_1 - u_2 - (h(u_1, \lambda) - h(u_2, \lambda))\|^q \\ &\leq \|u_1 - u_2\|^q - q \langle h(u_1, \lambda) - h(u_2, \lambda), j_q(u_1 - u_2) \rangle + c_q \|h(u_1, \lambda) - h(u_2, \lambda)\|^q \\ &\leq \|u_1 - u_2\|^q - q \alpha_h \|u_1 - u_2\|^q + c_q \beta_h^q \|u_1 - u_2\|^q \\ &\leq (1 - q \alpha_h + c_q \beta_h^q) \|u_1 - u_2\|^q. \end{aligned} \quad (9)$$

Similarly, since p is a locally α_p -relaxed accretive with respect to constant $\alpha_p > 0$ and locally β_p -Lipschitz continuous mapping with respect to constant $\beta_p > 0$, we have

$$\begin{aligned}
 & \|v_1 - v_2 - (p(v_1, \eta) - p(v_2, \eta))\|^q \\
 & \leq \|v_1 - v_2\|^q - q \langle p(v_1, \eta) - p(v_2, \eta), j_q(v_1 - v_2) \rangle + c_q \|p(v_1, \eta) - p(v_2, \eta)\|^q \\
 & \leq \|v_1 - v_2\|^q + q\alpha_p \|v_1 - v_2\|^q + c_q \beta_p^q \|v_1 - v_2\|^q \\
 & \leq (1 + q\alpha_p + c_q \beta_p^q) \|v_1 - v_2\|^q.
 \end{aligned} \tag{10}$$

Since U is a locally κ_U -Lipschitz continuous mapping with respect to the second variable with constant $\kappa_U > 0$ and G is a locally $\vartheta_G - \mathfrak{D}$ -Lipschitz continuous mapping with constant $\vartheta_G > 0$, we have

$$\begin{aligned}
 \|U(u_2, y_1, \lambda) - U(u_2, y_2, \lambda)\| & \leq \kappa_U \|y_1 - y_2\| \\
 & \leq \kappa_U \mathfrak{D}(G(v_1, \lambda) - G(v_2, \lambda)) \\
 & \leq \kappa_U \vartheta_G \|v_1 - v_2\|.
 \end{aligned} \tag{11}$$

Since V is a locally ζ_V -Lipschitz continuous mapping with respect to the first variable with constant $\zeta_V > 0$ and T is a locally $\vartheta_T - \mathfrak{D}$ -Lipschitz continuous mapping with constant $\vartheta_T > 0$, we have

$$\begin{aligned}
 \|V(x_1, v_2, \eta) - V(x_2, v_2, \eta)\| & \leq \zeta_V \|x_1 - x_2\| \\
 & \leq \zeta_V \mathfrak{D}(T(u_1, \eta) - T(u_2, \eta)) \\
 & \leq \zeta_V \vartheta_T \|u_1 - u_2\|.
 \end{aligned} \tag{12}$$

Since U is a locally relaxed (φ_U, ψ_U) -cocoercive mapping with respect to the first variable with constants $\varphi_U > 0$ and $\psi_U > 0$, respectively, we have

$$\begin{aligned}
 & \|u_1 - u_2 - \rho(U(u_1, y_1, \lambda) - U(u_2, y_1, \lambda))\|^q \\
 & \leq \|u_1 - u_2\|^q - q\rho \langle U(u_1, y_1, \lambda) - U(u_2, y_1, \lambda), j_q(u_1 - u_2) \rangle \\
 & \quad + c_q \rho^q \|U(u_1, y_1, \lambda) - U(u_2, y_1, \lambda)\|^q \\
 & \leq \|u_1 - u_2\|^q - q\rho(-\varphi_U \|U(u_1, y_1, \lambda) - U(u_2, y_1, \lambda)\|^q + \psi_U \|u_1 - u_2\|^q) \\
 & \quad + c_q \rho^q \zeta_U^q \|u_1 - u_2\|^q \\
 & \leq \|u_1 - u_2\|^q - q\rho(-\varphi_U \zeta_U^q \|u_1 - u_2\|^q + \psi_U \|u_1 - u_2\|^q) + c_q \rho^q \zeta_U^q \|u_1 - u_2\|^q \\
 & \leq (1 + q\rho\varphi_U \zeta_U^q - q\rho\psi_U + c_q \rho^q \zeta_U^q) \|u_1 - u_2\|^q.
 \end{aligned} \tag{13}$$

