

Weak Solutions for Impulsive Implicit Hadamard Fractional Differential Equations

Saïd Abbas

Tahar Moulay University of Saïda
Laboratory of Mathematics
Geometry, Analysis, Control and Applications
P.O. Box 138, EN-Nasr, 20000 Saïda, Algeria

Mouffak Benchohra, Farida Berhoun

Djillali Liabes University of Sidi Bel-Abbès
Laboratory of Mathematics
P.O. Box 89, Sidi Bel-Abbès 22000, Algeria

Juan J. Nieto

Departamento de Análisis Matemático,
Instituto de Matemáticas
Universidad de Santiago de Compostela,
Santiago de Compostela, Spain

Abstract

In this article, we present some results concerning the existence of weak solutions for a class of functional impulsive implicit differential equations involving the Hadamard fractional order derivative in Banach spaces. The main results are proved by applying fixed point theory combined with the technique of measure of weak noncompactness.

AMS Subject Classifications: 26A33, 34A37.

Keywords: Fractional differential equation, left-sided mixed Pettis Hadamard integral of fractional order, Pettis Hadamard fractional derivative, implicit, impulse, measure of weak noncompactness, weak solution, fixed point.

1 Introduction

Fractional differential and integral equations have recently been applied in various areas of engineering, mathematics, physics and bio-engineering and other applied sciences [28,37]. For some fundamental results in the theory of fractional calculus and fractional differential equations we refer the reader to the monographs of Abbas et al. [5,6], Kilbas et al. [30] and Zhou [40].

The measure of weak noncompactness is introduced by De Blasi [24]. The strong measure of noncompactness was developed first by Banaś and Goebel [14] and subsequently developed and used in many papers; see for example, Akhmerov et al. [10], Alvàrez [12], Benchohra et al. [21], Guo et al. [26], and the references therein. In [21,34] the authors considered some existence results by applying the techniques of the measure of noncompactness. Recently, several researchers obtained other results by application of the technique of measure of weak noncompactness; see [6, 18, 19], and the references therein.

Impulsive differential equations have become more important in recent years in some mathematical models of real phenomena, especially in biological or medical domains, in control theory, see for example the monographs of Abbas et al. [5], Benchohra et al. [20], Bainov and Simeonov [13], Graef et al. [25], Perestyuk et al. [35], and several papers have been published, see the papers of Abbas et al. [2–4], Agarwal et al. [8], Benchohra and Berhoun [16], and the references therein.

Implicit functional differential equations have been considered by many authors [7, 15, 32, 39]. Recently, considerable attention has been given to the existence of solutions of fractional differential equations with Hadamard fractional derivative; see [1, 9, 11, 17, 22, 38].

In this paper, our intention is to extend the results to implicit impulsive differential equations of Hadamard fractional derivative. We discuss the existence of weak solutions for the implicit impulsive Hadamard fractional differential equation of the form

$$\begin{cases} ({}^H D_{t_k}^r u)(t) = f(t, u(t), ({}^H D_{t_k}^r u)(t)); & t \in J_k, \quad k = 0, \dots, m, \\ \frac{(\ln t)^{r-1}}{\Gamma(r)} ({}^H I_{t_k}^{1-r} u)(t_k^+) = u(t_k^-) + L_k(u(t_k^-)); & k = 1, \dots, m, \\ ({}^H I_1^{1-r} u)(t)|_{t=1} = \phi, \end{cases} \quad (1.1)$$

where $T > 1$, $\phi \in E$, $J_0 = [1, t_1]$, $J_k := (t_k, t_{k+1}]$; $k = 1, \dots, m$, $1 = t_0 < t_1 < \dots < t_m < t_{m+1} = T$, $f : J_k \times E \times E \rightarrow E$; $k = 1, \dots, m$, $L_k : E \rightarrow E$; $k = 1, \dots, m$ are given continuous functions, E is a real (or complex) Banach space with norm $\|\cdot\|_E$ and dual E^* , such that E is the dual of a weakly compactly generated Banach space X , $\ln = \log_e$, ${}^H I_{t_k}^r$ is the left-sided mixed Hadamard integral of order $r \in (0, 1]$, and ${}^H D_{t_k}^r$ is the Hadamard fractional derivative of order r .

Our goal in this paper is to give existence results for implicit impulsive Hadamard fractional differential equations.

2 Preliminaries

Let \mathcal{C} be the Banach space of all continuous functions v from $J := [1, T]$ into E with the supremum (uniform) norm

$$\|v\|_\infty := \sup_{t \in J} \|v(t)\|_E.$$

As usual, $AC(J)$ denotes the space of absolutely continuous functions from J into E . By $C_{r,\ln}(J)$, we denote the weighted space of continuous functions defined by

$$C_{r,\ln}(J) = \{w(t) : (\ln t)^r w(t) \in \mathcal{C}, \|w\|_{C_{r,\ln}} := \sup_{t \in J} \|(\ln t)^r w(t)\|_E\}.$$

Let $(E, w) = (E, \sigma(E, E^*))$ be the Banach space E with its weak topology. Consider the Banach space

$$PC = \{u : J \rightarrow E : u \in C(J_k); k = 0, \dots, m, \text{ and there exist } u(t_k^-) \text{ and } ({}^H I_{t_k}^{1-r} u)(t_k^+); k = 1, \dots, m, \text{ with } u(t_k^-) = u(t_k)\},$$

with the norm

$$\|u\|_C = \sup_{t \in J} \|u(t)\|_E.$$

Also, we can define the weighted space of PC by

$$PC_{r,\ln}(I) = \{w(t) : (\ln t)^r w(t) \in PC, \|w\|_{PC_{r,\ln}} := \sup_{t \in J} \|(\ln t)^r w(t)\|_E\}.$$

In the following we denote $\|w\|_{PC_{r,\ln}}$ by $\|w\|_{PC}$.

Definition 2.1. A Banach space X is called weakly compactly generated (WCG, in short) if it contains a weakly compact set whose linear span is dense in X .

Definition 2.2. A function $h : E \rightarrow E$ is said to be weakly sequentially continuous if h takes each weakly convergent sequence in E to a weakly convergent sequence in E (i.e., for any (u_n) in E with $u_n \rightarrow u$ in (E, w) then $h(u_n) \rightarrow h(u)$ in (E, w)).

Definition 2.3 (See [36]). The function $u : I \rightarrow E$ is said to be Pettis integrable on J if and only if there is an element $u_j \in E$ corresponding to each $j \subset J$ such that $\phi(u_j) = \int_j \phi(u(s))ds$ for all $\phi \in E^*$, where the integral on the right hand side is assumed to exist in the sense of Lebesgue, (by definition, $u_j = \int_j u(s)ds$).

Let $P(J, E)$ be the space of all E -valued Pettis integrable functions on J , and $L^1(J, E)$, be the Banach space of measurable functions $u : J \rightarrow E$ which are Bochner integrable. Define the class $P_1(J, E)$ by

$$P_1(J, E) = \{u \in P(J, E) : \varphi(u) \in L^1(J, \mathbb{R}); \text{ for every } \varphi \in E^*\}.$$

The space $P_1(J, E)$ is normed by

$$\|u\|_{P_1} = \sup_{\varphi \in E^*, \|\varphi\| \leq 1} \int_1^T |\varphi(u(x))| d\lambda x,$$

where λ stands for a Lebesgue measure on J .

The following result is due to Pettis (see [36, Theorem 3.4 and Corollary 3.41]).

Proposition 2.4 (See [36]). *If $u \in P_1(J, E)$ and h is a measurable and essentially bounded E -valued function, then $uh \in P_1(J, E)$.*

For all what follows, the sign " \int " denotes the Pettis integral. Let us recall some definitions and properties of Hadamard fractional integration and differentiation. We refer to [27, 30] for a more detailed analysis.

Definition 2.5 (See [27, 30]). The Hadamard fractional integral of order $q > 0$ for a function $g \in L^1(J, E)$, is defined as

$$({}^H I_1^q g)(x) = \frac{1}{\Gamma(q)} \int_1^x \left(\ln \frac{x}{s}\right)^{q-1} \frac{g(s)}{s} ds,$$

where $\Gamma(\cdot)$ is the (Euler's) Gamma function defined by

$$\Gamma(\xi) = \int_0^\infty t^{\xi-1} e^{-t} dt; \quad \xi > 0.$$

Provided the integral exists.

Example 2.6. Let $q > 0$. Then

$${}^H I_1^q \ln t = \frac{1}{\Gamma(2+q)} (\ln t)^{1+q}; \text{ for a.e. } t \in [0, e].$$

Definition 2.7 (See [27, 30]). Let $1 \leq a < T$, $q > 0$, and $g \in L^1(J, E)$. Then

$$({}^H I_{a^+}^q g)(x) = \frac{1}{\Gamma(q)} \int_{a^+}^x \left(\ln \frac{x}{s}\right)^{q-1} \frac{g(s)}{s} ds,$$

Remark 2.8. Let $g \in P_1(J, E)$. For every $\varphi \in E^*$, we have

$$\varphi({}^H I_1^q g)(x) = ({}^H I_1^q \varphi g)(x); \text{ for a.e. } x \in J.$$

Analogously to the Riemann–Liouville fractional calculus, the Hadamard fractional derivative is defined in terms of the Hadamard fractional integral in the following way. Set

$$\delta = x \frac{d}{dx}, \quad n = [q] + 1,$$

where $[q]$ is the integer part of $q > 0$, and

$$AC_\delta^n := \{u : J \rightarrow E : \delta^{n-1}[u(x)] \in AC(J)\}.$$

Definition 2.9 (See [27, 30]). The Hadamard fractional derivative of order q applied to the function $w \in AC_\delta^n$ is defined as

$$({}^H D_1^q w)(x) = \delta^n ({}^H I_1^{n-q} w)(x).$$

Example 2.10. Let $0 < q < 1$. Then

$${}^H D_1^q \ln t = \frac{1}{\Gamma(2-q)} (\ln t)^{1-q}; \text{ for a.e. } t \in [0, e].$$

Definition 2.11 (See [27, 30]). Let $1 \leq a < T$ and $g \in L^1(J, E)$. Then

$$({}^H D_{a+}^q w)(x) = \delta^n ({}^H I_{a+}^{n-q} w)(x).$$

It has been proved (see e.g., Kilbas [29, Theorem 4.8]) that in the space $L^1(J, E)$, the Hadamard fractional derivative is the left-inverse operator to the Hadamard fractional integral, i.e.,

$$({}^H D_1^q)({}^H I_1^q w)(x) = w(x).$$

From [30, Theorem 2.3], we have

$$({}^H I_1^q)({}^H D_1^q w)(x) = w(x) - \frac{({}^H I_1^{1-q} w)(1)}{\Gamma(q)} (\ln x)^{q-1}.$$

Corollary 2.12. Let $h : J_0 \rightarrow E$ be a continuous function. A function $u \in L^1(J_0, E)$ is a solution of the equation

$$({}^H D_1^q u)(t) = h(t),$$

if and only if, u satisfies the Hadamard integral equation

$$u(t) = \frac{({}^H I_1^{1-q} u)(1)}{\Gamma(q)} (\ln t)^{q-1} + ({}^H I_1^q h)(t).$$

Lemma 2.13. *Let $h : J \rightarrow E$ be a continuous function. A function $u \in L^1(J, E)$ is solution of the fractional integral equation*

$$\left\{ \begin{array}{l} u(t) = \frac{\phi}{\Gamma(r)}(\ln t)^{r-1} + ({}^H I_1^r h)(t); \text{ if } t \in J_0, \\ u(t) = \frac{\phi}{\Gamma(r)}(\ln t)^{r-1} + \sum_{i=1}^k L_i(u(t_i^-)) \\ + \sum_{i=1}^k \int_{t_{i-1}}^{t_i} \left(\ln \frac{t_i}{s} \right)^{r-1} \frac{h(s)}{s\Gamma(r)} ds \\ + \int_{t_k}^t \left(\ln \frac{t}{s} \right)^{r-1} \frac{h(s)}{s\Gamma(r)} ds; \text{ if } t \in J_k, \ k = 1, \dots, m, \end{array} \right. \quad (2.1)$$

if and only if u is a solution of the problem

$$\left\{ \begin{array}{l} ({}^H D_{t_k}^r u)(t) = h(t); \ t \in J_k, \ k = 0, \dots, m, \\ \frac{(\ln t)^{r-1}}{\Gamma(r)} ({}^H I_{t_k}^{1-r} u)(t_k^+) = u(t_k^-) + L_k(u(t_k^-)); \ k = 1, \dots, m, \\ ({}^H I_1^{1-r} u)(t)|_{t=1} = \phi. \end{array} \right. \quad (2.2)$$