Since V is a locally relaxed (φ_V, ψ_V) -cocoercive mapping with respect to the second

variable with constants $\varphi_V > 0$ and $\psi_V > 0$, respectively, we have

$$\begin{aligned}
& \|v_1 - v_2 - \mu(V(x_1, v_1, \eta) - V(x_1, v_2, \eta))\|^q \\
& \leq \|v_1 - v_2\|^q - q\mu \langle V(x_1, v_1, \eta) - V(x_1, v_2, \eta), j_q(v_1 - v_2) \rangle \\
& \quad + c_q \mu^q \|V(x_1, v_1, \eta) - V(x_1, v_2, \eta)\|^q \\
& \leq \|v_1 - v_2\|^q - q\mu(-\varphi_V \|V(x_1, v_1, \eta) - V(x_1, v_2, \eta)\|^q + \psi_V \|v_1 - v_2\|^q) \\
& \quad + c_q \mu^q \kappa_V^q \|v_1 - v_2\|^q \\
& \leq \|v_1 - v_2\|^q - q\mu(-\varphi_V \kappa_V^q \|v_1 - v_2\|^q + \psi_V \|v_1 - v_2\|^q) + c_q \mu^q \kappa_V^q \|v_1 - v_2\|^q \\
& \leq (1 + q\mu\varphi_V \kappa_V^q - q\mu\psi_V + c_q \mu^q \kappa_V^q) \|v_1 - v_2\|^q.
\end{aligned} \tag{14}$$

It follows from (7), (9), (11) and (13) that

$$\begin{aligned}
\|a_1 - b_1\| & \leq \sqrt[q]{1 - q\alpha_h + c_q \beta_h^q} \|u_1 - u_2\| \\
& \quad + \delta \sqrt[q]{1 - q\rho(\psi_U - \varphi_U \zeta_U^q) + c_q \rho^q \zeta_U^q} \|u_1 - u_2\| \\
& \quad + \delta \rho \kappa_U \vartheta_G \|v_1 - v_2\| \\
& = \left[\sqrt[q]{1 - q\alpha_h + c_q \beta_h^q} + \delta \sqrt[q]{1 - q\rho(\psi_U - \varphi_U \zeta_U^q) + c_q \rho^q \zeta_U^q} \right] \|u_1 - u_2\| \\
& \quad + \delta \rho \kappa_U \vartheta_G \|v_1 - v_2\| \\
& \leq \theta_1 \|u_1 - u_2\| + \theta_2 \|v_1 - v_2\|
\end{aligned} \tag{15}$$

and

$$\begin{aligned}
\|a_2 - b_2\| & \leq \sqrt[q]{1 + q\alpha_p + c_q \beta_p^q} \|v_1 - v_2\| \\
& \quad + \delta \sqrt[q]{1 - q\mu(\psi_V - \varphi_V \kappa_V^q) + c_q \mu^q \kappa_V^q} \|v_1 - v_2\| \\
& \quad + \delta \mu \zeta_V \vartheta_T \|u_1 - u_2\| \\
& \leq \left[\sqrt[q]{1 + q\alpha_p + c_q \beta_p^q} + \delta \sqrt[q]{1 - q\mu(\psi_V - \varphi_V \kappa_V^q) + c_q \mu^q \kappa_V^q} \right] \|v_1 - v_2\| \\
& \quad + \delta \mu \zeta_V \vartheta_T \|u_1 - u_2\| \\
& \leq \theta_3 \|u_1 - u_2\| + \theta_4 \|v_1 - v_2\|,
\end{aligned} \tag{16}$$

where $\theta_1 = \sqrt[q]{1 - q\alpha_h + c_q \beta_h^q} + \delta \sqrt[q]{1 - q\rho(\psi_U - \varphi_U \zeta_U^q) + c_q \rho^q \zeta_U^q}$,

$$\theta_2 = \delta \rho \kappa_U \vartheta_G, \quad \theta_3 = \delta \mu \zeta_V \vartheta_T,$$

$$\theta_4 = \sqrt[q]{1 + q\alpha_p + c_q \beta_p^q} + \delta \sqrt[q]{1 - q\mu(\psi_V - \varphi_V \kappa_V^q) + c_q \mu^q \kappa_V^q}.$$

By (15) and (16), we have

$$\|a_1 - b_1\| + \|a_2 - b_2\| \leq \theta(\|u_1 - u_2\| + \|v_1 - v_2\|), \tag{17}$$

where $\theta = \max\{\theta_1 + \theta_3, \theta_2 + \theta_4\}$. Hence, we have

$$\begin{aligned} d((a_1, a_2), F(u_2, v_2, \lambda, \eta)) &= \inf_{(b_1, b_2) \in F(u_2, v_2, \lambda, \eta)} \left(\|a_1 - b_1\| + \|a_2 - b_2\| \right) \\ &\leq \theta(\|u_1 - u_2\| + \|v_1 - v_2\|) \\ &= \theta\|(u_1, v_1) - (u_2, v_2)\|_1 \end{aligned}$$

and

$$d((b_1, b_2), F(u_1, v_1, \lambda, \eta)) \leq \theta\|(u_1, v_1) - (u_2, v_2)\|_1.$$

From the definition of Hausdorff metric \mathfrak{D} on $CB(\mathcal{X} \times \mathcal{X})$, we have, for all $u_1, u_2, v_1, v_2 \in \mathcal{X}$ and $(\lambda, \eta) \in \Omega \times \Lambda$,

$$\begin{aligned} &\mathfrak{D}(F(u_1, v_1, \lambda, \eta), F(u_2, v_2, \lambda, \eta)) \\ &= \max \left\{ \sup_{(a_1, a_2) \in F(u_1, v_1, \lambda, \eta)} d((a_1, a_2), F(u_2, v_2, \lambda, \eta)), \right. \\ &\quad \left. \sup_{(b_1, b_2) \in F(u_2, v_2, \lambda, \eta)} d((b_1, b_2), F(u_1, v_1, \lambda, \eta)) \right\} \\ &\leq \theta\|(u_1, v_1) - (u_2, v_2)\|_1. \end{aligned} \tag{18}$$

We know that $\theta < 1$ from condition (4). Thus (18) implies that F is a contractive mapping which is uniform with respect to $(\lambda, \eta) \in \Omega \times \Lambda$. By the Nadler fixed point Theorem [21], $F(u, v, \lambda, \eta)$ has a fixed point (\bar{u}, \bar{v}) for each $(\lambda, \eta) \in \Omega \times \Lambda$. From the definition of F there exist $\bar{x} \in T(\bar{u}, \eta)$ and $\bar{y} \in G(\bar{v}, \lambda)$ such that (3) holds. By Lemma 2.6, $S(\lambda, \eta) \neq \emptyset$.

Now we have to prove that $S(\lambda, \eta)$ is closed. In fact, for each $(\lambda, \eta) \in \Omega \times \Lambda$, let $(u_n, v_n) \in S(\lambda, \eta)$ and $u_n \rightarrow u_0, v_n \rightarrow v_0$ as $n \rightarrow \infty$. Then we have

$$(u_n, v_n) \in F(u_n, v_n, \lambda, \eta), n = 1, 2, \dots.$$

And also, we have

$$\mathfrak{D}(F(u_n, v_n, \lambda, \eta), F(u_0, v_0, \lambda, \eta)) \leq \theta\|(u_n, v_n) - (u_0, v_0)\|_1.$$

It follows that

$$\begin{aligned} d((u_0, v_0), F(u_0, v_0, \lambda, \eta)) &\leq \|(u_0, v_0) - (u_n, v_n)\|_1 \\ &\quad + d((u_n, v_n), F(u_n, v_n, \lambda, \eta)) \\ &\quad + \mathfrak{D}(F(u_n, v_n, \lambda, \eta), F(u_0, v_0, \lambda, \eta)) \\ &\leq (1 + \theta)\|(u_n, v_n) - (u_0, v_0)\|_1 \\ &\rightarrow 0, \text{ as } n \rightarrow \infty. \end{aligned}$$

Hence, we have $(u_0, v_0) \in F(u_0, v_0, \lambda, \eta)$. From Lemma 2.6, we have $(u_0, v_0) \in S(\lambda, \eta)$. Therefore $S(\lambda, \eta)$ is a nonempty closed subset of $\mathcal{X} \times \mathcal{X}$. This completes the proof. \blacksquare