Proof. Assume u satisfies (2.2). If $t \in J_0$, then

$$({}^H D_1^r u)(t) = h(t).$$

Corollary 2.12 implies

$$u(t) = \frac{\phi}{\Gamma(r)}(\ln t)^{r-1} + ({}^H I_1^r h)(t).$$

If $t \in J_1$, then

$$({}^H D_{t_1}^r u)(t) = h(t).$$

Corollary 2.12 implies

$$\begin{aligned} u(t) &= \frac{({}^H I_{t_1}^{1-r} u)(t_1^+)}{\Gamma(r)}(\ln t)^{r-1} + ({}^H I_{t_1}^r h)(t) \\ &= L_1(u(t_1^-)) + u(t_1^-) + ({}^H I_{t_1}^r h)(t) \\ &= L_1(u(t_1^-)) + \frac{\phi}{\Gamma(r)}(\ln t)^{r-1} + ({}^H I_1^r h)(t_1) + ({}^H I_{t_1}^r h)(t). \end{aligned}$$

If $t \in J_2$, then

$$({}^H D_2^r u)(t) = h(t).$$

Corollary 2.12 implies

$$\begin{aligned} u(t) &= \frac{({}^H I_{t_2}^{1-r} u)(t_2^+)}{\Gamma(r)} (\ln t)^{r-1} + ({}^H I_{t_2}^r h)(t) \\ &= L_2(u(t_2^-)) + u(t_2^-) + ({}^H I_{t_2}^r h)(t) \\ &= L_2(u(t_2^-)) + L_1(u(t_1^-)) + \frac{\phi}{\Gamma(r)} (\ln t)^{r-1} \\ &\quad + ({}^H I_1^r h)(t_1) + ({}^H I_{t_1}^r h)(t_2) + ({}^H I_{t_2}^r h)(t). \end{aligned}$$

If $t \in J_k$, then again from Corollary 2.12 we get (2.1). Conversely, assume that u satisfies the impulsive fractional integral equations (2.1). If $t \in J_0$, then $u(t) = \frac{\phi}{\Gamma(r)} (\ln t)^{r-1} + ({}^H I_1^r h)(t)$. Thus, $({}^H I_1^{1-r} u)(t)|_{t=1} = \phi$ and using the fact that ${}^H D_1^r$ is the left inverse of ${}^H I_1^r$ we get $({}^H D_1^r u)(t) = h(t)$.

Now, if $t \in J_k$; $k = 1, \dots, m$, we get $({}^H D_{t_k}^r u)(t) = h(t)$. Also, we can easily show that

$$\frac{(\ln t)^{r-1}}{\Gamma(r)} ({}^H I_{t_k}^{1-r} u)(t_k^+) = u(t_k^-) + L_k(u(t_k^-)).$$

Hence, if u satisfies the impulsive fractional integral equations (2.1) then we get (2.2). \square

As a consequence; we have the following lemma.

Lemma 2.14. *Let $f(t, u, z) : J_k \times E \times E \rightarrow E$; $k = 0, \dots, m$, be a continuous function. Then problem (1.1) is equivalent to the problem of the solution of the equation*

$$g(t) = f \left(t, \frac{\phi}{\Gamma(r)} (\ln t)^{r-1} + ({}^H I_{t_k}^r g)(t), g(t) \right),$$

and if $g(t) \in C(J_k)$; $k = 0, \dots, m$, is the solution of the above equation, then

$$\left\{ \begin{aligned} &u(t) = \frac{\phi}{\Gamma(r)} (\ln t)^{r-1} + ({}^H I_1^r g)(t); \text{ if } t \in J_0, \\ &u(t) = \frac{\phi}{\Gamma(r)} (\ln t)^{r-1} + \sum_{i=1}^k (L_i(({}^H I_{t_i}^{1-r} u)(t_i^-)) \\ &\quad + \sum_{i=1}^k \int_{t_{i-1}}^{t_i} \left(\ln \frac{t_i}{s} \right)^{r-1} \frac{g(s)}{s \Gamma(r)} ds \\ &\quad + \int_{t_k}^t \left(\ln \frac{t}{s} \right)^{r-1} \frac{g(s)}{s \Gamma(r)} ds; \text{ if } t \in J_k, k = 1, \dots, m. \end{aligned} \right.$$

Definition 2.15 (See [24]). Let E be a Banach space, Ω_E the bounded subsets of E and B_1 the unit ball of E . The De Blasi measure of weak noncompactness is the map $\beta : \Omega_E \rightarrow [0, \infty)$ defined by

$$\beta(X) = \inf \{ \epsilon > 0 : \text{there exists a weakly compact subset } \Omega \text{ of } E : X \subset \epsilon B_1 + \Omega \}.$$

The De Blasi measure of weak noncompactness satisfies the following properties:

- (a) $A \subset B \Rightarrow \beta(A) \leq \beta(B)$,
- (b) $\beta(A) = 0 \Leftrightarrow A$ is weakly relatively compact,
- (c) $\beta(A \cup B) = \max\{\beta(A), \beta(B)\}$,
- (d) $\beta(\overline{A}^\omega) = \beta(A)$, (\overline{A}^ω denotes the weak closure of A),
- (e) $\beta(A + B) \leq \beta(A) + \beta(B)$,
- (f) $\beta(\lambda A) = |\lambda|\beta(A)$,
- (g) $\beta(\text{conv}(A)) = \beta(A)$,
- (h) $\beta(\cup_{|\lambda| \leq h} \lambda A) = h\beta(A)$.