Theorem 2.8. The hypotheses of Theorem 2.7 are hold and assume that for any $u, v \in \mathcal{X}$, the mappings $\lambda \rightarrow U(u, v, \lambda)$, $\eta \rightarrow V(u, v, \eta)$, $\lambda \rightarrow h(u, \lambda)$, $\eta \rightarrow p(v, \eta)$ are locally Lipschitz continuous with constants $\ell_U, \ell_V, \ell_p, \ell_h$, respectively. Let $\eta \rightarrow T(u, \eta)$ be a locally $\ell_T - \mathfrak{D}$ -Lipschitz continuous mapping and $\lambda \rightarrow G(v, \lambda)$ be a locally $\ell_G - \mathfrak{D}$ -Lipschitz continuous mapping for $u, v \in \mathcal{X}$. Let $P_{\mathcal{K}_r}$ be a Lipschitz continuous operator with constant $\delta = \frac{r}{r - r'}$. Then the solution $S(\lambda, \eta)$ for a system of parametric general regularized nonconvex variational inequalities is locally Lipschitz continuous from $\Omega \times \Lambda$ to $\mathcal{X} \times \mathcal{X}$.

Proof. By Theorem 2.7, for any $(t, \lambda, \bar{\lambda}) \in \mathcal{X} \times \Omega \times \Omega$ and $(z, \eta, \bar{\eta}) \in \mathcal{X} \times \Lambda \times \Lambda$, $S(\lambda, \eta)$ and $S(\bar{\lambda}, \bar{\eta})$ are nonempty closed subsets. Also, for each $(\lambda, \eta), (\bar{\lambda}, \bar{\eta}) \in \Omega \times \Lambda$, $F(u, v, \lambda, \eta)$ and $F(u, v, \bar{\lambda}, \bar{\eta})$ are contractive mappings with some constant $\theta \in (0, 1)$ and have fixed points $(u(\lambda, \eta), v(\lambda, \eta))$ and $(u(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}))$, respectively. Hence, by Lemma 2.4, for any fixed $(\lambda, \eta), (\bar{\lambda}, \bar{\eta}) \in \Omega \times \Lambda$, we have

$$\begin{aligned} & \mathfrak{D}(S(\lambda, \eta), S(\bar{\lambda}, \bar{\eta})) \\ & \leq \frac{1}{1 - \theta} \sup_{(u, v) \in \mathcal{X} \times \mathcal{X}} \mathfrak{D}(F(u(\lambda, \eta), v(\lambda, \eta), \lambda, \eta), F(u(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \bar{\lambda}, \bar{\eta})). \end{aligned} \quad (19)$$

For any $(a_1, a_2) \in F(u(\lambda, \eta), v(\lambda, \eta), \lambda, \eta)$, there exists $x(\lambda, \eta) \in T(u(\lambda, \eta), \eta)$, $y(\lambda, \eta) \in G(v(\lambda, \eta), \lambda)$ such that

$$\begin{aligned} a_1 &= u(\lambda, \eta) - h(u(\lambda, \eta), \lambda) + P_{\mathcal{K}_r}(u(\lambda, \eta) - \rho U(u(\lambda, \eta), y(\lambda, \eta), \lambda)) \\ a_2 &= v(\lambda, \eta) - p(v(\lambda, \eta), \eta) + P_{\mathcal{K}_r}(v(\lambda, \eta) - \mu V(x(\lambda, \eta), v(\lambda, \eta), \eta)). \end{aligned} \quad (20)$$

From the Nadler Theorem [21], there exists $x(\bar{\lambda}, \bar{\eta}) \in T(u(\bar{\lambda}, \bar{\eta}), \bar{\eta})$, $y(\bar{\lambda}, \bar{\eta}) \in G(v(\bar{\lambda}, \bar{\eta}), \bar{\lambda})$ such that

$$\begin{aligned} \|x(\lambda, \eta) - x(\bar{\lambda}, \bar{\eta})\| &\leq \mathfrak{D}(T(u(\lambda, \eta), \eta), T(u(\bar{\lambda}, \bar{\eta}), \bar{\eta})), \\ \|y(\lambda, \eta) - y(\bar{\lambda}, \bar{\eta})\| &\leq \mathfrak{D}(G(v(\lambda, \eta), \lambda), G(v(\bar{\lambda}, \bar{\eta}), \bar{\lambda})). \end{aligned} \quad (21)$$

Let

$$\begin{aligned} b_1 &= u(\bar{\lambda}, \bar{\eta}) - h(u(\bar{\lambda}, \bar{\eta}), \bar{\lambda}) + P_{\mathcal{K}_r}(u(\bar{\lambda}, \bar{\eta}) - \rho U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \bar{\lambda})), \\ b_2 &= v(\bar{\lambda}, \bar{\eta}) - p(v(\bar{\lambda}, \bar{\eta}), \bar{\eta}) + P_{\mathcal{K}_r}(v(\bar{\lambda}, \bar{\eta}) - \mu V(x(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \bar{\eta})). \end{aligned} \quad (22)$$