The next result follows directly from the Hahn–Banach theorem.

Proposition 2.16. *Let E be a normed space, and $x_0 \in E$ with $x_0 \neq 0$. Then, there exists $\varphi \in E^*$ with $\|\varphi\| = 1$ and $\varphi(x_0) = \|x_0\|$.*

For a given set V of functions $v : J \rightarrow E$ let us denote by

$$V(t) = \{v(t) : v \in V\}; \quad t \in J,$$

and

$$V(I) = \{v(t) : v \in V, t \in J\}.$$

Lemma 2.17 (See [26]). *Let $H \subset C$ be a bounded and equicontinuous. Then the function $t \rightarrow \beta(H(t))$ is continuous on J , and*

$$\beta_C(H) = \max_{t \in J} \beta(H(t)),$$

and

$$\beta \left(\int_J u(s) ds \right) \leq \int_J \beta(H(s)) ds,$$

where $H(s) = \{u(s) : u \in H, s \in J\}$, and β_C is the De Blasi measure of weak noncompactness defined on the bounded sets of C .

For our purpose we will need the following fixed point theorem.

Theorem 2.18 (See [33]). *Let Q be a nonempty, closed, convex and equicontinuous subset of a metrizable locally convex vector space $C(J, E)$ such that $0 \in Q$. Suppose $T : Q \rightarrow Q$ is weakly-sequentially continuous. If the implication*

$$\overline{V} = \overline{\text{conv}}(\{0\} \cup T(V)) \Rightarrow V \text{ is relatively weakly compact}, \quad (2.3)$$

holds for every subset $V \subset Q$, then the operator T has a fixed point.

3 Existence Results

Let us start by defining what we mean by a weak solution of the problem (1.1).

Definition 3.1. By a weak solution of the problem (1.1) we mean a measurable function $u \in PC(J)$ that satisfies the condition $(^H I_1^{1-r} u)(t)|_{t=1} = \phi$, and the equation $(^H D_{t_k}^r u)(t) = f(t, u(t), (^H D_{t_k}^r u)(t))$ on J_k ; $k = 0, \dots, m$.

The following hypotheses will be used in the sequel.

(H₁) For a.e. $t \in J_k$; $k = 0, \dots, m$, the functions $v \rightarrow f(t, v, \cdot)$ and $w \rightarrow f(t, \cdot, w)$ are weakly sequentially continuous.

(H₂) For a.e. $v, w \in E$, the function $t \rightarrow f(t, v, w)$ is Pettis integrable a.e. on J_k ; $k = 0, \dots, m$.

(H₃) There exists $p \in C(J_k, [0, \infty))$; $k = 0, \dots, m$ such that for all $\varphi \in E^*$, we have

$$|\varphi(f(t, u, v))| \leq \frac{p(t)\|\varphi\|}{1 + \|\varphi\| + \|u\|_E + \|v\|_E}; \text{ for a.e. } t \in J_k, \text{ and each } u, v \in E.$$

(H₄) For each bounded and measurable set $B \subset E$ and for each $t \in J_k$; $k = 0, \dots, m$, we have

$$\beta(f(t, B, ^H D_1^r B)) \leq (\ln t)^{1-r} p(t) \beta(B),$$

where $^H D_1^r B = \{^H D_1^r w : w \in B\}$.

(H₅) There exists a constant $l^* > 0$ such that for all $\varphi \in E^*$, we have

$$|\varphi(L_k(u))| \leq \frac{l^*\|\varphi\|}{1 + \|\varphi\| + \|u\|_E}; \text{ for a.e. } t \in J_k; k = 1, \dots, m, \text{ and each } u \in E.$$

Set

$$p^* = \sup_{t \in J} p(t),$$

Theorem 3.2. Assume that the hypotheses (H₁) – (H₄) hold. If

$$L := ml^*(\ln T)^{1-r} + \frac{2p^* \ln T}{\Gamma(1+r)} < 1, \quad (3.1)$$

then the problem (1.1) has at least one solution defined on I .

Proof. Transform the problem (1.1) into a fixed point equation. Consider the operator $N : \mathcal{PC} \rightarrow \mathcal{PC}$ defined by

$$\left\{ \begin{array}{l} (Nu)(t) = \frac{\phi}{\Gamma(r)}(\ln t)^{r-1} + ({}^H I_1^r g)(t); \text{ if } t \in J_0, \\ (Nu)(t) = \frac{\phi}{\Gamma(r)}(\ln t)^{r-1} + \sum_{i=1}^k L_i(u(t_i^-)) \\ + \sum_{i=1}^k \int_{t_{i-1}}^{t_i} \left(\ln \frac{t_i}{s} \right)^{r-1} \frac{g(s)}{s\Gamma(r)} ds \\ + \int_{t_k}^t \left(\ln \frac{t}{s} \right)^{r-1} \frac{g(s)}{s\Gamma(r)} ds; \text{ if } t \in J_k, \ k = 1, \dots, m, \end{array} \right. \quad (3.2)$$

where $g \in C(J_k)$; $k = 0, \dots, m$, with

$$g(t) = f \left(t, \frac{\phi}{\Gamma(r)}(\ln t)^{r-1} + ({}^H I_{t_k}^r g)(t), g(t) \right).$$