Then, we have

$$(b_1, b_2) \in F(u(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \bar{\lambda}, \bar{\eta}).$$

From (20), (22) and Proposition 1.7, we have

$$\begin{aligned}
& \|a_1 - b_1\| \\
& \leq \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - (h(u(\lambda, \eta), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \lambda))\| \\
& \quad + \|h(u(\bar{\lambda}, \bar{\eta}), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \bar{\lambda})\| \\
& \quad + \|P_{\mathcal{K}_r}(u(\lambda, \eta) - \rho U(u(\lambda, \eta), y(\lambda, \eta), \lambda)) \\
& \quad - P_{\mathcal{K}_r}(u(\bar{\lambda}, \bar{\eta}) - \rho U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \bar{\lambda}))\| \\
& \leq \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - (h(u(\lambda, \eta), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \lambda))\| \\
& \quad + \|h(u(\bar{\lambda}, \bar{\eta}), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \bar{\lambda})\| \\
& \quad + \|P_{\mathcal{K}_r}(u(\lambda, \eta) - \rho U(u(\lambda, \eta), y(\lambda, \eta), \lambda)) \\
& \quad - P_{\mathcal{K}_r}(u(\bar{\lambda}, \bar{\eta}) - \rho U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \bar{\lambda}))\| \\
& \quad + \|P_{\mathcal{K}_r}(u(\bar{\lambda}, \bar{\eta}) - \rho U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \lambda)) \\
& \quad - P_{\mathcal{K}_r}(u(\bar{\lambda}, \bar{\eta}) - \rho U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \bar{\lambda}))\| \\
& \leq \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - (h(u(\lambda, \eta), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \lambda))\| \\
& \quad + \|h(u(\bar{\lambda}, \bar{\eta}), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \bar{\lambda})\| \\
& \quad + \delta \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - \rho(U(u(\lambda, \eta), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \lambda))\| \\
& \quad + \delta \|u(\bar{\lambda}, \bar{\eta}) - u(\bar{\lambda}, \bar{\eta}) - \rho(U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \bar{\lambda}))\| \\
& \leq \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - (h(u(\lambda, \eta), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \lambda))\| \\
& \quad + \|h(u(\bar{\lambda}, \bar{\eta}), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \bar{\lambda})\| \\
& \quad + \delta \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - \rho(U(u(\lambda, \eta), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda))\| \\
& \quad + \delta \rho \|U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \lambda)\| \\
& \quad + \delta \rho \|U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \bar{\lambda})\| \\
& \leq \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - (h(u(\lambda, \eta), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \lambda))\| + \ell_h \|\lambda - \bar{\lambda}\| \\
& \quad + \delta \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - \rho(U(u(\lambda, \eta), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda))\| \\
& \quad + \delta \rho \|U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \lambda)\| \\
& \quad + \delta \rho \ell_U \|\bar{\lambda} - \bar{\lambda}\| \\
& \leq \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - (h(u(\lambda, \eta), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \lambda))\| + \ell_h \|\lambda - \bar{\lambda}\| \\
& \quad + \delta \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - \rho(U(u(\lambda, \eta), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda))\| \\
& \quad + \delta \rho \|U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \lambda)\| \\
& \quad + \delta \rho \ell_U \|\bar{\lambda} - \bar{\lambda}\|
\end{aligned} \tag{23}$$