First notice that, the hypotheses imply that $\left(\ln \frac{t_k}{s} \right)^{r-1} \frac{g(s)}{s}$; for all $t \in J_k$, $k = 0, \dots, m$, is Pettis integrable, and for each $u \in C$, the function

$$t \mapsto f \left(t, \frac{\phi}{\Gamma(r)}(\ln t)^{r-1} + ({}^H I_{t_k}^r g)(t), g(t) \right) : k = 0, \dots, m,$$

is Pettis integrable over J_k ; $k = 0, \dots, m$. Thus, the operator N is well defined. Let $R > 0$ be such that

$$R > ml^*(\ln T)^{1-r} + \frac{2p^* \ln T}{\Gamma(1+r)},$$

and consider the set

$$\begin{aligned} Q = \left\{ u \in \mathcal{PC} : \|u\|_{\mathcal{PC}} \leq R \text{ and } \|(\ln x_2)^{1-r} u(x_2) - (\ln x_1)^{1-r} u(x_1)\|_E \right. \\ \leq ml^* |(\ln x_2)^{1-r} - (\ln x_1)^{1-r}| + \frac{2p^*}{\Gamma(1+r)} (\ln T)^{1-r} \left| \ln \frac{x_2}{x_1} \right|^r \\ \left. + \frac{2p^*}{\Gamma(r)} \int_1^{x_1} \left| (\ln x_2)^{1-r} \left(\ln \frac{x_2}{s} \right)^{r-1} - (\ln x_1)^{1-r} \left(\ln \frac{x_1}{s} \right)^{r-1} \right| ds \right\}. \end{aligned}$$

Clearly, the subset Q is closed, convex and equicontinuous. We shall show that the operator N satisfies all the assumptions of Theorem 2.18. The proof will be given in several steps.

Step 1. N maps Q into itself.

Let $u \in Q$, $t \in J_0$ and assume that $(Nu)(t) \neq 0$. Then there exists $\varphi \in E^*$ such that

$$\|(\ln t)^{1-r} (Nu)(t)\|_E = \varphi((\ln t)^{1-r} (Nu)(t)).$$

Thus

$$\|(\ln t)^{1-r}(Nu)(t)\|_E = \varphi \left(\frac{\phi}{\Gamma(r)} + \frac{(\ln t)^{1-r}}{\Gamma(r)} \int_1^t \left(\ln \frac{t}{s} \right)^{r-1} \frac{g(s)}{s} ds \right),$$

where $g \in C$ with

$$g(t) = f \left(t, \frac{\phi}{\Gamma(r)} (\ln t)^{r-1} + ({}^H I_1^r g)(t), g(t) \right).$$

Then

$$\begin{aligned} \|(\ln t)^{1-r}(Nu)(t)\|_E &\leq \frac{(\ln t)^{1-r}}{\Gamma(r)} \int_1^t \left(\ln \frac{t}{s} \right)^{r-1} \frac{|\varphi(g(s))|}{s} ds \\ &\leq \frac{p^*(\ln T)^{1-r}}{\Gamma(r)} \int_1^t \left(\ln \frac{t}{s} \right)^{r-1} \frac{ds}{s} \\ &\leq \frac{p^* \ln T}{\Gamma(1+r)} \\ &\leq R. \end{aligned}$$

Also, if $u \in Q$, $t \in J_k$: $k = 1, \dots, m$, we get

$$\begin{aligned} \|(\ln t)^{1-r}(Nu)(t)\|_E &\leq \sum_{i=1}^k \varphi((\ln t)^{1-r} L_i(u(t_i^-))) \\ &\quad + (\ln T)^{1-r} \sum_{i=1}^k \int_{t_{i-1}}^{t_i} \left(\ln \frac{t_i}{s} \right)^{r-1} \frac{\varphi(g(s))}{s\Gamma(r)} ds \\ &\quad + (\ln T)^{1-r} \int_{t_k}^t \left(\ln \frac{t}{s} \right)^{r-1} \frac{\varphi(g(s))}{s\Gamma(r)} ds \\ &\leq ml^*(\ln T)^{1-r} + \frac{2p^* \ln T}{\Gamma(1+r)} \\ &\leq R. \end{aligned}$$

Next, let $x_1, x_2 \in J_0$ such that $1 \leq x_1 < x_2 \leq t_1$ and let $u \in Q$, with

$$(\ln x_2)^{1-r}(Nu)(x_2) - (\ln x_1)^{1-r}(Nu)(x_1) \neq 0.$$

Then there exists $\varphi \in E^*$ such that

$$\begin{aligned} \|(\ln x_2)^{1-r}(Nu)(x_2) - (\ln x_1)^{1-r}(Nu)(x_1)\|_E \\ = \varphi((\ln x_2)^{1-r}(Nu)(x_2) - (\ln x_1)^{1-r}(Nu)(x_1)) \end{aligned}$$

and $\|\varphi\| = 1$. Then

$$\begin{aligned} & \|(\ln x_2)^{1-r}(Nu)(x_2) - (\ln x_1)^{1-r}(Nu)(x_1)\|_E \\ &= \varphi((\ln x_2)^{1-r}(Nu)(x_2) - (\ln x_1)^{1-r}(Nu)(x_1)) \\ &\leq ml^* |(\ln x_2)^{1-r} - (\ln x_1)^{1-r}| \\ &+ \varphi \left((\ln x_2)^{1-r} \int_1^{x_2} \left(\ln \frac{x_2}{s} \right)^{r-1} \frac{g(s)}{s\Gamma(r)} ds - (\ln x_1)^{1-r} \int_1^{x_1} \left(\ln \frac{x_1}{s} \right)^{r-1} \frac{g(s)}{s\Gamma(r)} ds \right), \end{aligned}$$

where $g \in C$ with

$$g(t) = f \left(t, \frac{\phi}{\Gamma(r)} (\ln t)^{r-1} + ({}^H I_1^r g)(t), g(t) \right).$$

Then

$$\begin{aligned} & \|(\ln x_2)^{1-r}(Nu)(x_2) - (\ln x_1)^{1-r}(Nu)(x_1)\|_E \\ &\leq ml^* |(\ln x_2)^{1-r} - (\ln x_1)^{1-r}| \\ &+ (\ln x_2)^{1-r} \int_{x_1}^{x_2} \left| \ln \frac{x_2}{s} \right|^{r-1} \frac{|\varphi(g(s))|}{s\Gamma(r)} ds \\ &+ \int_1^{x_1} \left| (\ln x_2)^{1-r} \left(\ln \frac{x_2}{s} \right)^{r-1} - (\ln x_1)^{1-r} \left(\ln \frac{x_1}{s} \right)^{r-1} \right| \frac{|\varphi(g(s))|}{s\Gamma(r)} ds \\ &\leq ml^* |(\ln x_2)^{1-r} - (\ln x_1)^{1-r}| \\ &+ (\ln x_2)^{1-r} \int_{x_1}^{x_2} \left| \ln \frac{x_2}{s} \right|^{r-1} \frac{p(s)}{\Gamma(r)} ds \\ &+ \int_1^{x_1} \left| (\ln x_2)^{1-r} \left(\ln \frac{x_2}{s} \right)^{r-1} - (\ln x_1)^{1-r} \left(\ln \frac{x_1}{s} \right)^{r-1} \right| \frac{p(s)}{\Gamma(r)} ds. \end{aligned}$$

Thus, we get

$$\begin{aligned} & \|(\ln x_2)^{1-r}(Nu)(x_2) - (\ln x_1)^{1-r}(Nu)(x_1)\|_E \\ &\leq ml^* |(\ln x_2)^{1-r} - (\ln x_1)^{1-r}| \\ &+ \frac{p^*}{\Gamma(1+r)} (\ln T)^{1-r} \left| \ln \frac{x_2}{x_1} \right|^r \\ &+ \frac{p^*}{\Gamma(r)} \int_1^{x_1} \left| (\ln x_2)^{1-r} \left(\ln \frac{x_2}{s} \right)^{r-1} - (\ln x_1)^{1-r} \left(\ln \frac{x_1}{s} \right)^{r-1} \right| ds. \end{aligned}$$

Also, if we let $x_1, x_2 \in J_k$; $k = 1, \dots, m$ such that $t_k \leq x_1 < x_2 \leq t_{k+1}$ and let $u \in Q$, we obtain

$$\begin{aligned} & \|(\ln x_2)^{1-r}(Nu)(x_2) - (\ln x_1)^{1-r}(Nu)(x_1)\|_E \\ &\leq ml^* |(\ln x_2)^{1-r} - (\ln x_1)^{1-r}| + \frac{2p^*}{\Gamma(1+r)} (\ln T)^{1-r} \left| \ln \frac{x_2}{x_1} \right|^r \\ &+ \frac{2p^*}{\Gamma(r)} \int_1^{x_1} \left| (\ln x_2)^{1-r} \left(\ln \frac{x_2}{s} \right)^{r-1} - (\ln x_1)^{1-r} \left(\ln \frac{x_1}{s} \right)^{r-1} \right| ds. \end{aligned}$$

Hence $N(Q) \subset Q$.

Step 2. N is weakly-sequentially continuous.

Let (u_n) be a sequence in Q and let $(u_n(t)) \rightarrow u(t)$ in (E, ω) for each $t \in J_k$; $k = 0, \dots, m$. Fix $t \in J_k$; $k = 0, \dots, m$, since f satisfies the assumption (H_1) , we have $f(t, u_n(t), {}^H D_{t_k} u_n(t))$ converges weakly uniformly to $f(t, u(t), {}^H D_{t_k} u(t))$. Hence the Lebesgue dominated convergence theorem for Pettis integral implies $(Nu_n)(t)$ converges weakly uniformly to $(Nu)(t)$ in (E, ω) , for each $t \in J_k$; $k = 0, \dots, m$. Thus, $N(u_n) \rightarrow N(u)$. Hence, $N : Q \rightarrow Q$ is weakly-sequentially continuous.

Step 3. The implication (2.3) holds.

Let V be a subset of Q such that $\bar{V} = \overline{\text{conv}}(N(V) \cup \{0\})$. Obviously

$$V(t) \subset \overline{\text{conv}}(NV)(t) \cup \{0\}, \quad t \in J_k; \quad k = 0, \dots, m.$$

Further, as V is bounded and equicontinuous, by [23, Lemma 3] the function $t \rightarrow v(t) = \beta(V(t))$ is continuous on J_k ; $k = 0, \dots, m$. From $(H_3) - (H_5)$, Lemma 2.17 and the properties of the measure β , for any $t \in J_0$, we have

$$\begin{aligned} (\ln t)^{1-r} v(t) &\leq \beta((\ln t)^{1-r}(NV)(t) \cup \{0\}) \\ &\leq \beta((\ln t)^{1-r}(NV)(t)) \\ &\leq \frac{(\ln T)^{1-r}}{\Gamma(r)} \int_1^t \left| \ln \frac{t}{s} \right|^{r-1} \frac{p(s)\beta(V(s))}{s} ds \\ &\leq \frac{(\ln T)^{1-r}}{\Gamma(r)} \int_1^t \left| \ln \frac{t}{s} \right|^{r-1} \frac{(\ln s)^{1-r} p(s)v(s)}{s} ds \\ &\leq \frac{p^* \ln T}{\Gamma(1+r)} \|v\|_C. \end{aligned}$$

Thus

$$\|v\|_C \leq L \|v\|_C.$$

Also, for any $t \in J_k$; $k = 1, \dots, m$, we get

$$\begin{aligned} (\ln t)^{1-r} v(t) &\leq \beta((\ln t)^{1-r}(NV)(t) \cup \{0\}) \\ &\leq \beta((\ln t)^{1-r}(NV)(t)) \\ &\leq (\ln T)^{1-r} \sum_{i=1}^k l^* \beta(V(s)) \\ &\quad + (\ln T)^{1-r} \sum_{i=1}^k \int_{t_{i-1}}^{t_i} \left(\ln \frac{t_i}{s} \right)^{r-1} \frac{p(s)\beta(V(s))}{s\Gamma(r)} ds \\ &\quad + (\ln T)^{1-r} \int_{t_k}^t \left(\ln \frac{t}{s} \right)^{r-1} \frac{p(s)\beta(V(s))}{s\Gamma(r)} ds \\ &\leq l^* (\ln T)^{1-r} \sum_{i=1}^k (\ln t)^{1-r} v(t) \end{aligned}$$

$$\begin{aligned}
& + (\ln T)^{1-r} \sum_{i=1}^k \int_{t_{i-1}}^{t_i} \left(\ln \frac{t_i}{s} \right)^{r-1} \frac{(\ln s)^{1-r} p(s) v(s)}{s \Gamma(r)} ds \\
& + (\ln T)^{1-r} \int_{t_k}^t \left(\ln \frac{t}{s} \right)^{r-1} \frac{(\ln s)^{1-r} p(s) v(s)}{s \Gamma(r)} ds \\
& \leq \left(ml^* (\ln T)^{1-r} + \frac{2p^* \ln T}{\Gamma(1+r)} \right) \|v\|_C.
\end{aligned}$$