and

$$\begin{aligned}
& \|a_2 - b_2\| \\
& \leq \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta}) - (p(v(\lambda, \eta), \eta) - p(v(\bar{\lambda}, \bar{\eta}), \eta))\| \\
& \quad + \|p(v(\bar{\lambda}, \bar{\eta}), \eta) - p(v(\bar{\lambda}, \bar{\eta}), \bar{\eta})\| \\
& \quad - \|P_{\mathcal{K}_r}(v(\lambda, \eta) - \mu V(x(\lambda, \eta), v(\lambda, \eta), \eta)) \\
& \quad - P_{\mathcal{K}_r}(v(\bar{\lambda}, \bar{\eta}) - \mu V(x(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \bar{\eta}))\| \\
& \leq \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta}) - (p(v(\lambda, \eta), \eta) - p(v(\bar{\lambda}, \bar{\eta}), \eta))\| \\
& \quad + \|p(v(\bar{\lambda}, \bar{\eta}), \eta) - p(v(\bar{\lambda}, \bar{\eta}), \bar{\eta})\| \\
& \quad + \|P_{\mathcal{K}_r}(v(\lambda, \eta) - \mu V(x(\lambda, \eta), v(\lambda, \eta), \eta)) \\
& \quad - P_{\mathcal{K}_r}(v(\bar{\lambda}, \bar{\eta}) - \mu V(x(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \eta))\| \\
& \quad + \|P_{\mathcal{K}_r}(v(\bar{\lambda}, \bar{\eta}) - \mu V(x(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \eta)) \\
& \quad - P_{\mathcal{K}_r}(v(\bar{\lambda}, \bar{\eta}) - \mu V(x(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \bar{\lambda}))\| \\
& \leq \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta}) - (p(v(\lambda, \eta), \eta) - p(v(\bar{\lambda}, \bar{\eta}), \eta))\| \\
& \quad + \|p(v(\bar{\lambda}, \bar{\eta}), \eta) - p(v(\bar{\lambda}, \bar{\eta}), \bar{\eta})\| \\
& \quad + \delta \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta}) - \mu(V(x(\lambda, \eta), v(\lambda, \eta), \eta) - V(x(\lambda, \eta), v(\bar{\lambda}, \bar{\eta}), \eta))\| \\
& \quad + \delta \|v(\bar{\lambda}, \bar{\eta}) - v(\bar{\lambda}, \bar{\eta}) - \mu(V(x(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \eta) - V(x(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \bar{\eta}))\| \\
& \leq \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta}) - (p(v(\lambda, \eta), \eta) - p(v(\bar{\lambda}, \bar{\eta}), \eta))\| + \ell_p \|\eta - \bar{\eta}\| \\
& \quad + \delta \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta}) - \mu(V(x(\lambda, \eta), v(\lambda, \eta), \eta) - V(x(\lambda, \eta), v(\bar{\lambda}, \bar{\eta}), \eta))\| \\
& \quad + \delta \mu \|V(x(\lambda, \eta), v(\bar{\lambda}, \bar{\eta}), \eta) - V(x(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \eta)\| + \delta \mu \ell_V \|\eta - \bar{\eta}\|. \quad (24)
\end{aligned}$$

Now, we know that

$$\begin{aligned}
& \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - (h(u(\lambda, \eta), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \lambda))\|^q \\
& \leq \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\|^q - q \langle h(u(\lambda, \eta), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \lambda), j_q(u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})) \rangle \\
& \quad + c_q \|h(u(\lambda, \eta), \lambda) - h(u(\bar{\lambda}, \bar{\eta}), \lambda)\|^q \\
& \leq (1 - q\alpha_h + c_q \beta_h^q) \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\|^q, \quad (25)
\end{aligned}$$

$$\begin{aligned}
& \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta}) - \rho(U(u(\lambda, \eta), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda))\|^q \\
& \leq \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\|^q \\
& \quad - q\rho \langle U(u(\lambda, \eta), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda), j_q(u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})) \rangle \\
& \quad + c_q \rho^q \|U(u(\lambda, \eta), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda)\|^q \\
& \leq \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\|^q \\
& \quad - q\rho(-\varphi_U \|U(u(\lambda, \eta), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda)\|^q \\
& \quad - \psi_U \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\|^q) + c_q \rho^q \zeta_U^q \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\|^q \\
& \leq (1 - q\rho(\psi_U - \varphi_U \zeta_U^q) + c_q \rho^q \zeta_U^q) \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\|^q \quad (26)
\end{aligned}$$

and

$$\begin{aligned}
& \|U(u(\bar{\lambda}, \bar{\eta}), y(\lambda, \eta), \lambda) - U(u(\bar{\lambda}, \bar{\eta}), y(\bar{\lambda}, \bar{\eta}), \lambda)\| \\
& \leq \kappa_U \|y(\lambda, \eta) - y(\bar{\lambda}, \bar{\eta})\| \\
& \leq \kappa_U \mathfrak{D}(G(v(\lambda, \eta), \lambda) - G(v(\bar{\lambda}, \bar{\eta}), \bar{\lambda})) \\
& \leq \kappa_U [\mathfrak{D}(G(v(\lambda, \eta), \lambda) - G(v(\bar{\lambda}, \bar{\eta}), \lambda)) + \mathfrak{D}(G(v(\bar{\lambda}, \bar{\eta}), \lambda) - G(v(\bar{\lambda}, \bar{\eta}), \bar{\lambda}))] \\
& \leq \kappa_U [\vartheta_G \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\| + \ell_G \|\lambda - \bar{\lambda}\|].
\end{aligned} \tag{27}$$

And also, we know that

$$\begin{aligned}
& \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta}) - (p(v(\lambda, \eta), \eta) - p(v(\bar{\lambda}, \bar{\eta}), \eta))\|^q \\
& \leq \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q - q \langle p(v(\lambda, \eta), \eta) - p(v(\bar{\lambda}, \bar{\eta}), \eta), j_q(v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})) \rangle \\
& \quad + c_q \|p(v(\lambda, \eta), \eta) - p(v(\lambda, \eta), \eta)\|^q \\
& \leq \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q + q\alpha_p \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q + c_q \beta_p^q \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q \\
& \leq (1 + q\alpha_p + c_q \beta_p^q) \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q,
\end{aligned} \tag{28}$$

$$\begin{aligned}
& \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta}) - \mu(V(x(\lambda, \eta), v(\lambda, \eta), \eta) - V(x(\lambda, \eta), v(\bar{\lambda}, \bar{\eta}), \eta))\|^q \\
& \leq \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q \\
& \quad - q\mu \langle V(x(\lambda, \eta), v(\lambda, \eta), \eta) - V(x(\lambda, \eta), v(\bar{\lambda}, \bar{\eta}), \eta), j_q(v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})) \rangle \\
& \quad + c_q \mu^q \|V(x(\lambda, \eta), v(\lambda, \eta), \eta) - V(x(\lambda, \eta), v(\bar{\lambda}, \bar{\eta}), \eta)\|^q \\
& \leq \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q \\
& \quad - q\mu(-\varphi_V \|V(x(\lambda, \eta), v(\lambda, \eta), \eta) - V(x(\lambda, \eta), v(\bar{\lambda}, \bar{\eta}), \eta)\|^q \\
& \quad + \psi_V \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q) + c_q \mu^q \kappa_V^q \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q \\
& \leq \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q - q\mu(-\varphi_V \kappa_V^q \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q \\
& \quad + \psi_V \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q) + c_q \mu^q \kappa_V^q \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q \\
& \leq (1 - q\mu(\psi_V - \varphi_V \kappa_V^q) + c_q \mu^q \kappa_V^q) \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|^q
\end{aligned} \tag{29}$$

and

$$\begin{aligned}
& \|V(x(\lambda, \eta), v(\bar{\lambda}, \bar{\eta}), \eta) - V(x(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \eta)\| \\
& \leq \zeta_V \|x(\lambda, \eta) - x(\bar{\lambda}, \bar{\eta})\| \\
& \leq \zeta_V \mathfrak{D}(T(u(\lambda, \eta), \eta), T(u(\bar{\lambda}, \bar{\eta}), \bar{\eta})) \\
& \leq \zeta_V [\mathfrak{D}(T(u(\lambda, \eta), \eta), T(u(\bar{\lambda}, \bar{\eta}), \eta)) + \mathfrak{D}(T(u(\bar{\lambda}, \bar{\eta}), \eta), T(u(\bar{\lambda}, \bar{\eta}), \bar{\eta}))] \\
& \leq \zeta_V [\vartheta_T \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\| + \ell_T \|\eta - \bar{\eta}\|].
\end{aligned} \tag{30}$$