Hence

$$\|v\|_C \leq L \|v\|_C.$$

From (3.1), we get $\|v\|_C = 0$, that is $v(t) = \beta(V(t)) = 0$, for each $t \in I$ and then by [31, Theorem 2], V is weakly relatively compact in \mathcal{C} . Applying now Theorem 2.18, we conclude that N has a fixed point which is a solution of the problem (1.1). \square

4 An Example

Let

$$E = l^1 = \left\{ u = (u_1, u_2, \dots, u_n, \dots), \sum_{n=1}^{\infty} |u_n| < \infty \right\}$$

be the Banach space with the norm

$$\|u\|_E = \sum_{n=1}^{\infty} |u_n|.$$

Consider the problem of implicit impulsive Hadamard fractional differential equations of the form

$$\begin{cases}
({}^H D_{t_k}^r u)(t) = f(t, u(t), ({}^H D_{t_k}^r u)(t)); & t \in J_k, \quad k = 0, \dots, m, \\
\frac{(\ln t)^{r-1}}{\Gamma(r)} ({}^H I_{t_k}^{1-r} u)(t_k^+) = u(t_k^-) + L_k(u(t_k^-)); & k = 1, \dots, m, \\
({}^H I_1^{1-r} u)(t)|_{t=1} = 0,
\end{cases} \quad (4.1)$$

where $J = [1, e]$, $r \in (0, 1]$, $u = (u_1, u_2, \dots, u_n, \dots)$,

$f = (f_1, f_2, \dots, f_n, \dots)$, ${}^H D_{t_k}^r u = ({}^H D_{t_k}^r u_1, {}^H D_{t_k}^r u_2, \dots, {}^H D_{t_k}^r u_n, \dots)$; $k = 0, \dots, m$,

$f_n(t, u(t), ({}^H D_{t_k}^r u)(t)) = \frac{ct^2}{1 + \|u(t)\|_E + \|{}^H D_{t_k}^r u(t)\|_E} \left(e^{-7} + \frac{1}{e^{t+5}} \right) u_n(t)$; $t \in [1, e]$,

$L_k(u(t_k^-)) = \frac{1}{3e^4(1 + \|u(t_k^-)\|_E)}$; $k = 1, \dots, m$.

Clearly, the function f is continuous.

For each $u \in E$ and $t \in [1, e]$, we have

$$\|f(t, u(t), ({}^H D_{t_k}^r)(t))\|_E \leq \frac{ct^2}{1 + \|u(t)\|_E + \|{}^H D_{t_k}^r u(t)\|_E} \left(e^{-7} + \frac{1}{e^{t+5}} \right),$$

and

$$\|L_k(u(t_k^-))\|_E \leq \frac{1}{3e^4(1 + \|u(t_k^-)\|_E)}.$$

Hence, the hypothesis (H_3) is satisfied with $p^* = ce^{-4}$, and (H_5) is satisfied with $l^* = \frac{1}{3e^4}$.

We shall show that condition (3.1) holds with $T = e$. Indeed, if we assume, for instance, that the number of impulses $m = 3$, and $r = \frac{1}{2}$, then we have

$$ml^*(\ln T)^{1-r} + \frac{2p^* \ln T}{\Gamma(1+r)} = \frac{1}{e^4} + \frac{2c}{e^4 \Gamma(\frac{3}{2})} = \frac{9}{16} < 1.$$

A simple computations show that all conditions of Theorem 3.2 are satisfied. It follows that the problem (4.1) has at least one solution on $[1, e]$.

References

- [1] Saïd Abbas, Wafaa Albarakati, Mouffak Benchohra and Gaston Mandata N'Guérékata, Existence and Ulam stabilities for Hadamard fractional integral equations in Fréchet spaces, *J. Frac. Calc. Appl.* **7** (2) (2016), 1–12.
- [2] Saïd Abbas and Mouffak Benchohra, Existence and Ulam stability for impulsive discontinuous fractional differential inclusions in Banach Algebras, *Mediterr. J. Math.* **12** (4), (2015), 1245–1264.
- [3] Saïd Abbas and Mouffak Benchohra, Existence of solutions to fractional-order impulsive hyperbolic partial differential inclusions, *Electron. J. Differential Equations* **2014** (2014), No. 196, pp 1–13.
- [4] Saïd Abbas and Mouffak Benchohra, Upper and lower solutions method for Darboux problem for fractional order implicit impulsive partial hyperbolic differential equations, *Acta Univ. Palacki. Olomuc.*, **51** (2) (2012), 5–18.
- [5] Saïd Abbas, Mouffak Benchohra and Gaston Mandata N'Guérékata, *Topics in Fractional Differential Equations*, Springer, New York, 2012.
- [6] Saïd Abbas, Mouffak Benchohra and Gaston Mandata N'Guérékata, *Advanced Fractional Differential and Integral Equations*, Nova Science Publishers, New York, 2015.

- [7] Saïd Abbas, Mouffak Benchohra and Aleksandr N. Vityuk, On fractional order derivatives and Darboux problem for implicit differential equations, *Frac. Calc. Appl. Anal.* **15** (2) (2012), 168–182.
- [8] Ravi P. Agarwal, Mouffak Benchohra and Boualam A. Slimani, Existence results for differential equations with fractional order impulses, *Mem. Differential Equations Math. Phys.* **44** (1) (2008), 1–21.
- [9] Bashir Ahmad, Sotiris K. Ntouyas, Initial value problem of fractional order Hadamard-type functional differential equations, *Electron. J. Differential Equations* **2015** (2015), No. 77, pp 1–9.
- [10] R. R. Akhmerov, M. I. Kamenskii, A. S. Patapov, A. E. Rodkina and B. N. Sadovskii, *Measures of Noncompactness and Condensing Operators*. Birkhauser Verlag, Basel, 1992.
- [11] S. Aljoudi, Bashir Ahmad, Juan J. Nieto, and Ahmed Alsaedi, A coupled system of Hadamard type sequential fractional differential equations with coupled strip conditions, *Chaos, Solitons Fractals* **91** (2016), 39–46.
- [12] J. C. Alvàrez, Measure of noncompactness and fixed points of nonexpansive condensing mappings in locally convex spaces, *Rev. Real. Acad. Cienc. Exact. Fis. Natur. Madrid* **79** (1985), 53–66.
- [13] D. D. Bainov and P. S. Simeonov, *Systems with Impulsive effect*, Horwood, Chichester, 1989.
- [14] Jòzef Banaś and Kai Goebel, *Measures of Noncompactness in Banach Spaces*, Marcel Dekker, New York, 1980.
- [15] Tomas D. Benavides, An existence theorem for implicit differential equations in a Banach space, *Ann. Mat. Pura Appl.* **4** (1978), 119–130.
- [16] Mouffak Benchohra and Farida Berhoun, Impulsive fractional differential equations with state dependent delay, *Commun. Appl. Anal.* **14** (2) (2010), 213–224.
- [17] Mouffak Benchohra, Soufiane Bouriah, Jamal Eddine Lazreg and Juan J. Nieto, Nonlinear implicit Hadamard's fractional differential equations with delay in Banach spaces, *Acta Univ. Palack. Olomuc. Fac. Rerum Natur. Math.* **55** (1) (2016), 15–26.
- [18] Mouffak Benchohra, John Graef and Fatima-Zohra Mostefai, Weak solutions for boundary-value problems with nonlinear fractional differential inclusions, *Nonlinear Dyn. Syst. Theory* **11** (3) (2011), 227–237.

- [19] Mouffak Benchohra, Johnny Henderson and Fatima-Zohra Mostefai, Weak solutions for hyperbolic partial fractional differential inclusions in Banach spaces, *Comput. Math. Appl.* **64** (2012), 3101–3107.
- [20] Mouffak Benchohra, Johnny Henderson and Sotiris K. Ntouyas, *Impulsive Differential Equations and Inclusions*, Hindawi Publishing Corporation, Vol. 2, New York, 2006.
- [21] Mouffak Benchohra, Johnny Henderson and Djamila Seba, Measure of noncompactness and fractional differential equations in Banach spaces, *Commun. Appl. Anal.* **12** (4) (2008), 419–428.
- [22] Mouffak Benchohra, and Jamal Eddine Lazreg, Existence and Ulam stability for nonlinear implicit fractional differential equations with Hadamard derivative, *Stud. Univ. Babes-Bolyai Math.* **62** (1) (2017), 27–38.
- [23] D. Bugajewski and S. Szufła, Kneser’s theorem for weak solutions of the Darboux problem in a Banach space, *Nonlinear Anal.* **20** (2) (1993), 169–173.
- [24] Francesco S. De Blasi, On the property of the unit sphere in a Banach space, *Bull. Math. Soc. Sci. Math. R.S. Roumanie* **21** (1977), 259–262.
- [25] John R. Graef, Johnny Henderson and Abdelghani Ouahab, *Impulsive Differential Inclusions. A Fixed Point Approach*, De Gruyter, Berlin/Boston, 2013.
- [26] Dongning Guo, Vangipuram Lakshmikantham and X. Liu, *Nonlinear Integral Equations in Abstract Spaces*, Kluwer Academic Publishers, Dordrecht, 1996.
- [27] Jacques Hadamard, Essai sur l’étude des fonctions données par leur développement de Taylor, *J. Pure Appl. Math.* **4** (8) (1892), 101–186.
- [28] Rudolf Hilfer, *Applications of Fractional Calculus in Physics*, World Scientific, Singapore, 2000.
- [29] Anatoly A. Kilbas, Hadamard-type fractional calculus. *J. Korean Math. Soc.* **38** (6) (2001) 1191–1204.
- [30] Anatoly A. Kilbas, Hari M. Srivastava and Juan J. Trujillo, *Theory and Applications of Fractional Differential Equations*. Elsevier Science B.V., Amsterdam, 2006.
- [31] Arthur R. Mitchell and Ch. Smith. Nonlinear Equations in Abstract Spaces. In: Lakshmikantham, V. (ed.) An existence theorem for weak solutions of differential equations in Banach spaces, pp. 387–403. Academic Press, New York (1978).
- [32] Juan J. Nieto, Abdelghani Ouahab and V. Venktesh, Implicit fractional differential equations via the Liouville-Caputo derivative. *Mathematics* **3** (2015), 398–411.

- [33] Donal O'Regan, Fixed point theory for weakly sequentially continuous mapping, *Math. Comput. Model.* **27** (5) (1998), 1–14.
- [34] Donal O'Regan, Weak solutions of ordinary differential equations in Banach spaces, *Appl. Math. Lett.* **12** (1999), 101–105.
- [35] N. A. Perestyuk, V. A. Plotnikov, A. M. Samoilenko and N. V. Skripnik, *Differential Equation with Impulse Effects, Multivalued Right-hand Sides with Discontinuities* Walter de Gruyter, Berlin/Boston, 2011.
- [36] Billy J. Pettis, On integration in vector spaces, *Trans. Amer. Math. Soc.* **44** (1938), 277–304.
- [37] Vasily E. Tarasov, *Fractional dynamics: Application of Fractional Calculus to Dynamics of Particles, Fields and Media*, Springer, Heidelberg; Higher Education Press, Beijing, 2010.
- [38] P. Thiramanus, Sotiris K. Ntouyas and J. Tariboon, Existence and uniqueness results for Hadamard-type fractional differential equations with nonlocal fractional integral boundary conditions, *Abst. Appl. Anal.* (2014), 9 p.
- [39] Aleksandr N. Vityuk and A. V. Mykhailenko, The Darboux problem for an implicit fractional-order differential equation, *J. Math. Sci.* **175** (4) (2011), 391–401.
- [40] Yong Zhou, *Basic Theory of Fractional Differential Equations*, World Scientific, Singapore, 2014.