Therefore, from (23)–(30), we have

$$\begin{aligned}
& \|a_1 - b_1\| + \|a_2 - b_2\| \\
& \leq \left[\sqrt[q]{1 - q\alpha_h + c_q\beta_h^q} + \delta \sqrt[q]{1 - q\rho(\psi_U - \varphi_U\zeta_U^q) + c_q\rho^q\zeta_U^q} + \delta\mu\zeta_V\vartheta_T \right] \\
& \quad \times \|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\| \\
& \quad + \left[\sqrt[q]{1 + q\alpha_p + c_q\beta_p^q} + \delta \sqrt[q]{1 - q\mu(\psi_V - \varphi_V\kappa_V^q) + c_q\mu^q\kappa_V^q} + \delta\rho\kappa_U\vartheta_G \right] \\
& \quad \times \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\| \\
& \quad + [\ell_h + \delta\rho\ell_U + \mu\delta\kappa_U\ell_G]\|\lambda - \bar{\lambda}\| + [\ell_p + \delta\mu\ell_V + \rho\delta\zeta_V\ell_T]\|\eta - \bar{\eta}\| \\
& = \theta_1\|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\| + \theta_2\|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\| + J_1\|\lambda - \bar{\lambda}\| + J_2\|\eta - \bar{\eta}\| \\
& \leq \theta[\|u(\lambda, \eta) - u(\bar{\lambda}, \bar{\eta})\| + \|v(\lambda, \eta) - v(\bar{\lambda}, \bar{\eta})\|] + J_1\|\lambda - \bar{\lambda}\| + J_2\|\eta - \bar{\eta}\| \\
& \leq \theta[\|a_1 - b_1\| + \|a_2 - b_2\|] + J_1\|\lambda - \bar{\lambda}\| + J_2\|\eta - \bar{\eta}\|, \tag{31}
\end{aligned}$$

where

$$\begin{aligned}
\theta_1 &= \sqrt[q]{1 - q\alpha_h + c_q\beta_h^q} + \delta \sqrt[q]{1 - q\rho(\psi_U - \varphi_U\zeta_U^q) + c_q\rho^q\zeta_U^q} + \delta\mu\zeta_V\vartheta_T, \\
\theta_2 &= \sqrt[q]{1 + q\alpha_p + c_q\beta_p^q} + \delta \sqrt[q]{1 - q\mu(\psi_V - \varphi_V\kappa_V^q) + c_q\mu^q\kappa_V^q} + \delta\rho\kappa_U\vartheta_G, \\
J_1 &= \ell_h + \delta\rho\ell_U + \mu\delta\kappa_U\ell_G, \\
J_2 &= \ell_p + \delta\mu\ell_V + \rho\delta\zeta_V\ell_T, \\
\theta &= \max\{\theta_1, \theta_2\}.
\end{aligned}$$

It follows from (4) and (31) that

$$\begin{aligned}
\|a_1 - b_1\| + \|a_2 - b_2\| &\leq \frac{1}{1 - \theta} \left[J_1\|\lambda - \bar{\lambda}\| + J_2\|\eta - \bar{\eta}\| \right] \\
&\leq \frac{1}{1 - \theta} \max\{J_1, J_2\} \left(\|\lambda - \bar{\lambda}\| + \|\eta - \bar{\eta}\| \right) \\
&\leq \wp (\|\lambda - \bar{\lambda}\| + \|\eta - \bar{\eta}\|),
\end{aligned}$$

where $\wp = \frac{1}{1 - \theta} \max\{J_1, J_2\}$. Hence, we have

$$\begin{aligned}
& d((a_1, a_2), F(u(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \bar{\lambda}, \bar{\eta})) \\
& = \inf_{(b_1, b_2) \in F(u(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \bar{\lambda}, \bar{\eta})} \left(\|a_1 - b_1\| + \|a_2 - b_2\| \right) \\
& \leq \wp (\|\lambda - \bar{\lambda}\| + \|\eta - \bar{\eta}\|) \\
& = \wp \|(\lambda, \eta) - (\bar{\lambda}, \bar{\eta})\|_1. \tag{32}
\end{aligned}$$

Similarly, we have

$$d((b_1, b_2), F(u(\lambda, \eta), v(\lambda, \eta), \lambda, \eta)) \leq \wp \|(\lambda, \eta) - (\bar{\lambda}, \bar{\eta})\|_1. \quad (33)$$

Hence from (19), (32) and (33), we have

$$\begin{aligned} & \mathcal{D}(S(\lambda, \eta), S(\bar{\lambda}, \bar{\eta})) \\ & \leq \frac{1}{1-\theta} \sup_{(u,v) \in H \times H} \mathcal{D}(F(u(\lambda, \eta), v(\lambda, \eta), \lambda, \eta), F(u(\bar{\lambda}, \bar{\eta}), v(\bar{\lambda}, \bar{\eta}), \bar{\lambda}, \bar{\eta})) \\ & \leq \frac{\wp}{1-\theta} \|(\lambda, \eta) - (\bar{\lambda}, \bar{\eta})\|. \end{aligned}$$

This means that $S(\lambda, \eta)$ is Lipschitz continuous with respect to $(\lambda, \eta) \in \Omega \times \Lambda$. ■

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